

CS375 / Psych 249: Large-Scale Neural Network Models for Neuroscience

Lecture 2: The biological inspiration of CNNs

2025.01.07

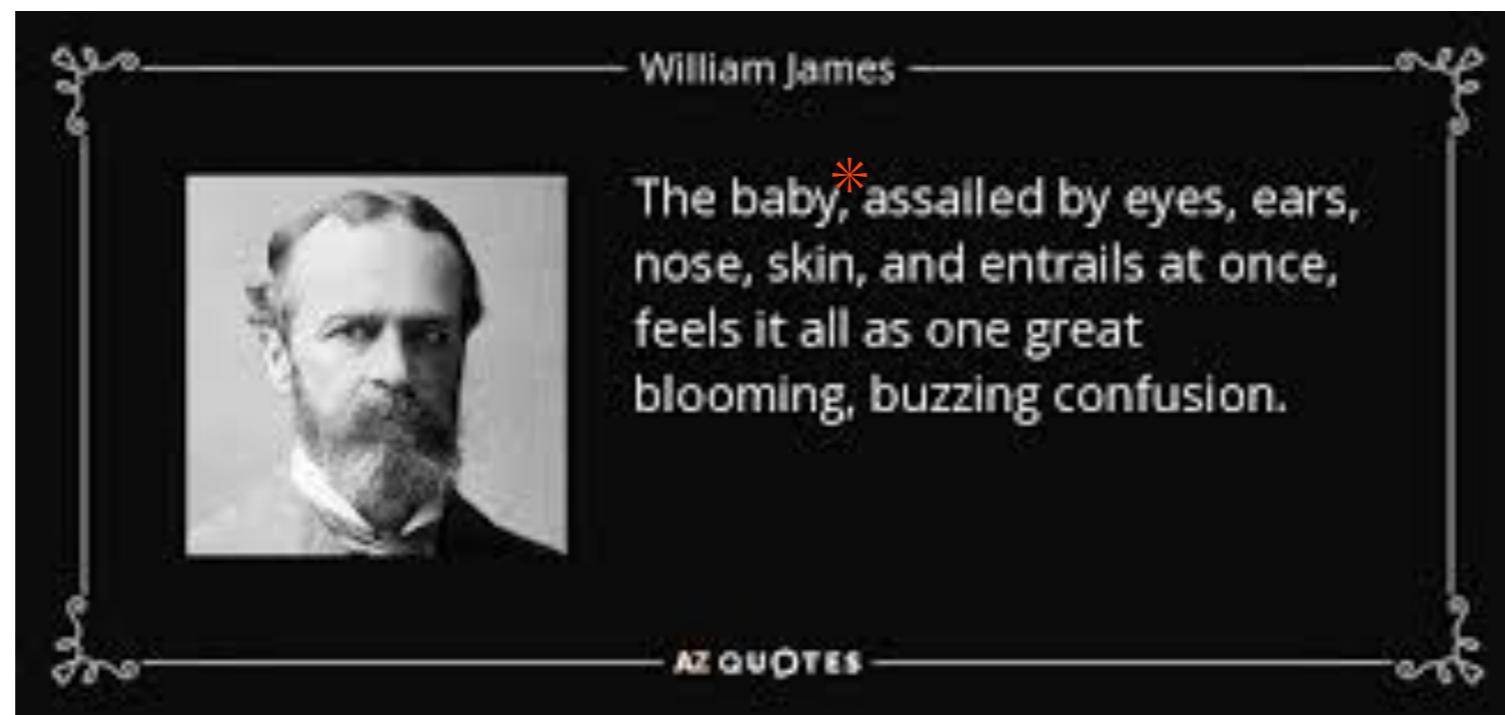
Daniel Yamins

Departments of Computer Science and of Psychology
Stanford Neuroscience and Artificial Intelligence Laboratory
Wu Tsai Neurosciences Institute
Stanford University



Problem: Entity Extraction

Understanding complex, noisy data streams is a critical part of cognition.



Without sophisticated parsing and entity extraction, the world would be “as one great blooming, buzzing confusion” (for babies or otherwise).

* actually not clearly true for babies ...

Problem: Entity Extraction

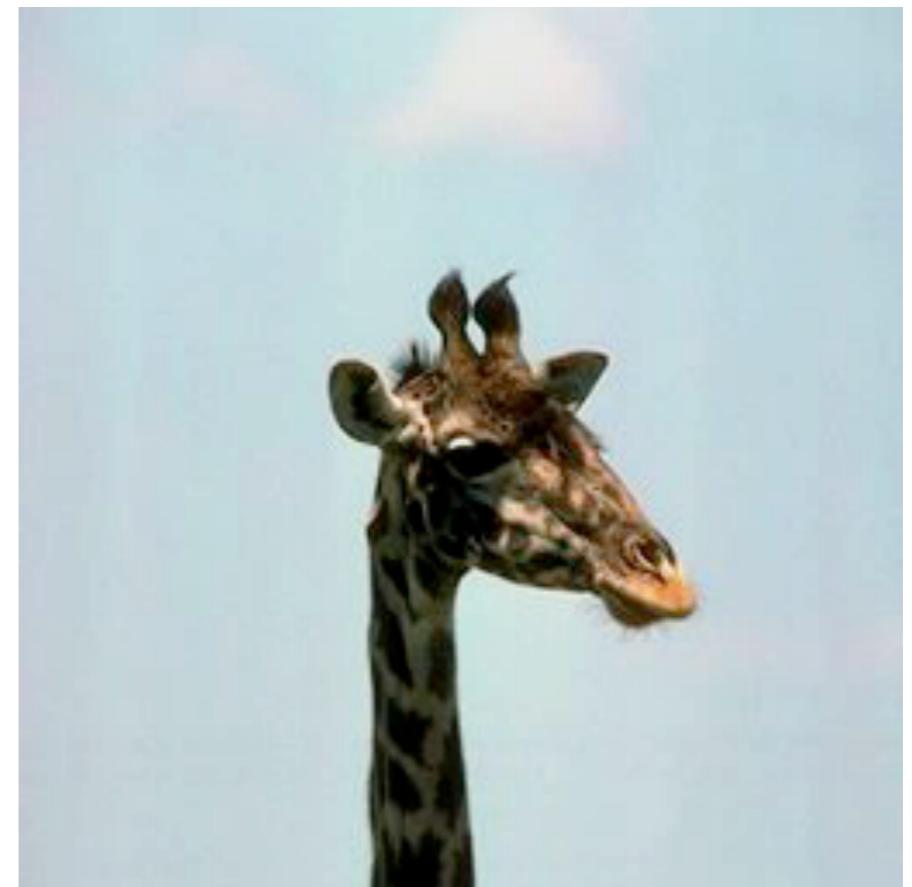
Why is the problem hard computationally?

- I. Nonlinear misalignment between physical and behavioral dimensions

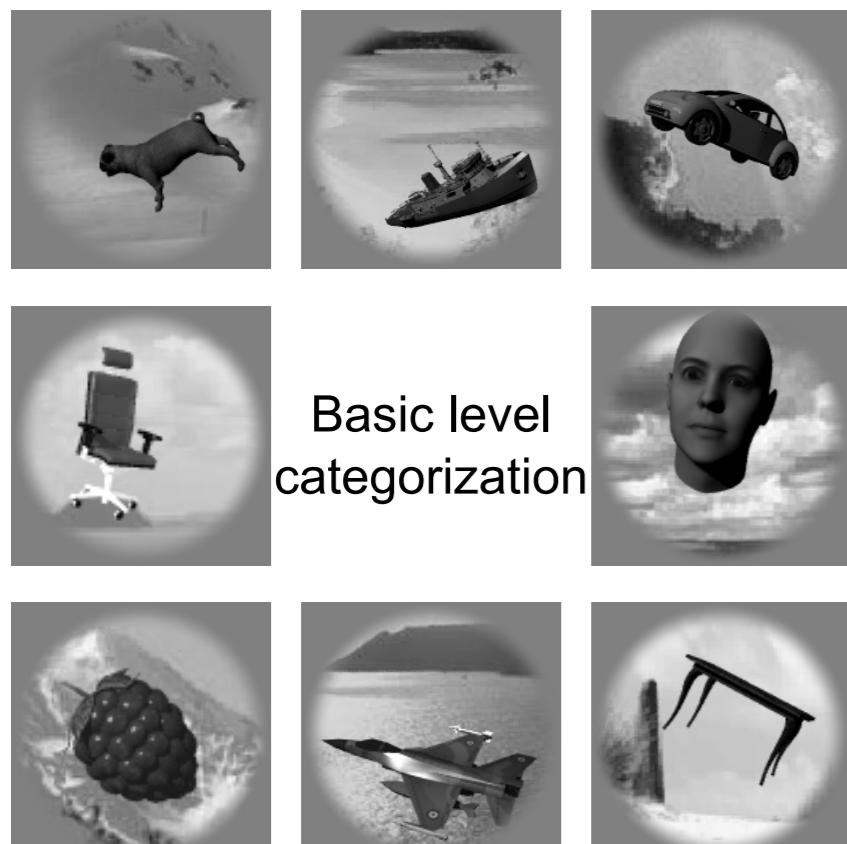
Problem: Entity Extraction

Why is the problem hard computationally?

1. Nonlinear misalignment between physical and behavioral dimensions
2. Needs to be done ***fast***, and thus, presumably, massively in parallel

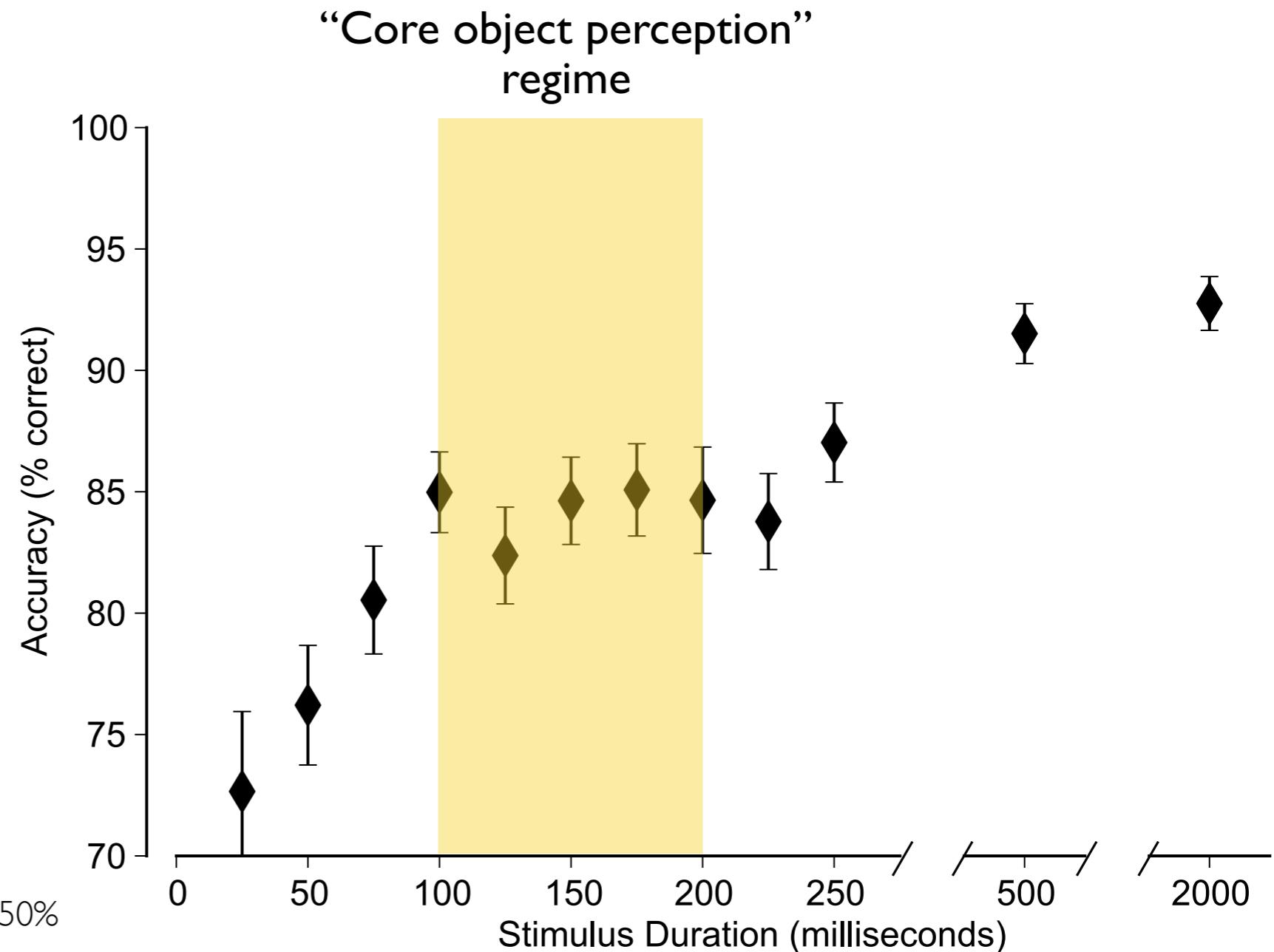


Problem: Entity Extraction



Basic level categorization

Chance is 50%

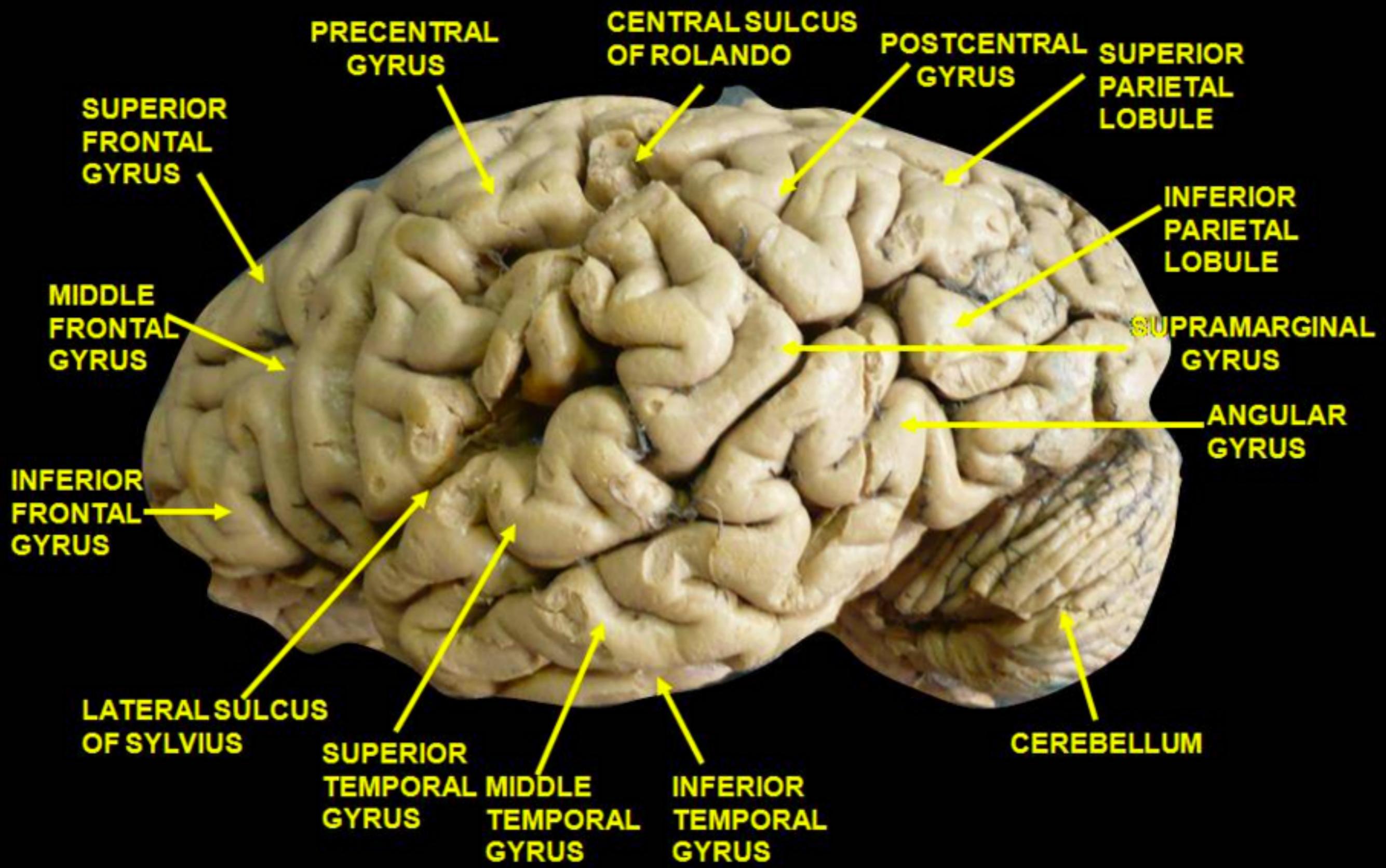


All the data I will show
you today



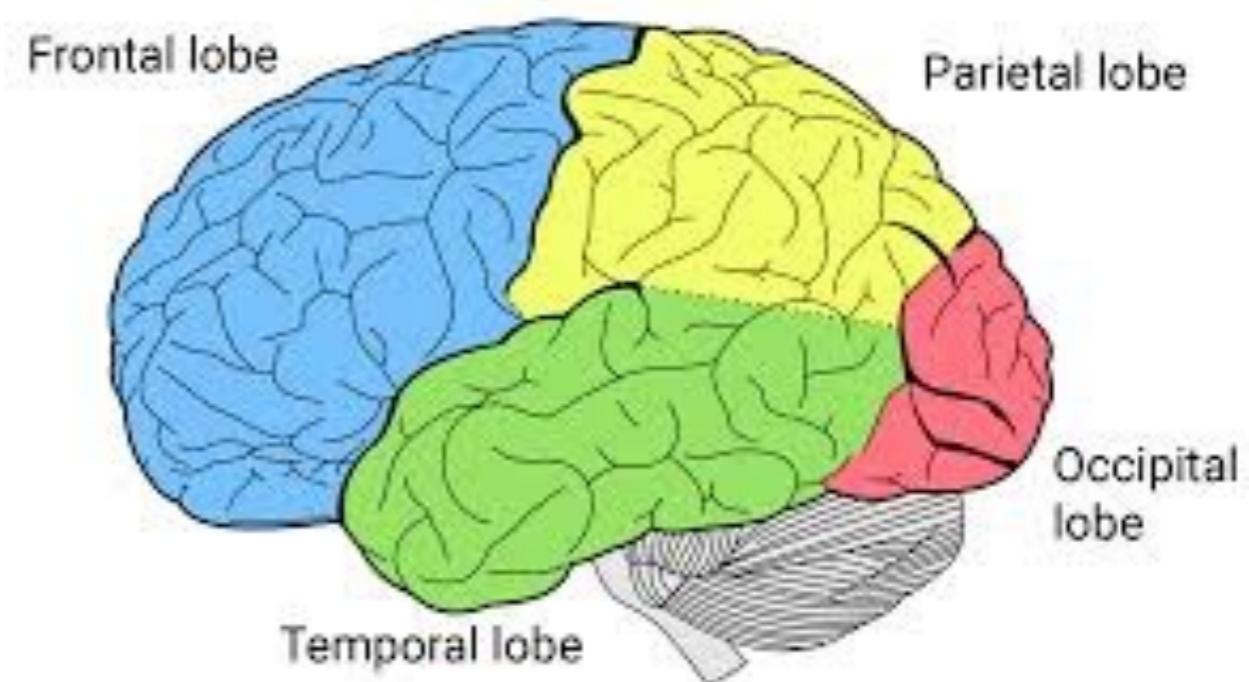
Typical primate fixation
duration during natural
viewing





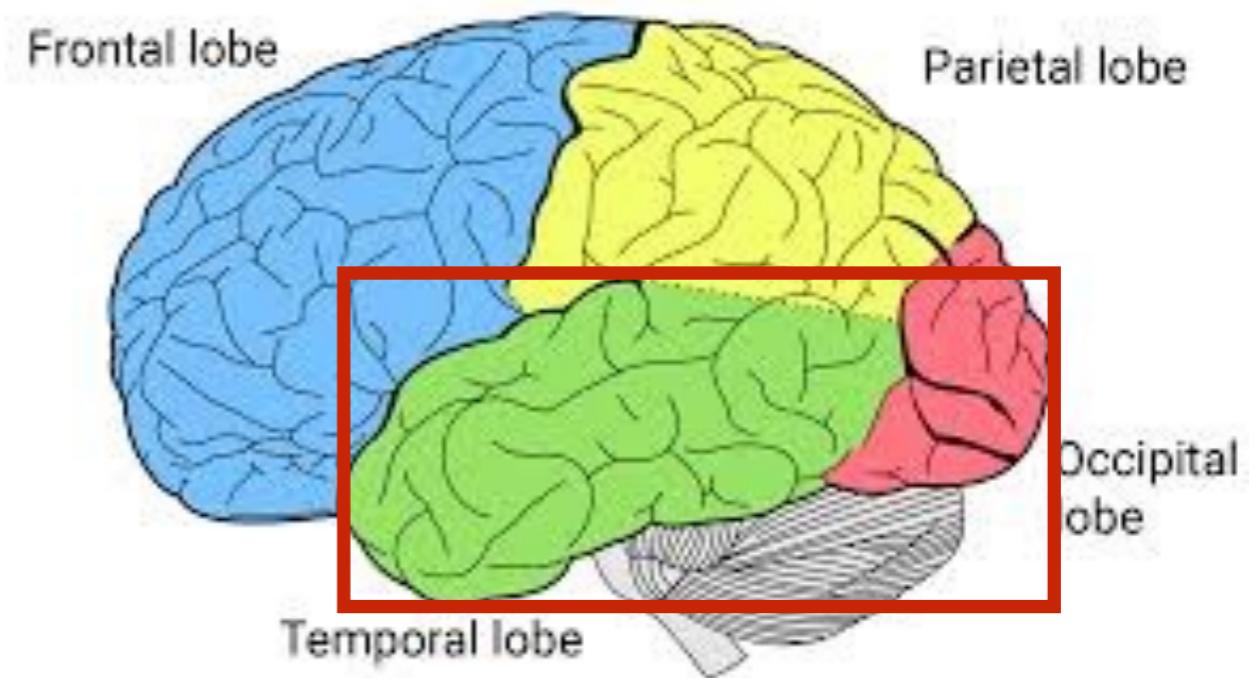
Many Different Computational Goals

- ▶ Sensory processing
 - visual, auditory, somatosensory recognition (occipital, temporal)
 - navigation (hippocampus?)
- ▶ motor command production & execution (motor cortex)
- ▶ memory, decision making and planning (hippocampus, prefrontal cortex)
- ▶ language
- ▶ emotions, theory-of-mind



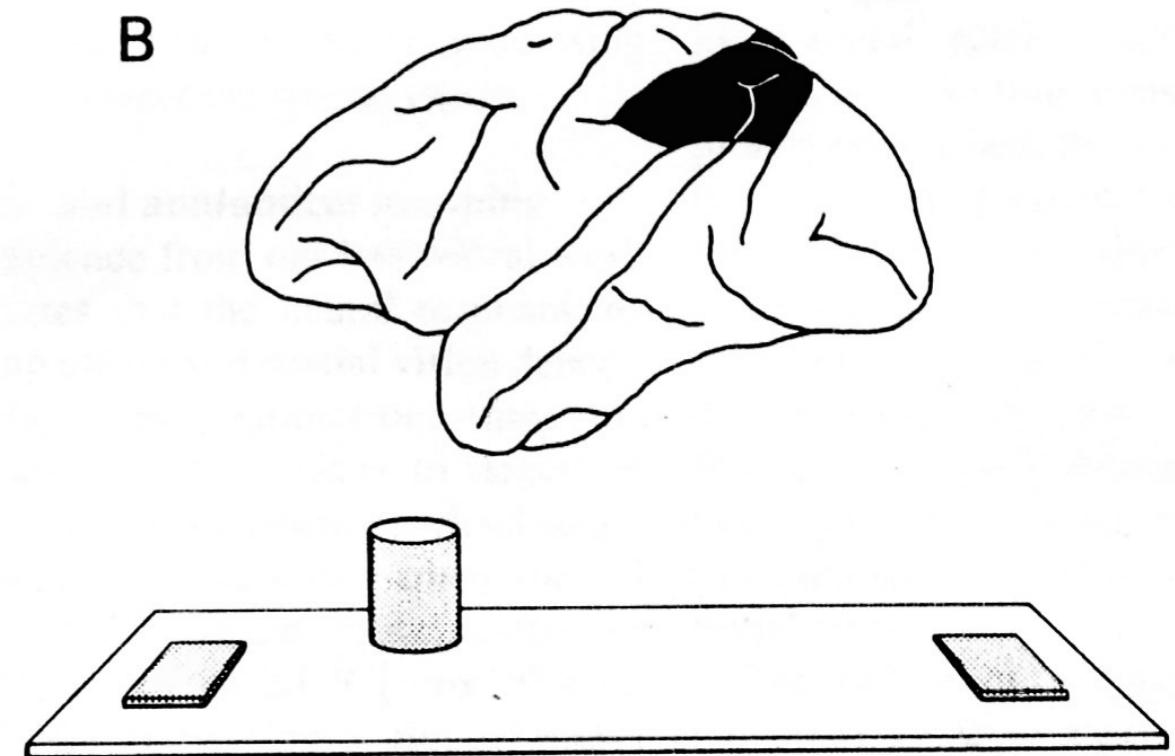
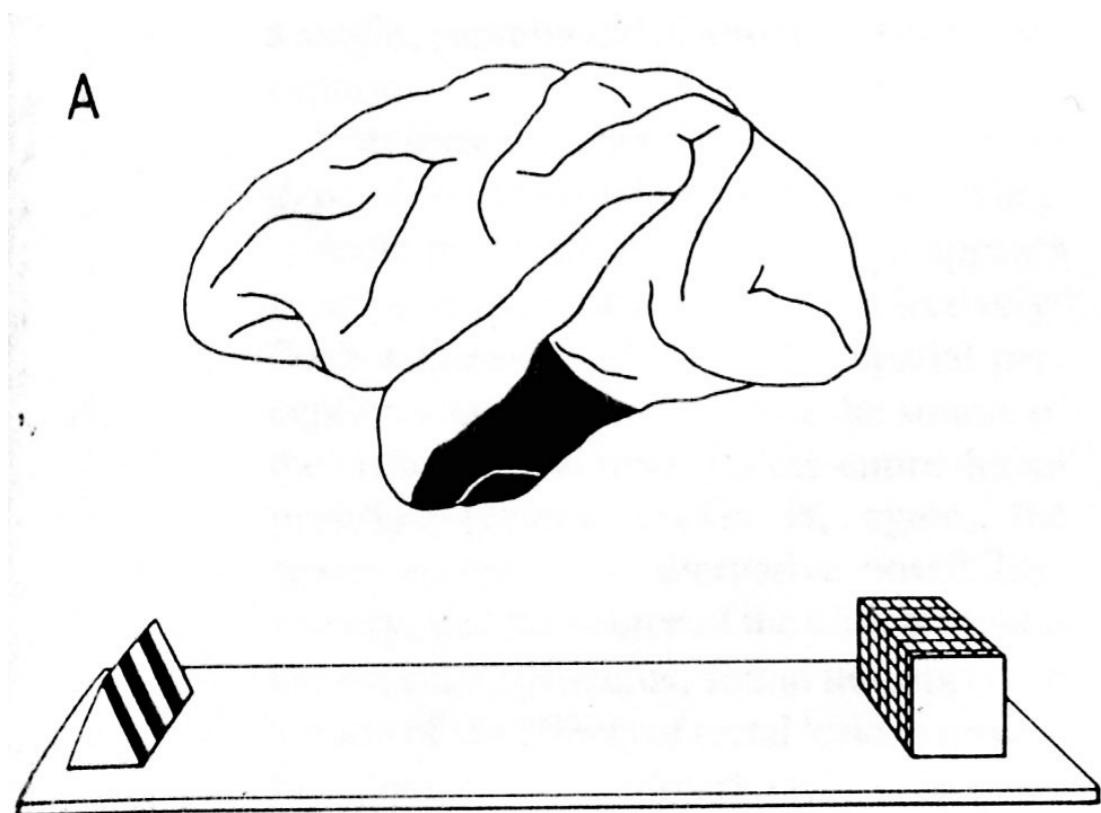
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Background: Ventral visual stream

Mishkin & Ungerleider, 1982



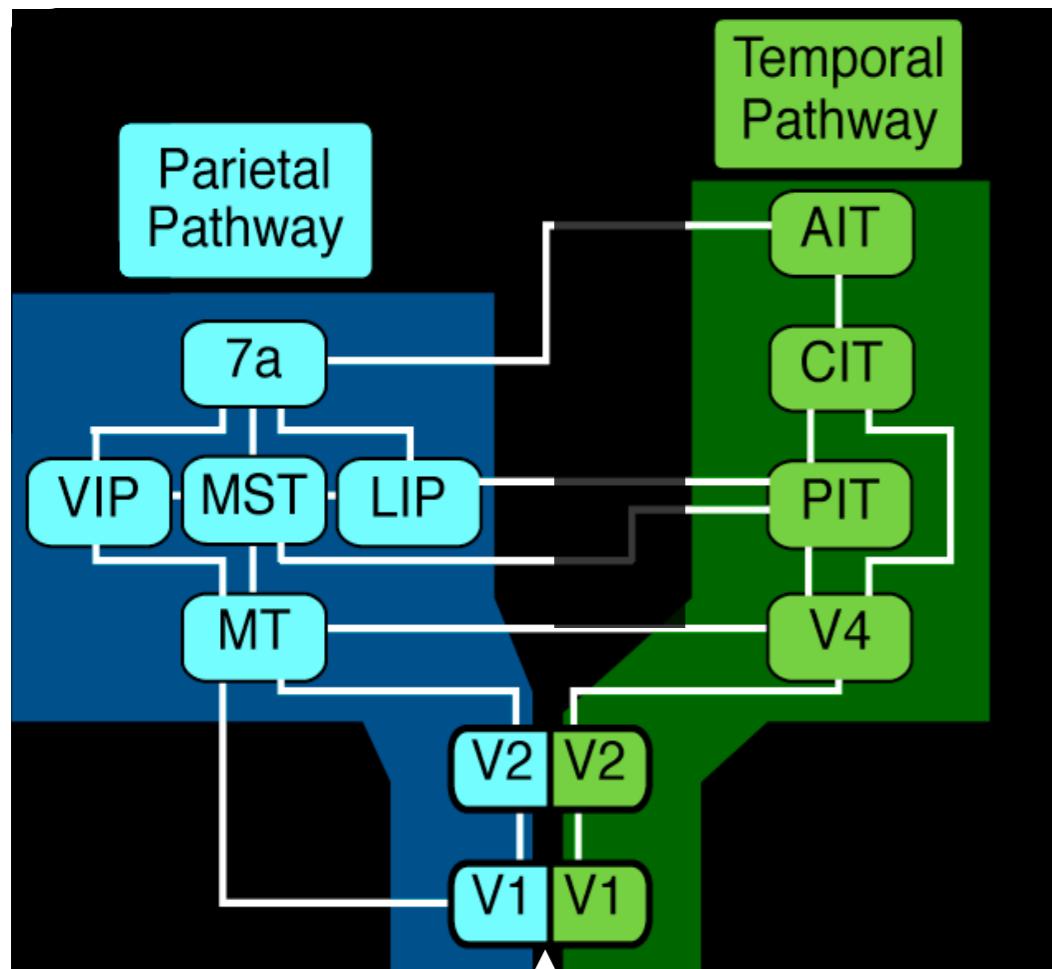
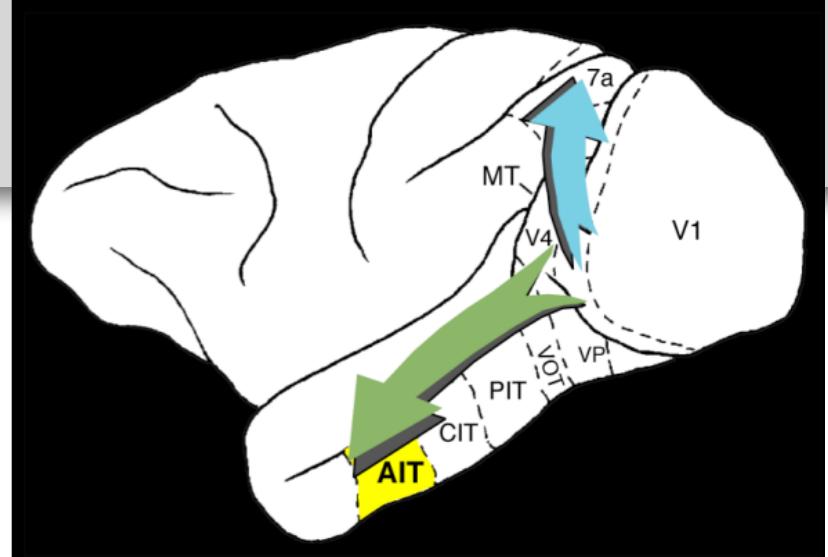
“what” / ventral / occipitotemporal

Lesions in IT cortex produce deficits in shape discrimination tasks (Gross et al, 1973, Mishkin 1982)

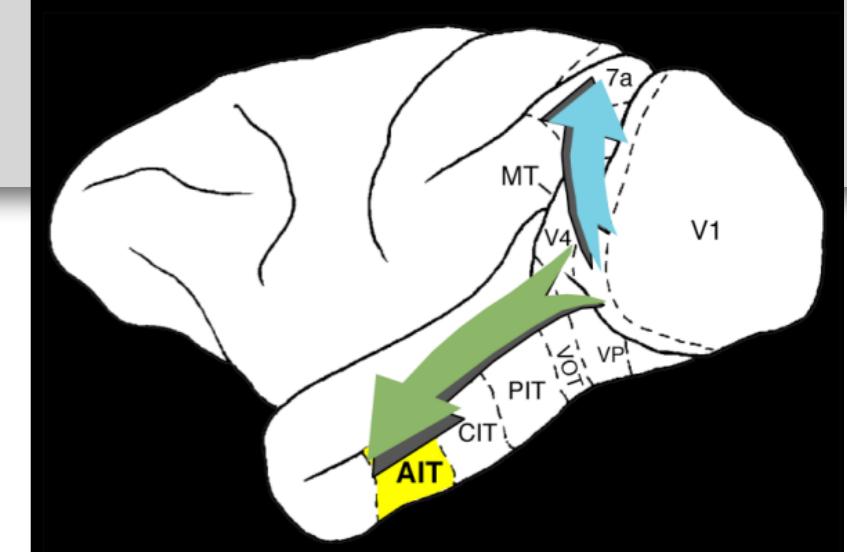
“where” / dorsal / parietal

Lesions in parietal cortex produce deficits in landmark task (Pohl et al. 1973)

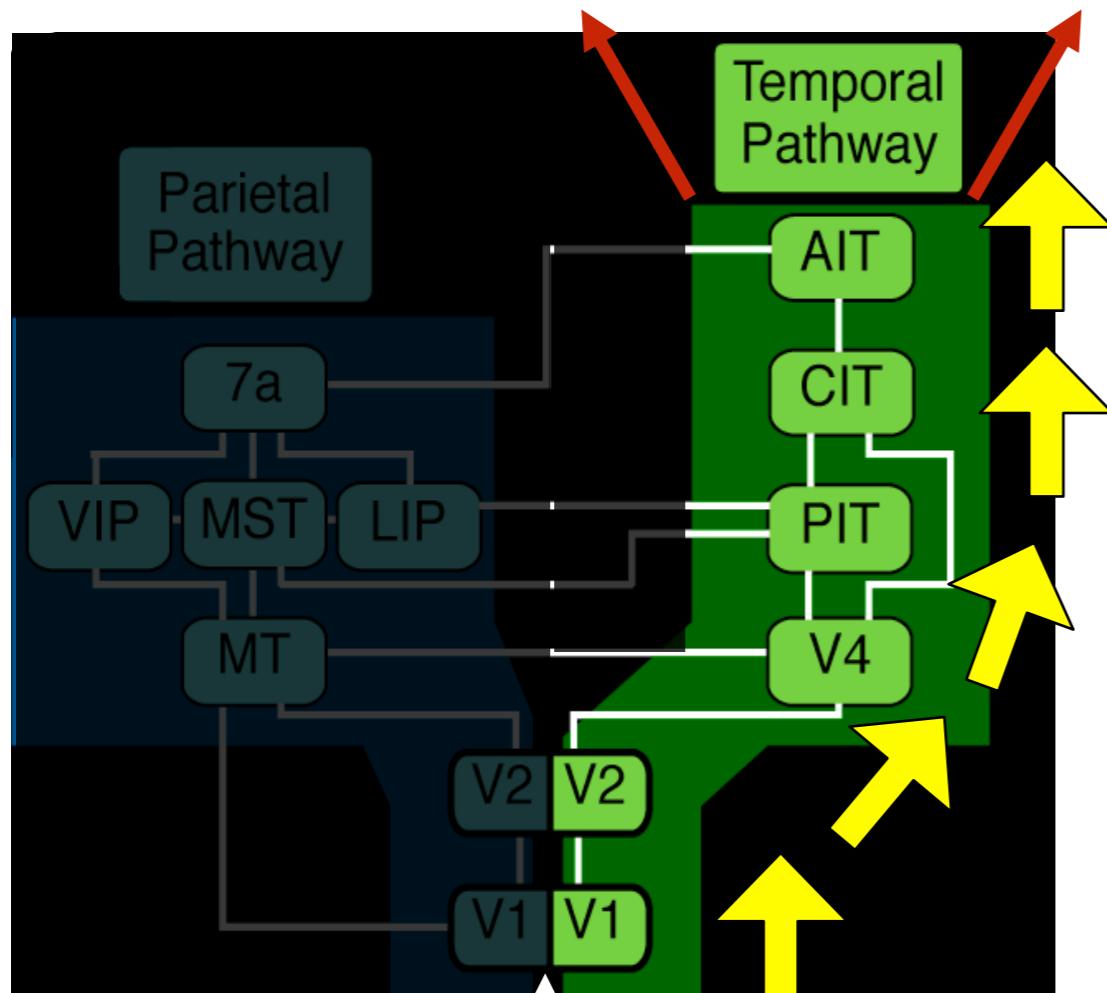
Background: Ventral visual stream



Background: Ventral visual stream



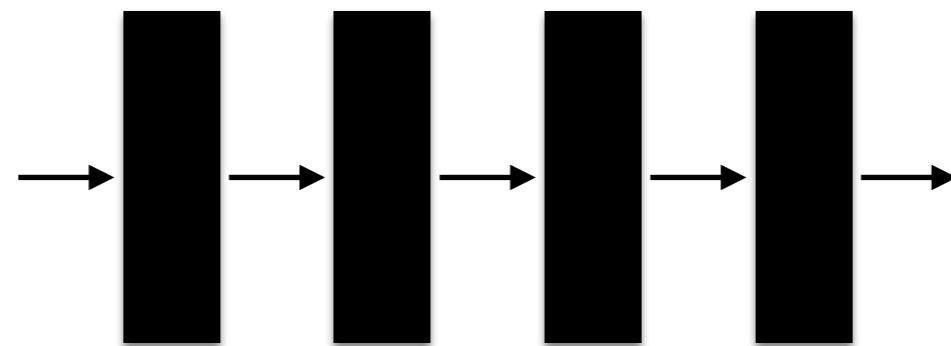
Decision and action Memory



- Tolerance to identity-preserving transforms
- Ability to support visual recognition
- Correlation with perceptual report
- Sensitivity to behavioral state (e.g. attention)
- Visually-evoked latency
- Selectivity to visual “feature” conjunctions
- Effects of experience (*plasticity*)

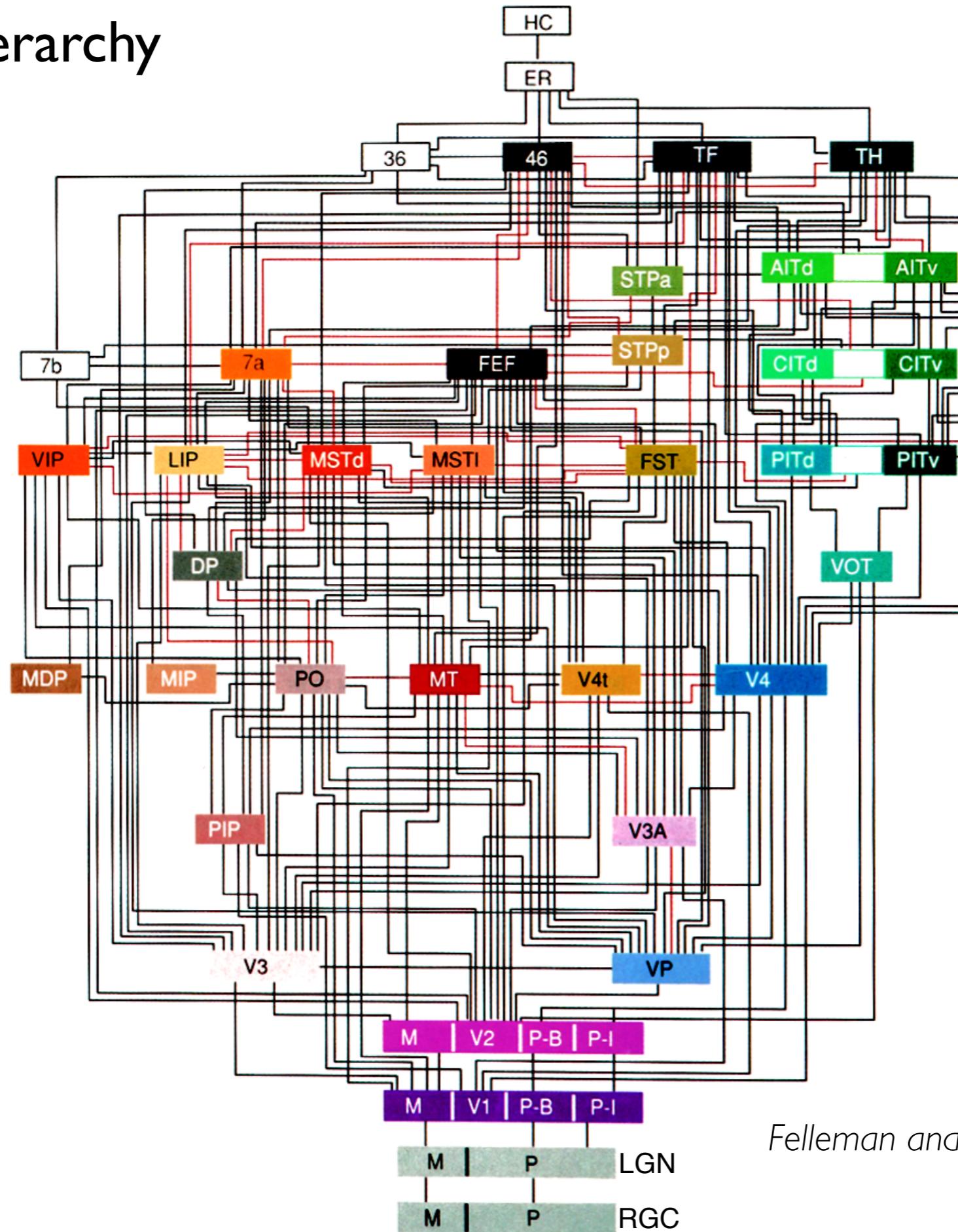
Sensory cascade

sensory cascade in
visual (mostly-) cortex



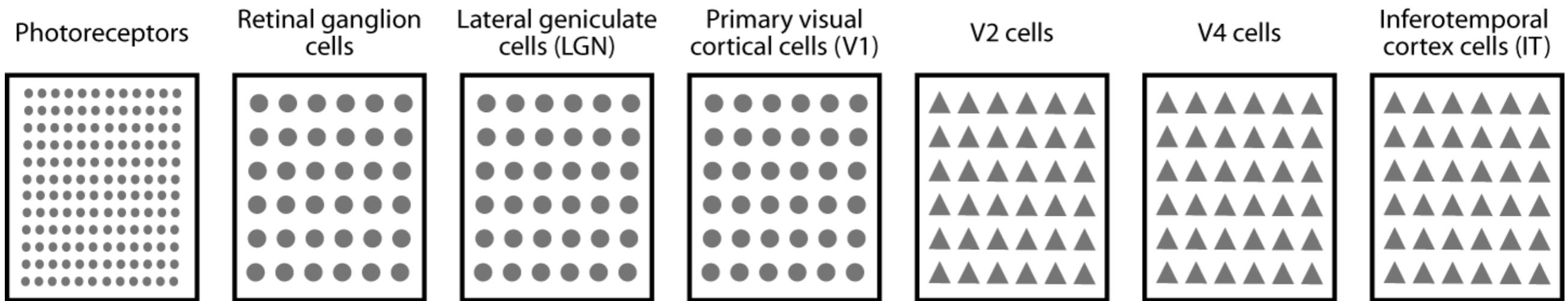
Madame Curie!

Visual area hierarchy

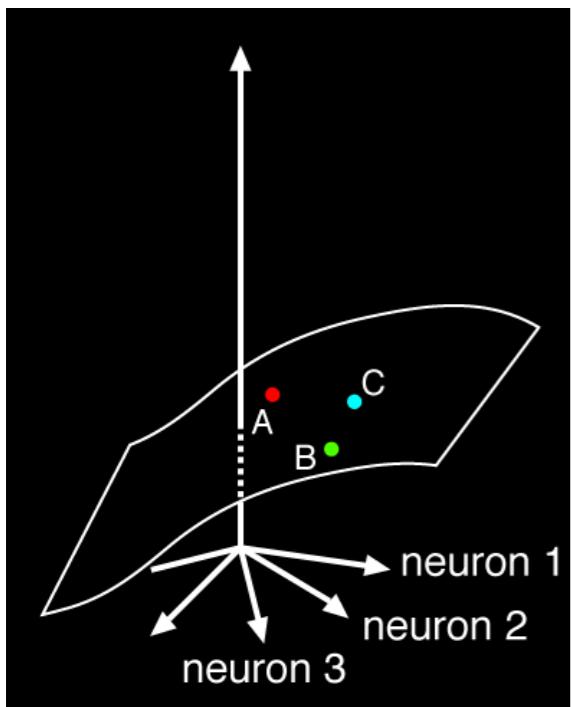


Felleman and Van Essen, 1991

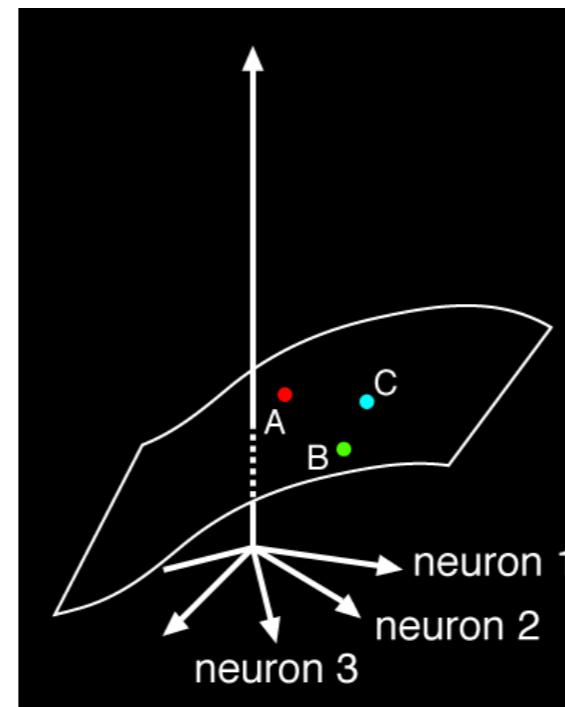
How does the brain represent the visual world?



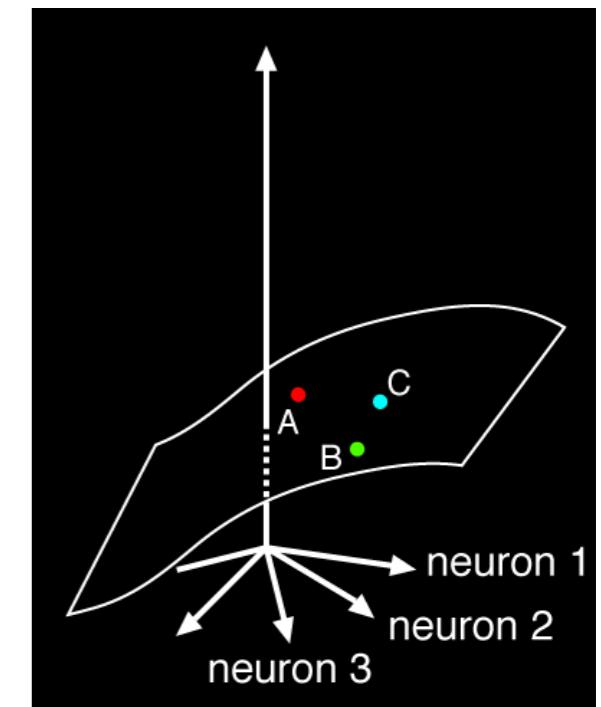
photoreceptor representation



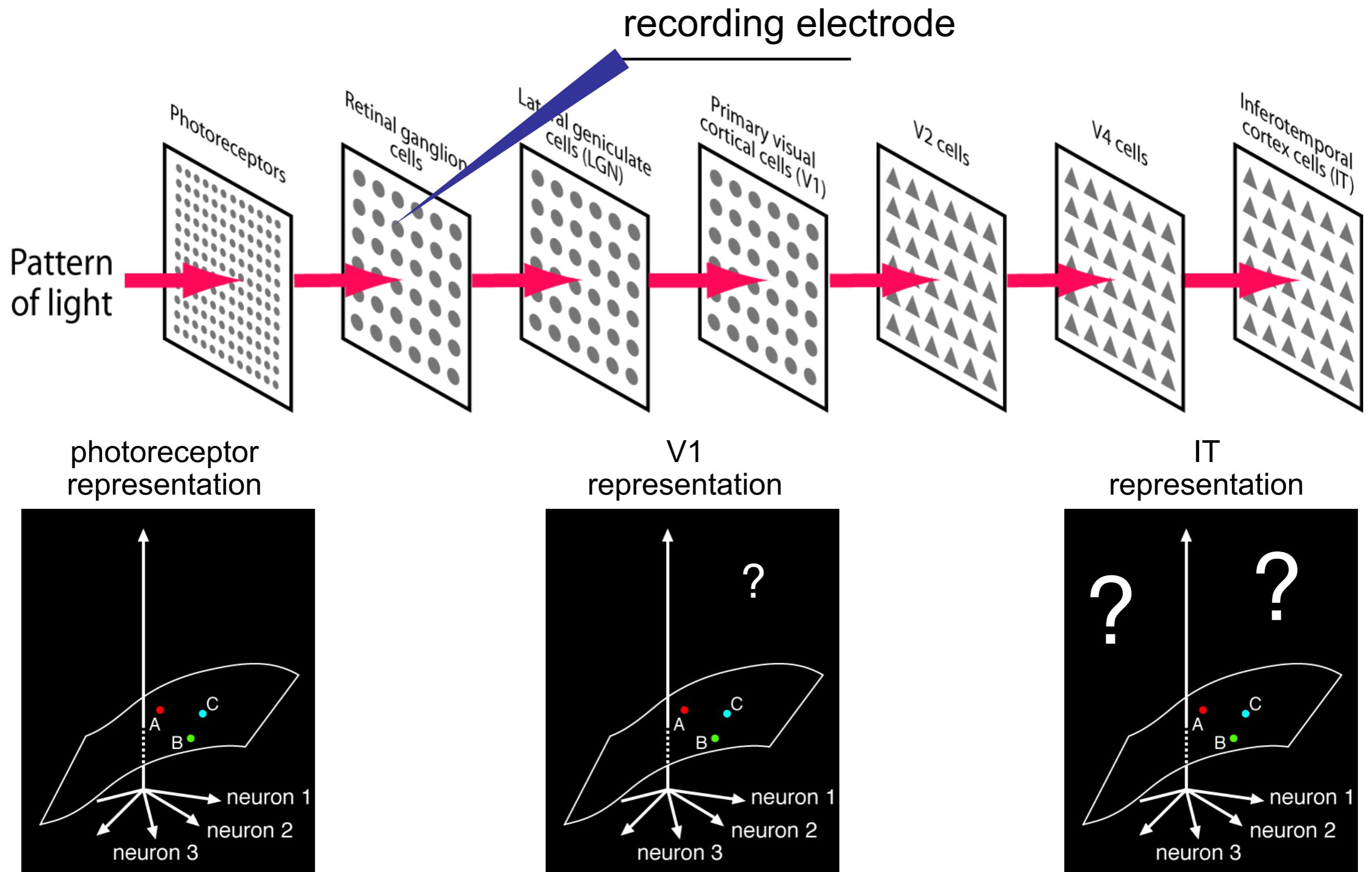
V1 representation



IT representation

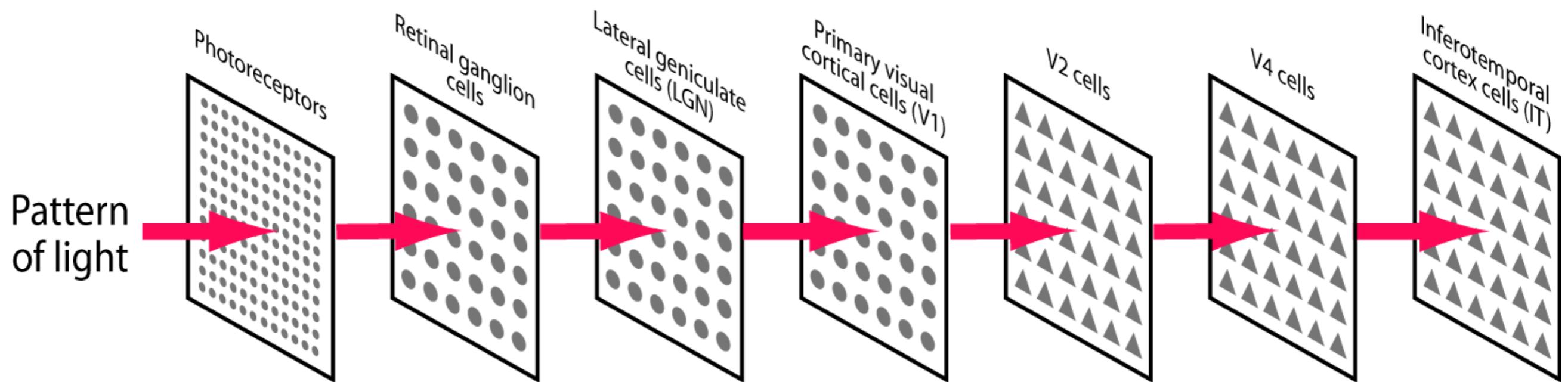


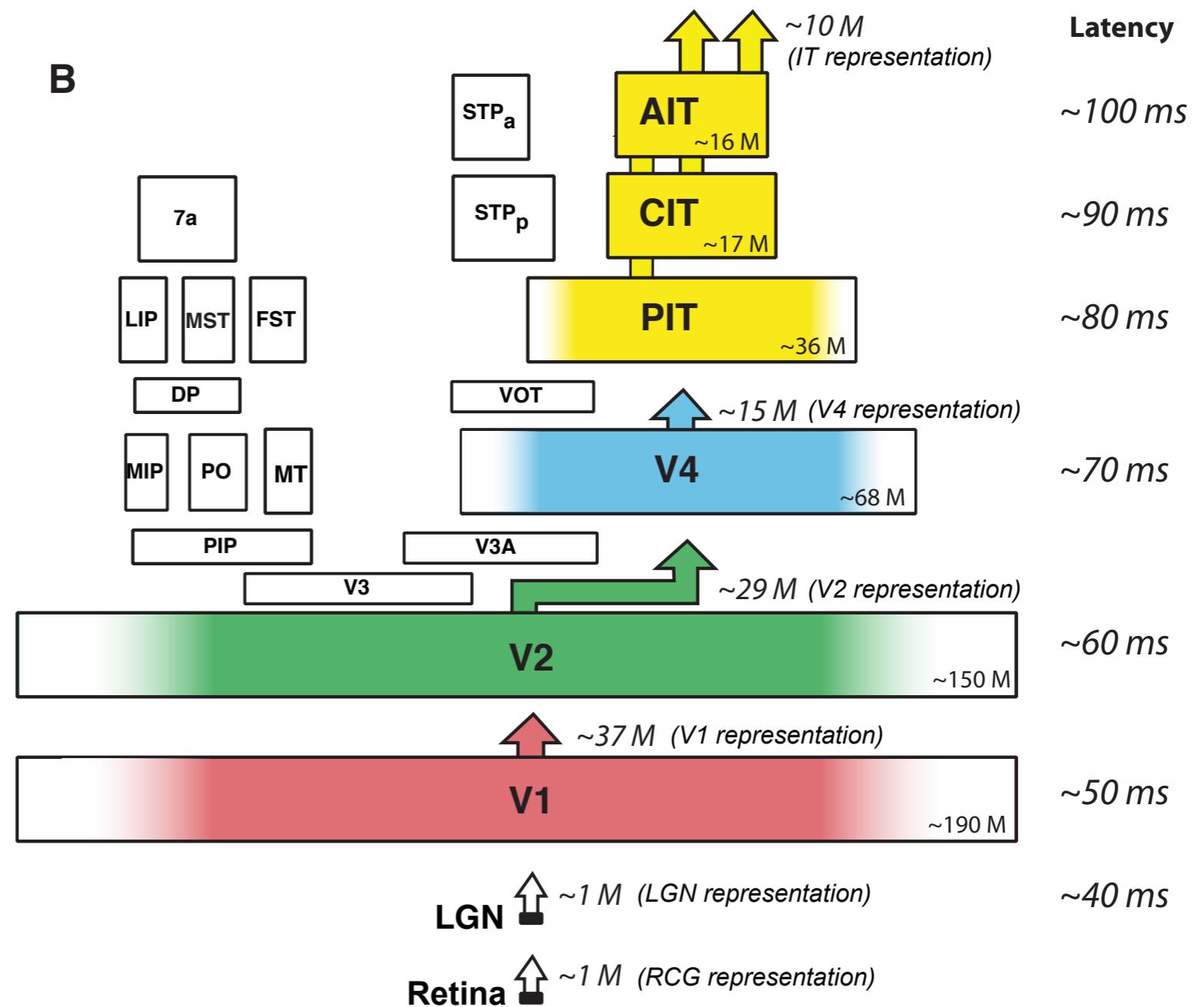
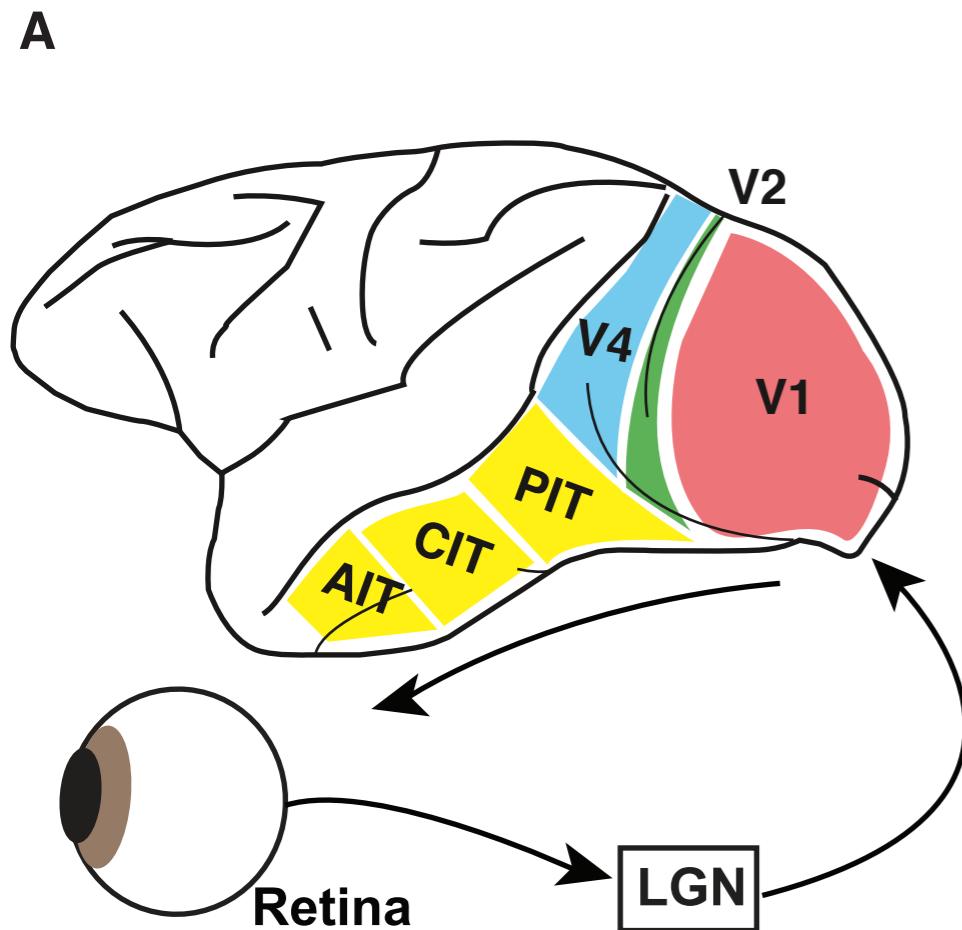
How does the brain **re-represent** the visual world?



Four important pieces on information

- 1) Neuronal selectivity generally increases as we move up the cortical hierarchy
- 2) Receptive field (RF) size generally increases as we move up the cortical hierarchy
- 3) Selectivity pattern is typically apparent at the time first spikes are elicited by a visual stimulus (“feedforward” assumption)
- 4) There is hierarchy of times at which first spikes are detected.



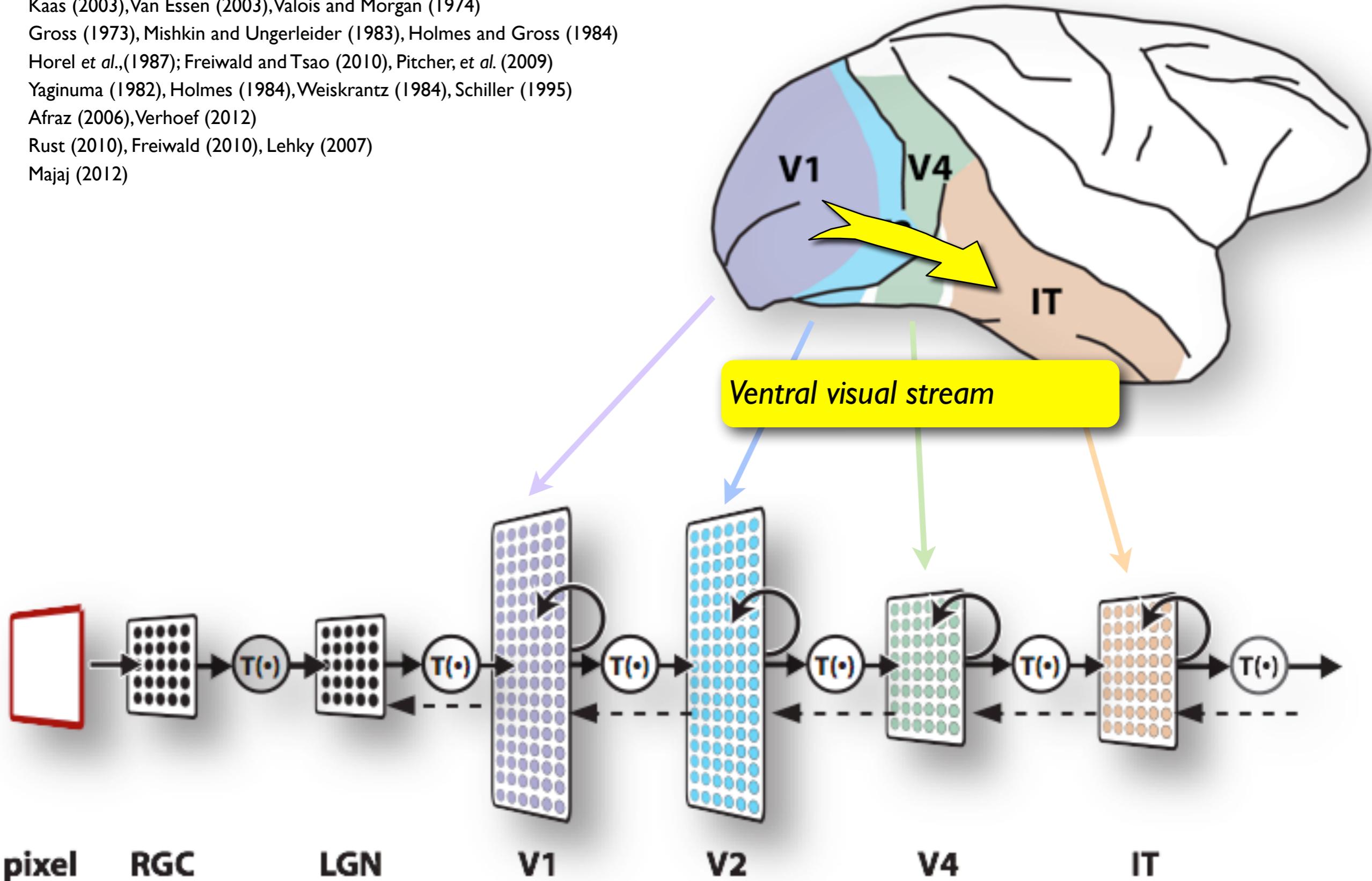


Adapted from DiCarlo et al. 2012

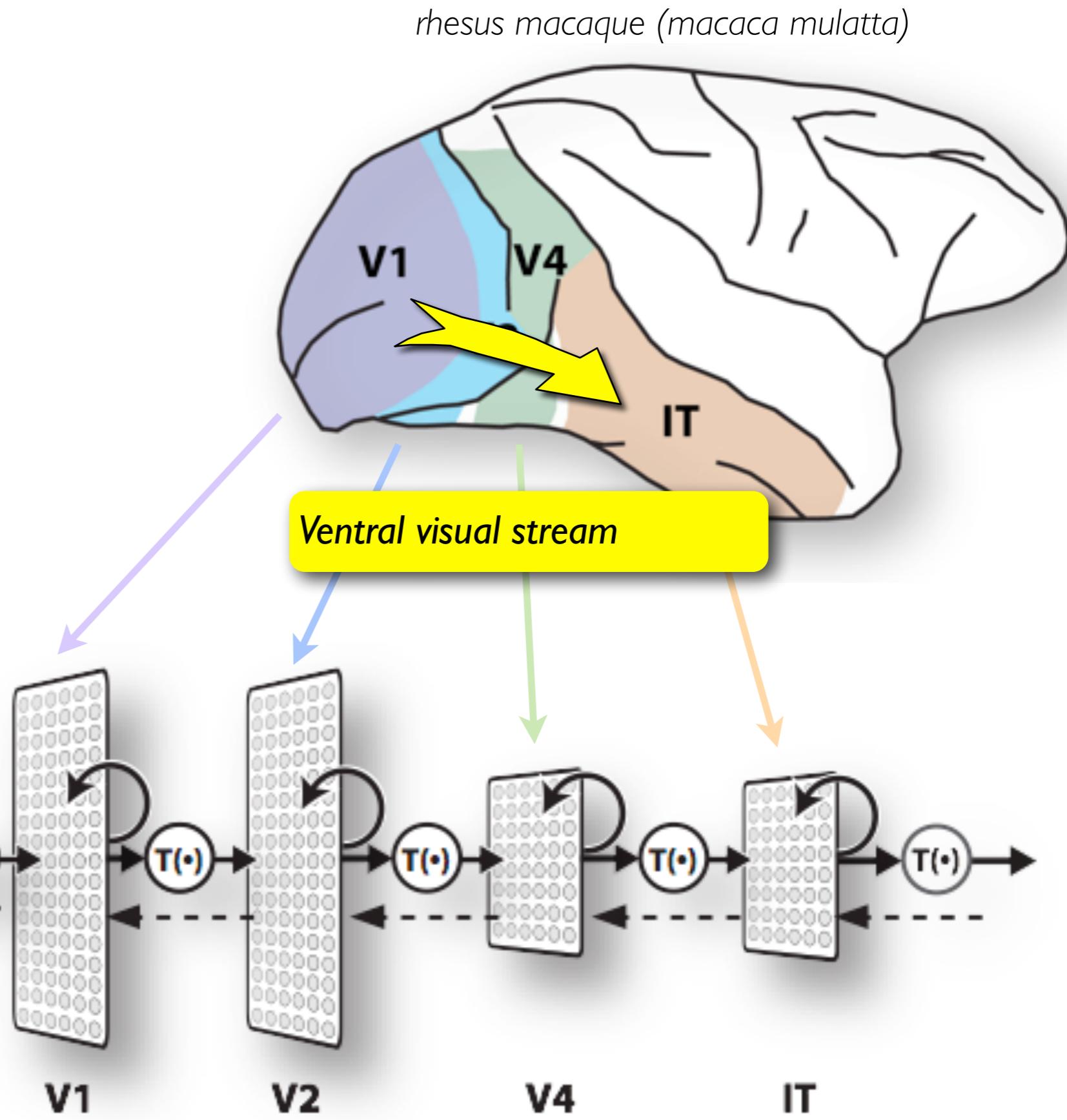
Background: Ventral visual stream

Kaas (2003), Van Essen (2003), Valois and Morgan (1974)
Gross (1973), Mishkin and Ungerleider (1983), Holmes and Gross (1984)
Horel et al., (1987); Freiwald and Tsao (2010), Pitcher, et al. (2009)
Yaginuma (1982), Holmes (1984), Weiskrantz (1984), Schiller (1995)
Afraz (2006), Verhoef (2012)
Rust (2010), Freiwald (2010), Lehky (2007)
Majaj (2012)

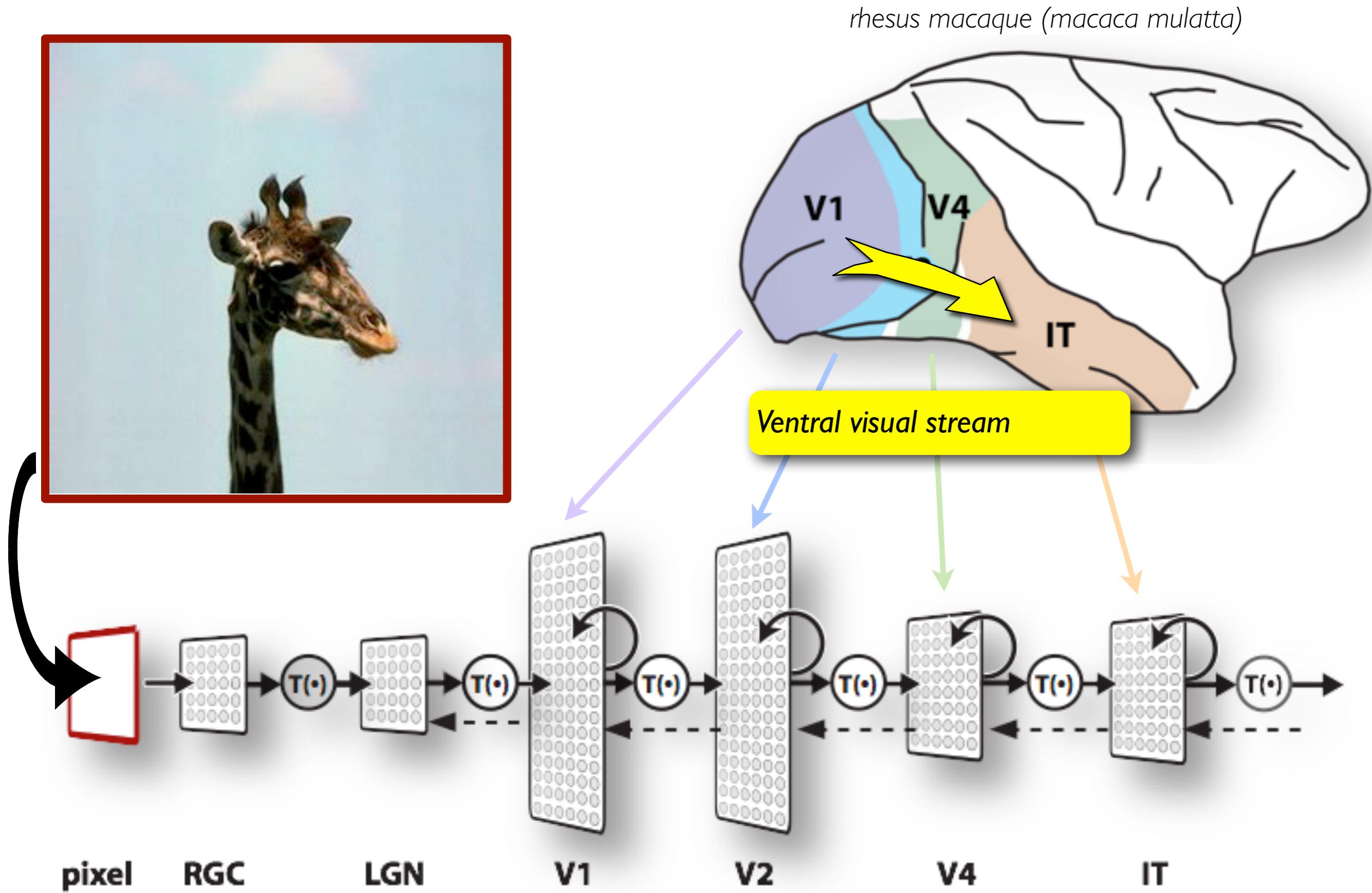
rhesus macaque (*macaca mulatta*)



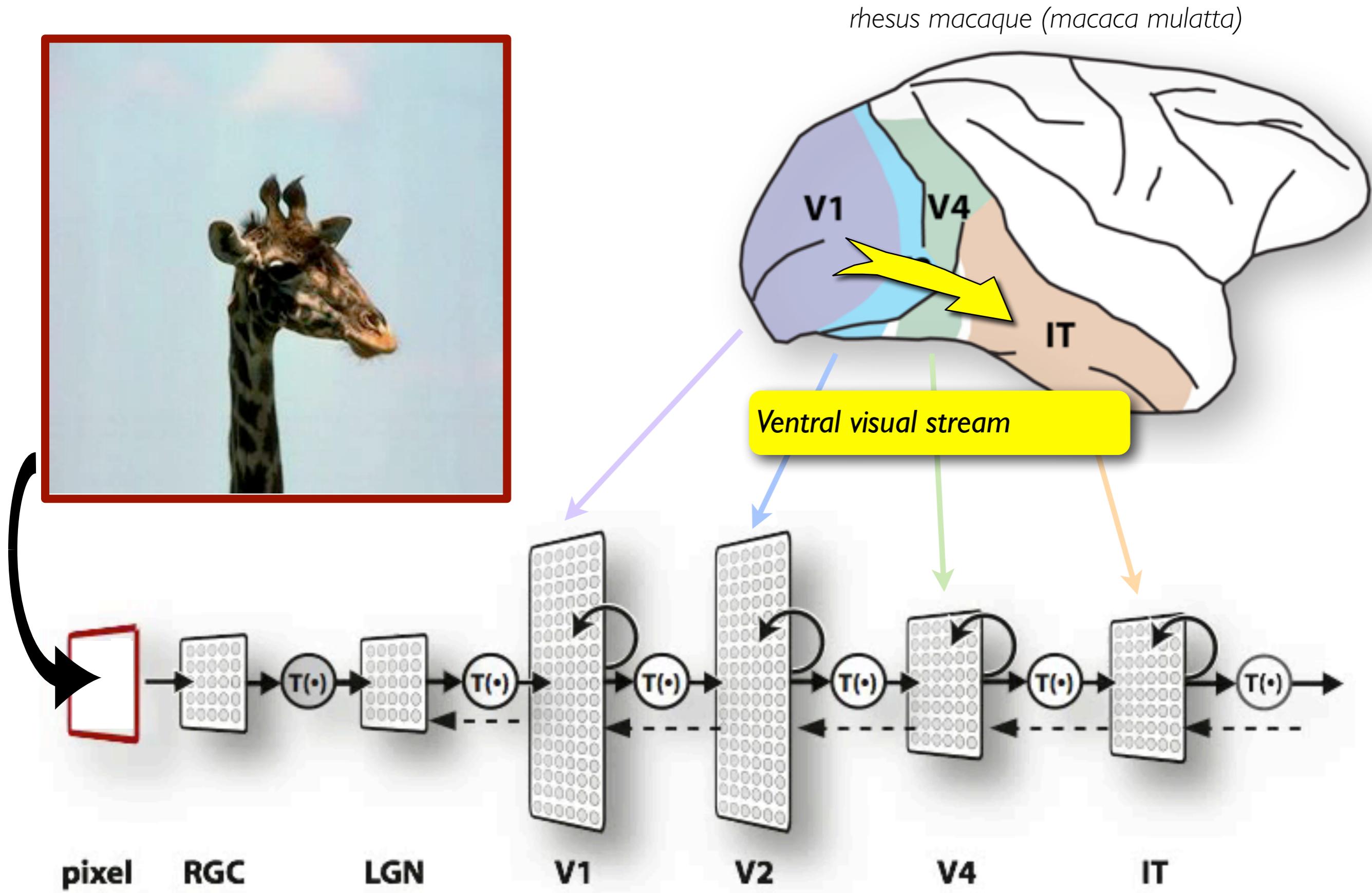
Background: Ventral visual stream



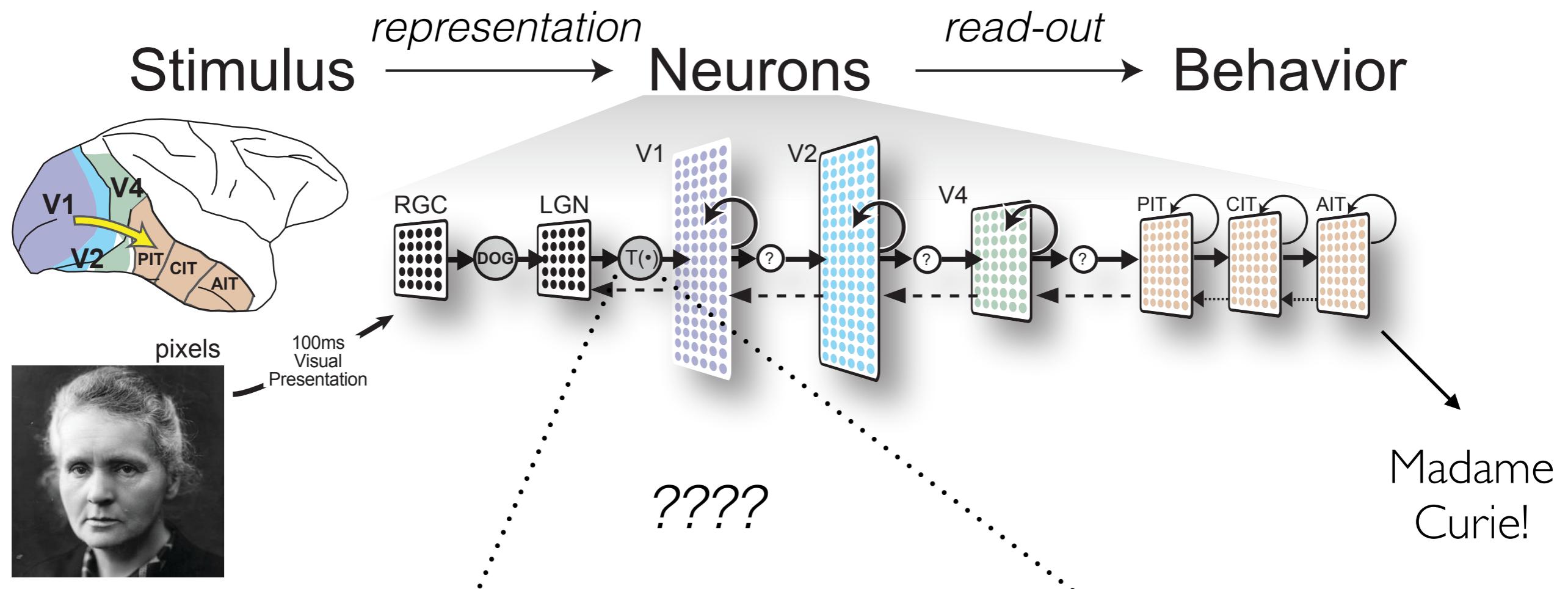
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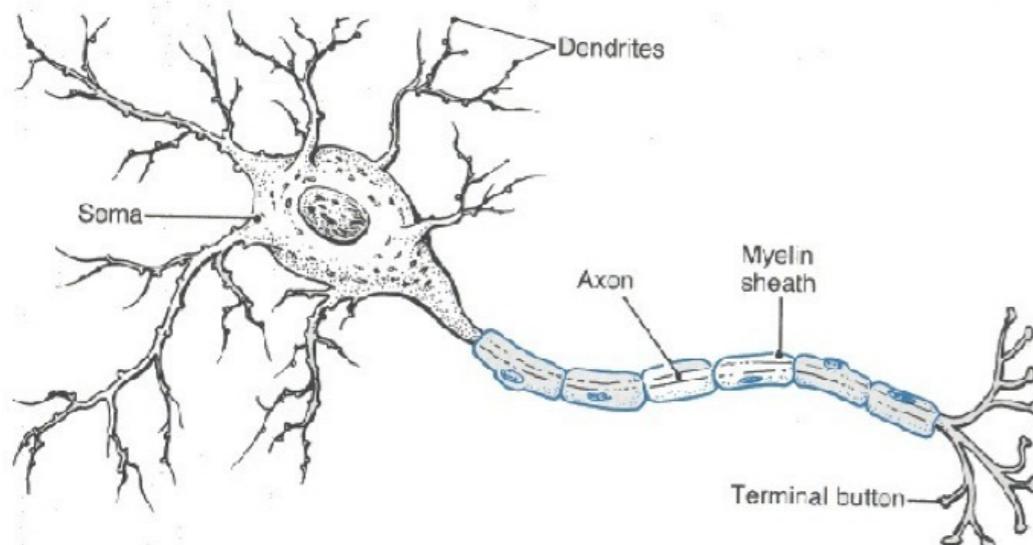


Ventral Stream = Connected series of brain areas



Recall ...

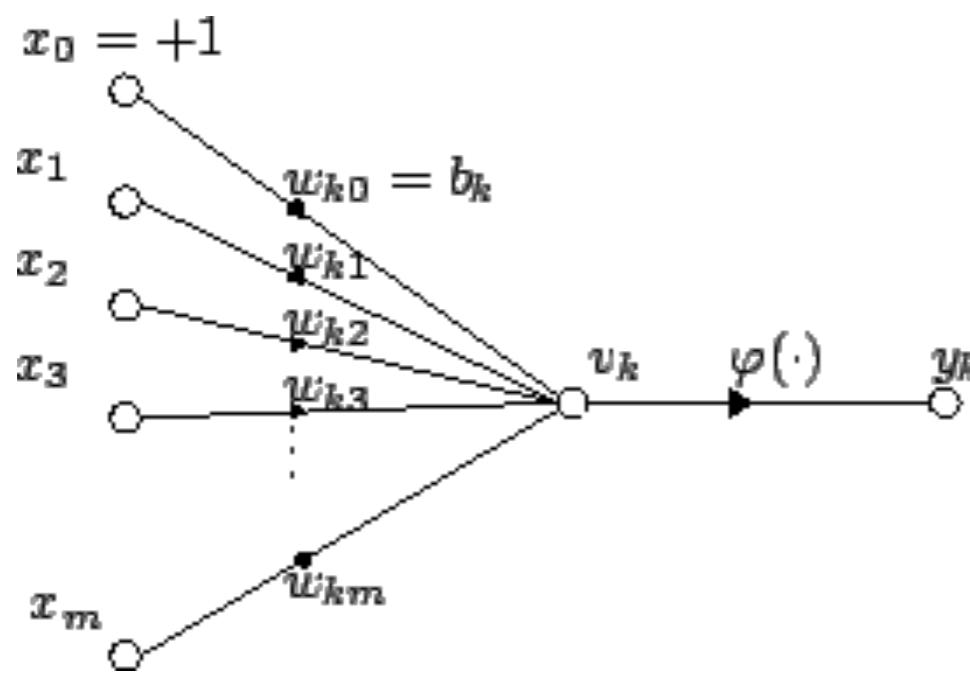
McCulloch and Pitts (1943)



$$y_k = \phi \left(\sum_{j=0}^m w_{kj} x_j + b_k \right)$$

$$\phi : \mathbb{R} \longmapsto \mathbb{R}$$

some nonlinear activation function



$$w_{kj} \in \mathbb{R}^{m+1}$$

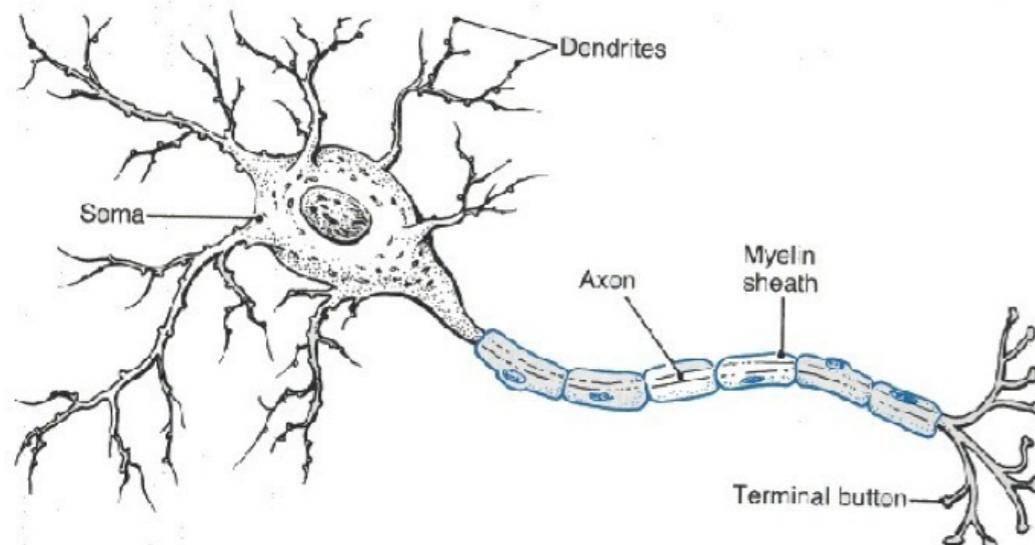
“synaptic strengths”

$$b_j \in \mathbb{R}$$

“biases”

Recall ...

McCulloch and Pitts (1943)

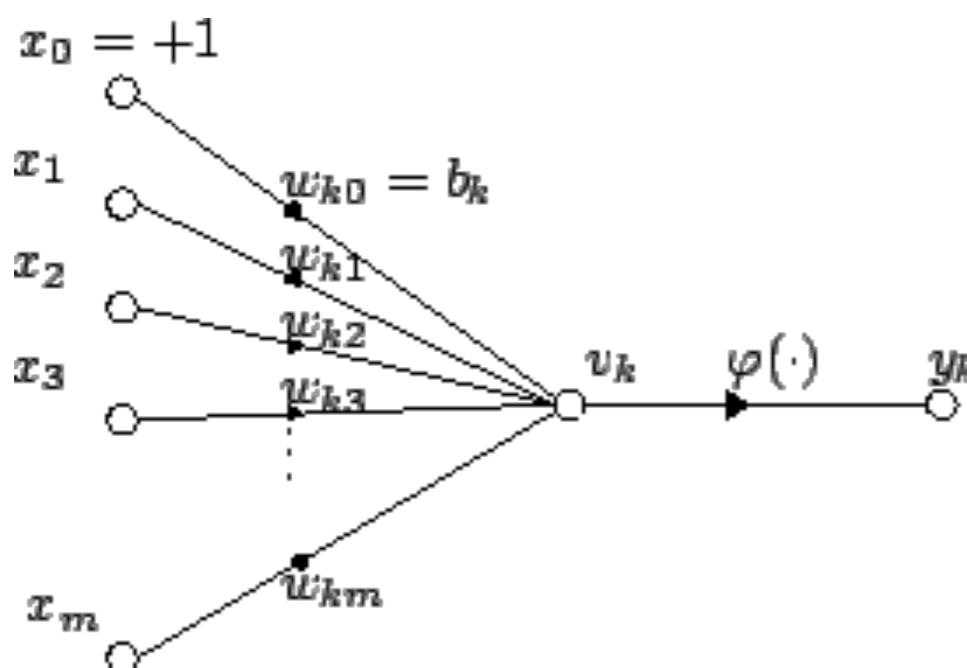


$$y_k = \phi \left(\sum_{j=0}^m w_{kj} x_j + b_k \right)$$

???

$$\phi : \mathbb{R} \longmapsto \mathbb{R}$$

some (nonlinear) activation function



???

$$w_{kj} \in \mathbb{R}^{m+1}$$

“synaptic strengths”

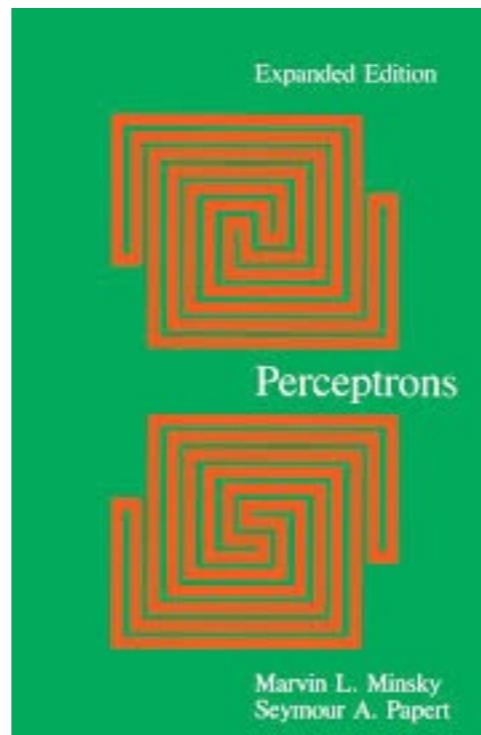
$$b_j \in \mathbb{R}$$

“biases”

and what's the connectivity?

Cautionary tale

Minsky & Papert (1969)



$$y_k = \phi \left(\sum_{j=0}^m w_{kj} x_j + b_k \right)$$

$$\phi : \mathbb{R} \longmapsto \mathbb{R}$$

1. better have more than one layer



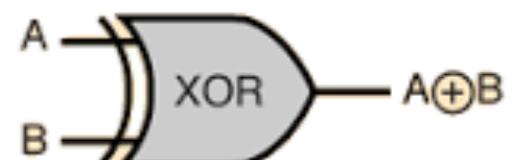
$$\sum_{i=0}^N v_i \phi(w_i^T x + b_i)$$

at least (and which, according to the UAT, is enough)

cause otherwise ... ain't no XOR

and what's the connectivity?

2. better be actually nonlinear



A	B	Out
0	0	0
0	1	1
1	0	1
1	1	0

Limitations of Perceptrons



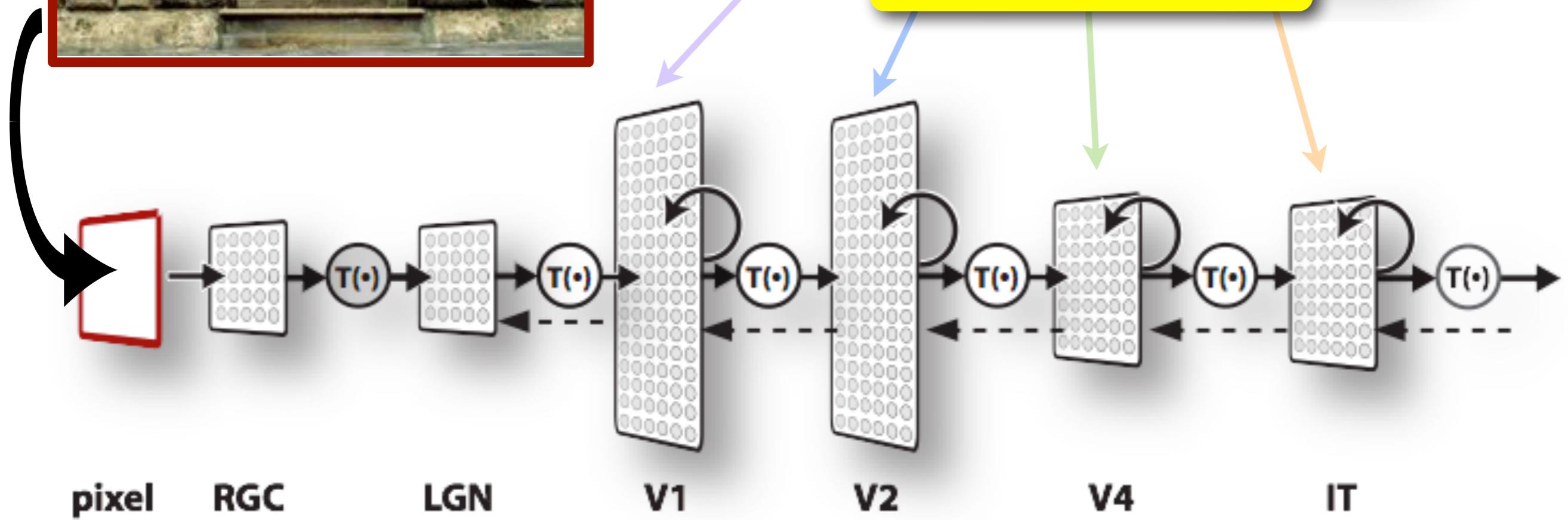
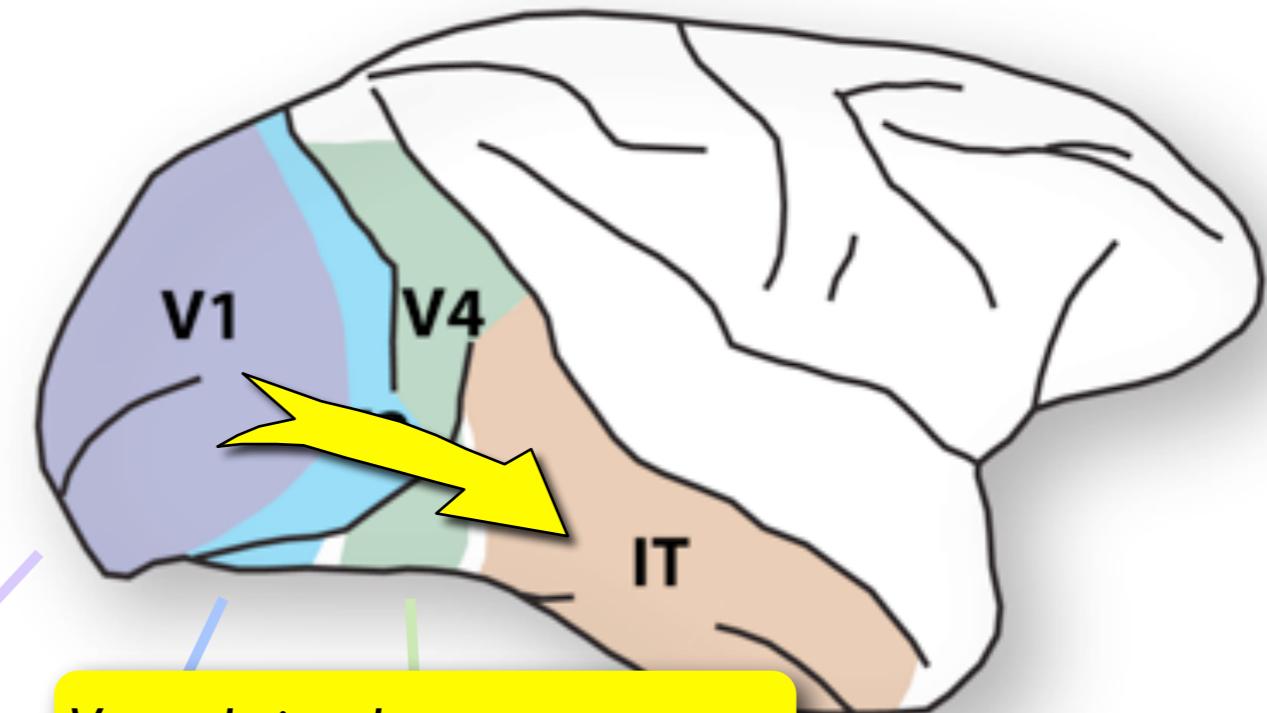
- *Minsky & Papert published (1969) “Perceptrons” stressing the limitations of perceptrons*
- *Single-layer perceptrons cannot solve problems that are linearly inseparable (e.g., xor)*
- *Most interesting problems are linearly inseparable*
- *Kills funding for neural nets for 12-15 years*



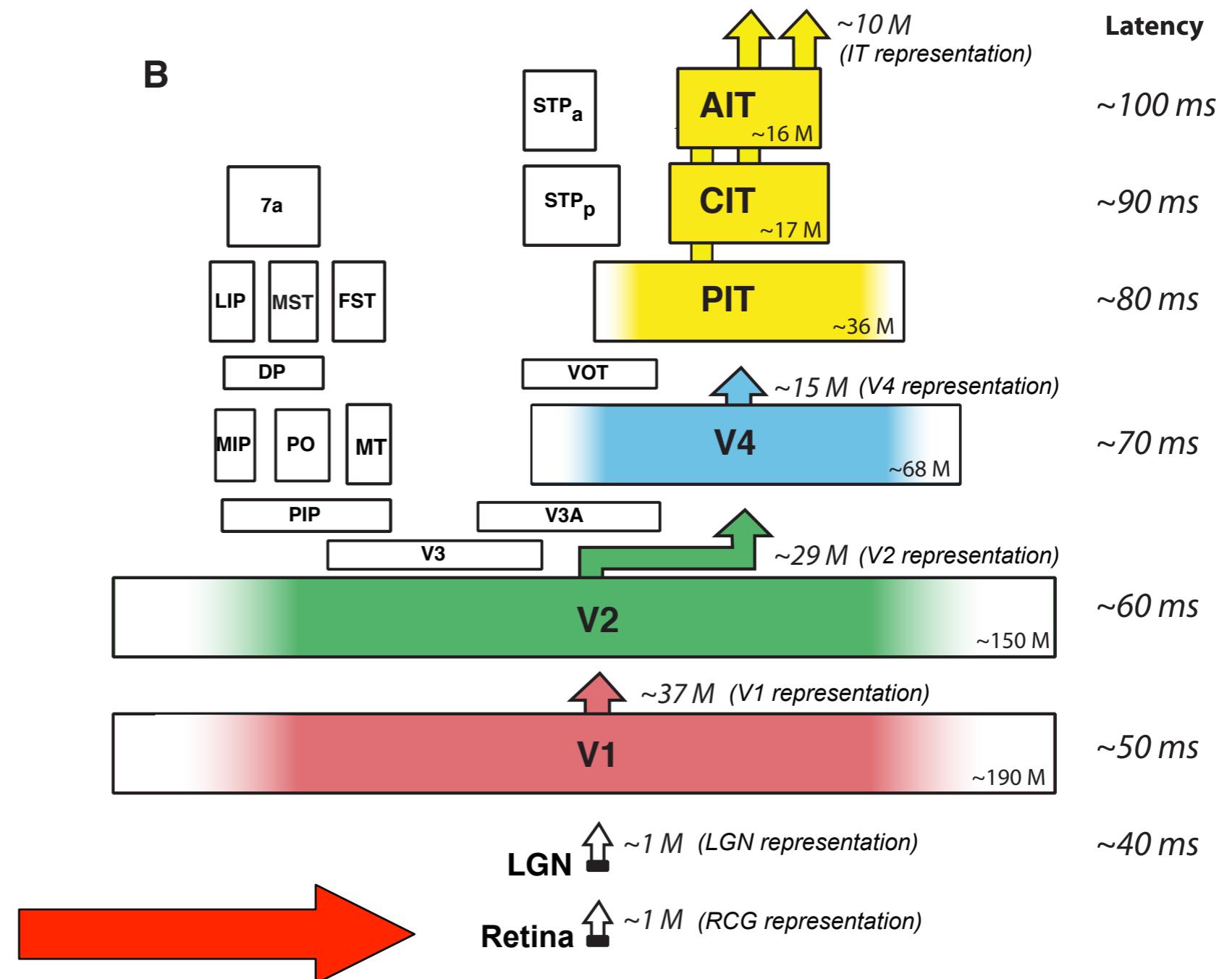
Maybe a bit apocryphal but I can definitely say from personal experience that MIT CSAIL felt very “anti-neural networks” as late as 2012

Ventral Stream = Connected series of brain areas

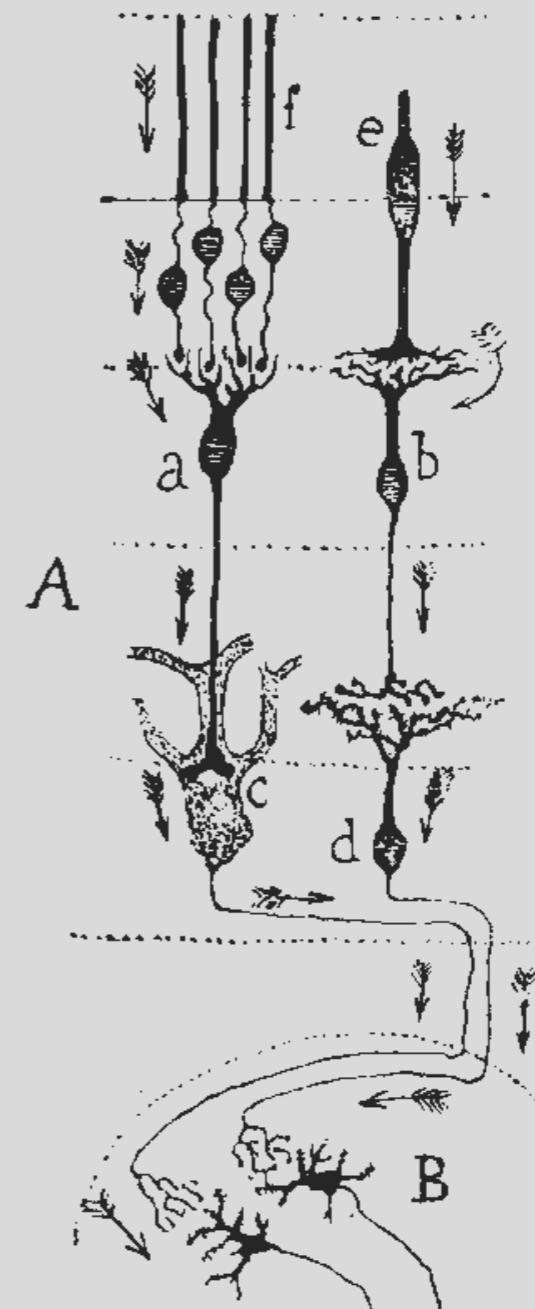
neuroanatomy + neurophysiology tell us:



You are here.



Origins in the Retina



Ramon y Cajal from Rodieck
(1973)

Origins in the Retina

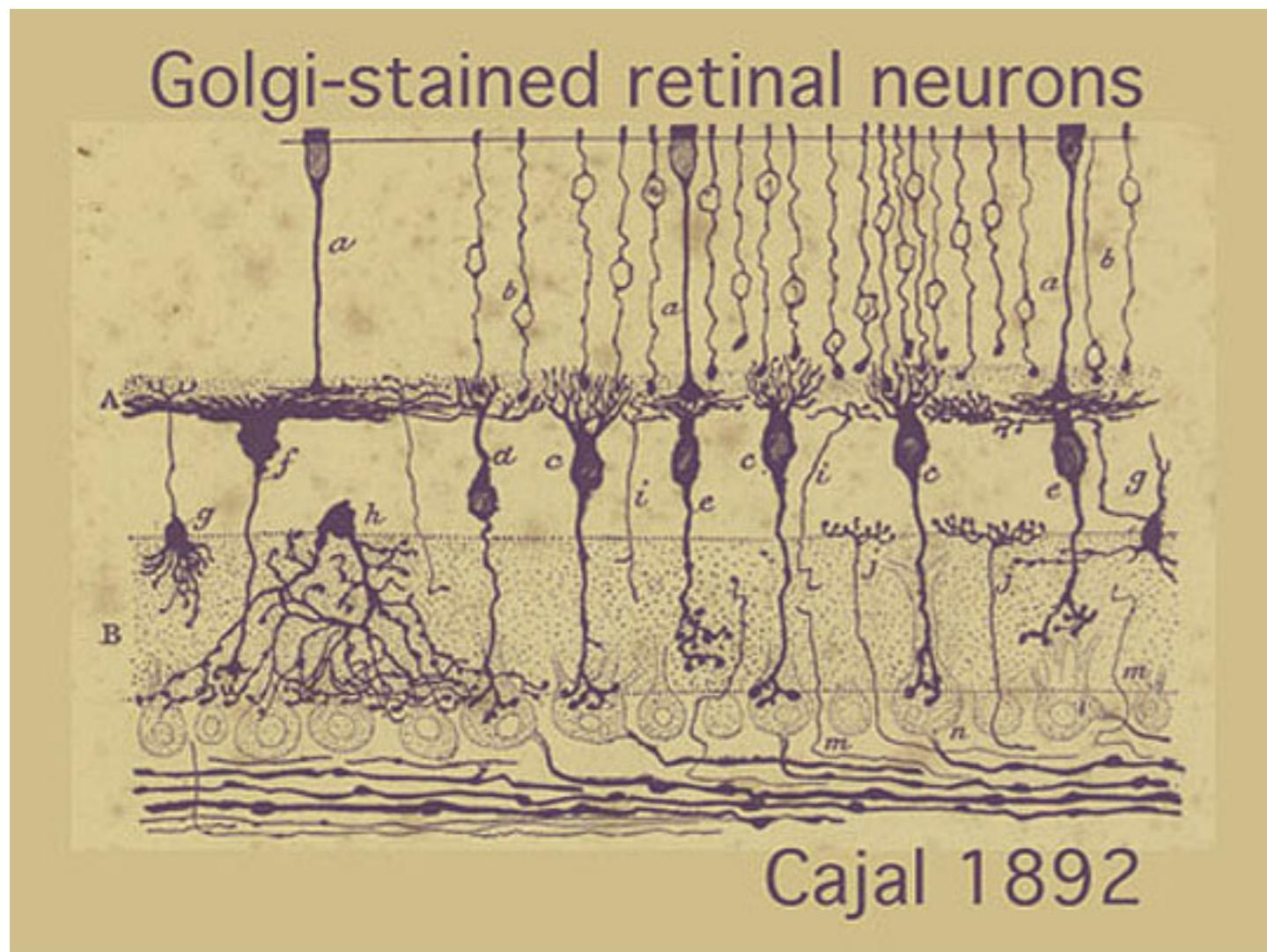
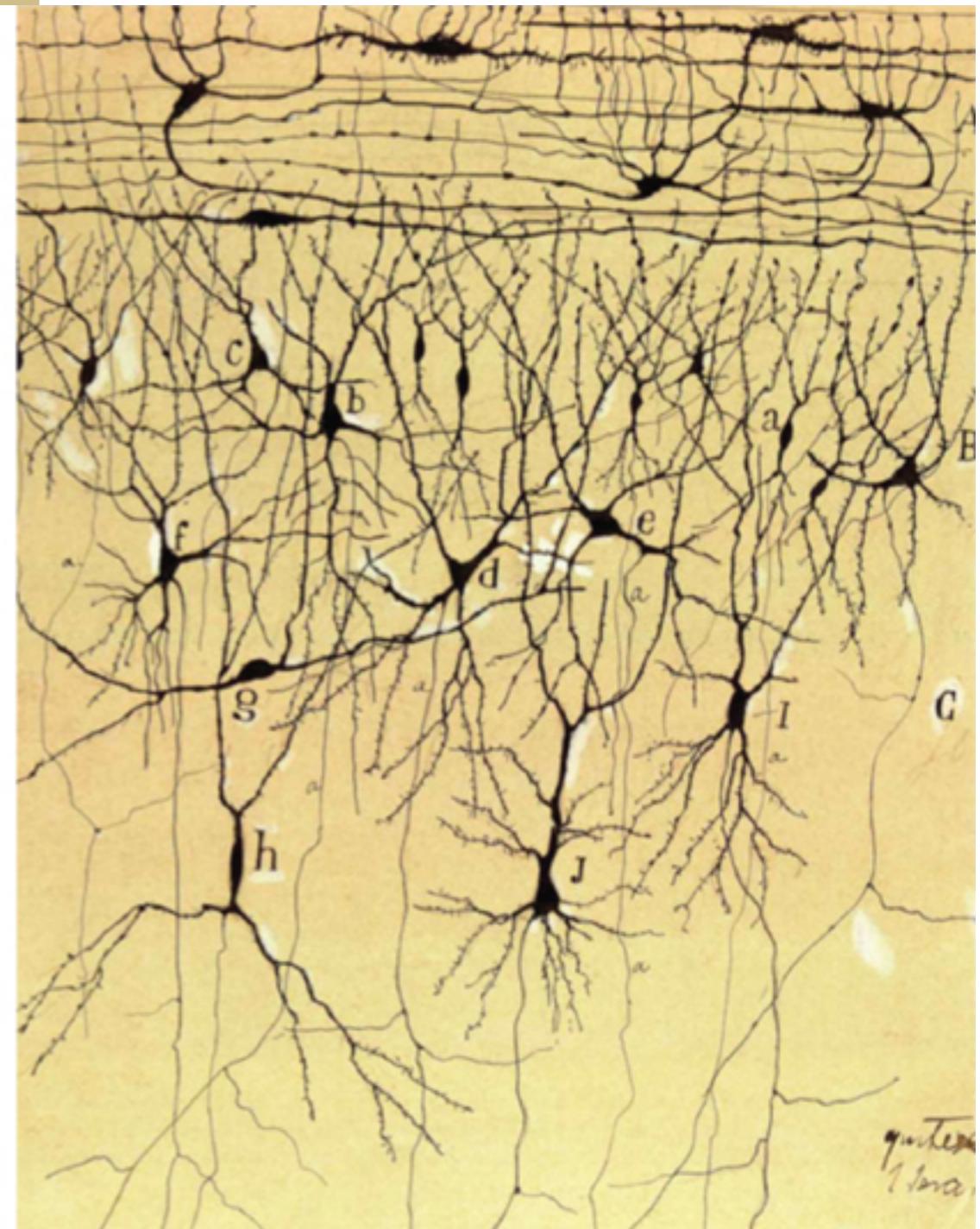
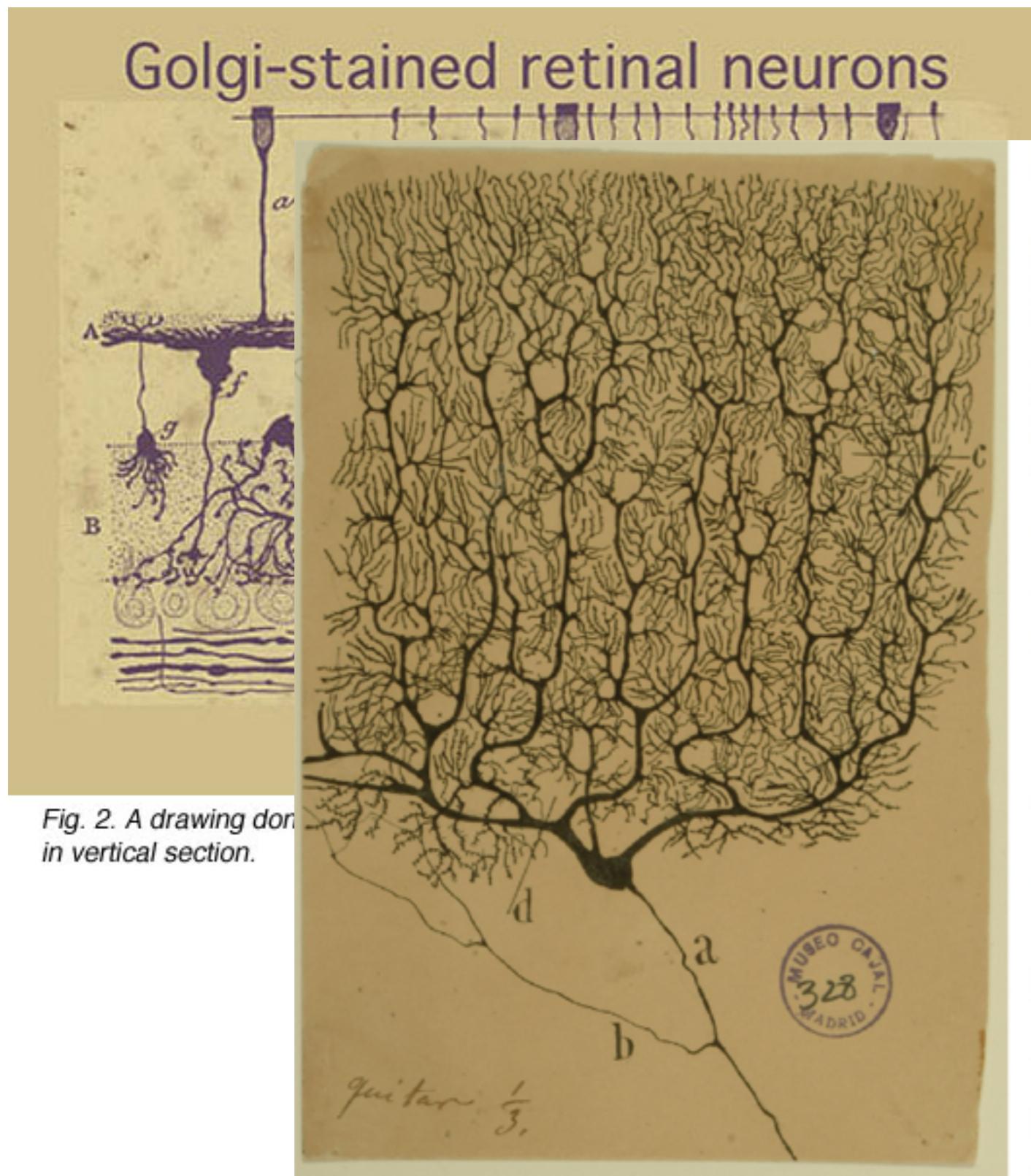
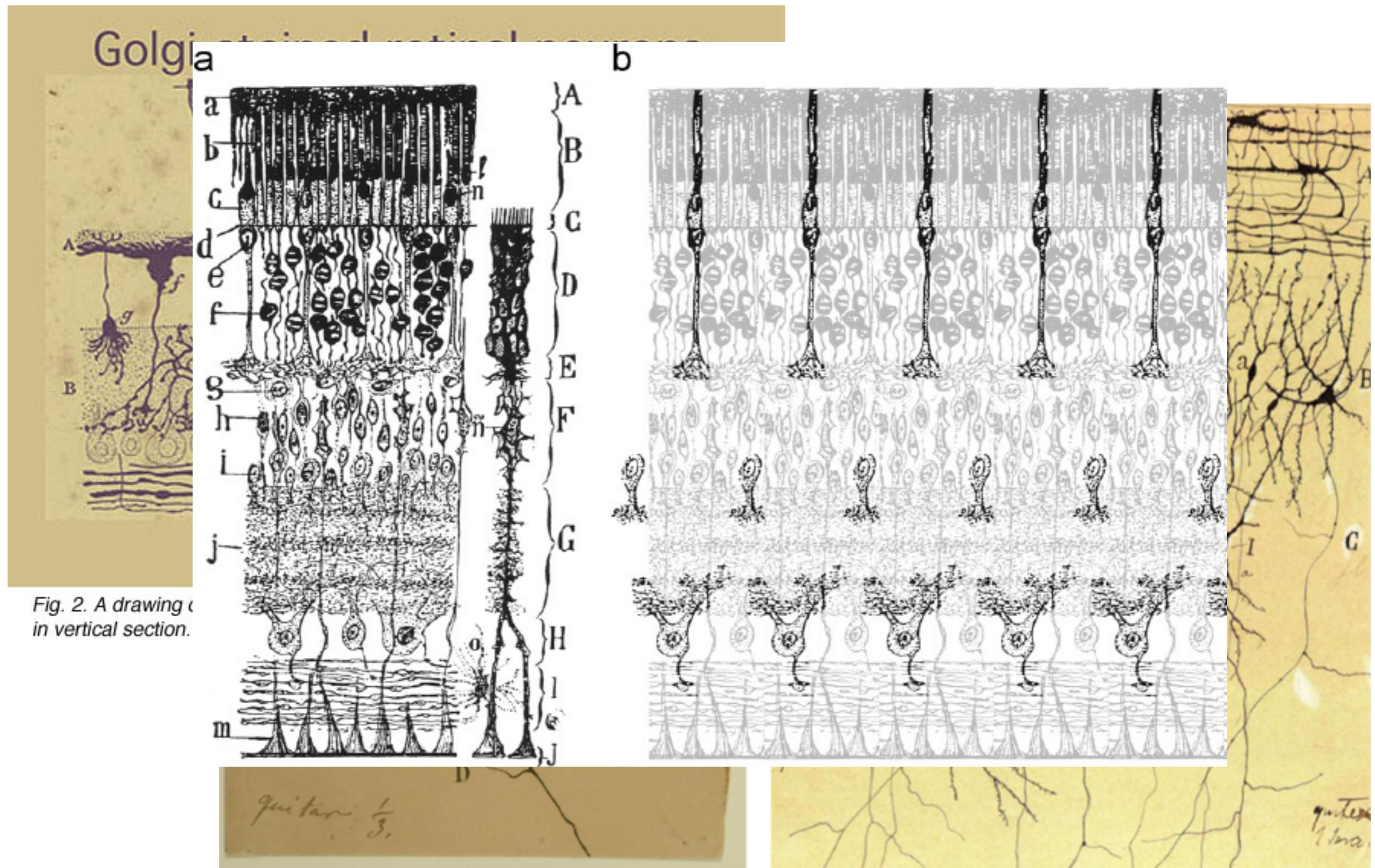


Fig. 2. A drawing done by Cajal to show some of the neurons of the retina in vertical section.

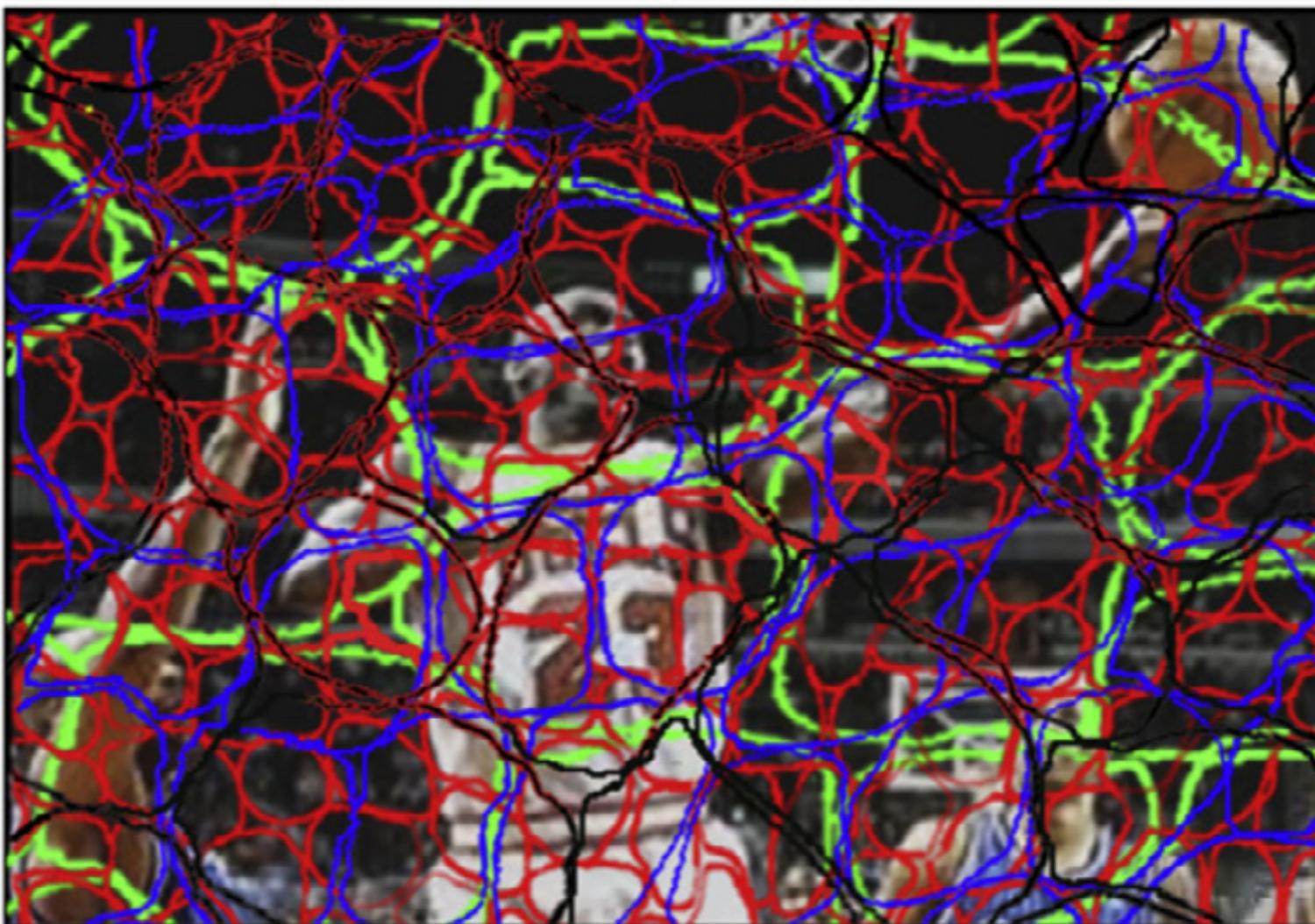
Origins in the Retina



Origins in the Retina



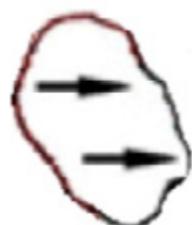
Origins in the Retina



(a)



(b)



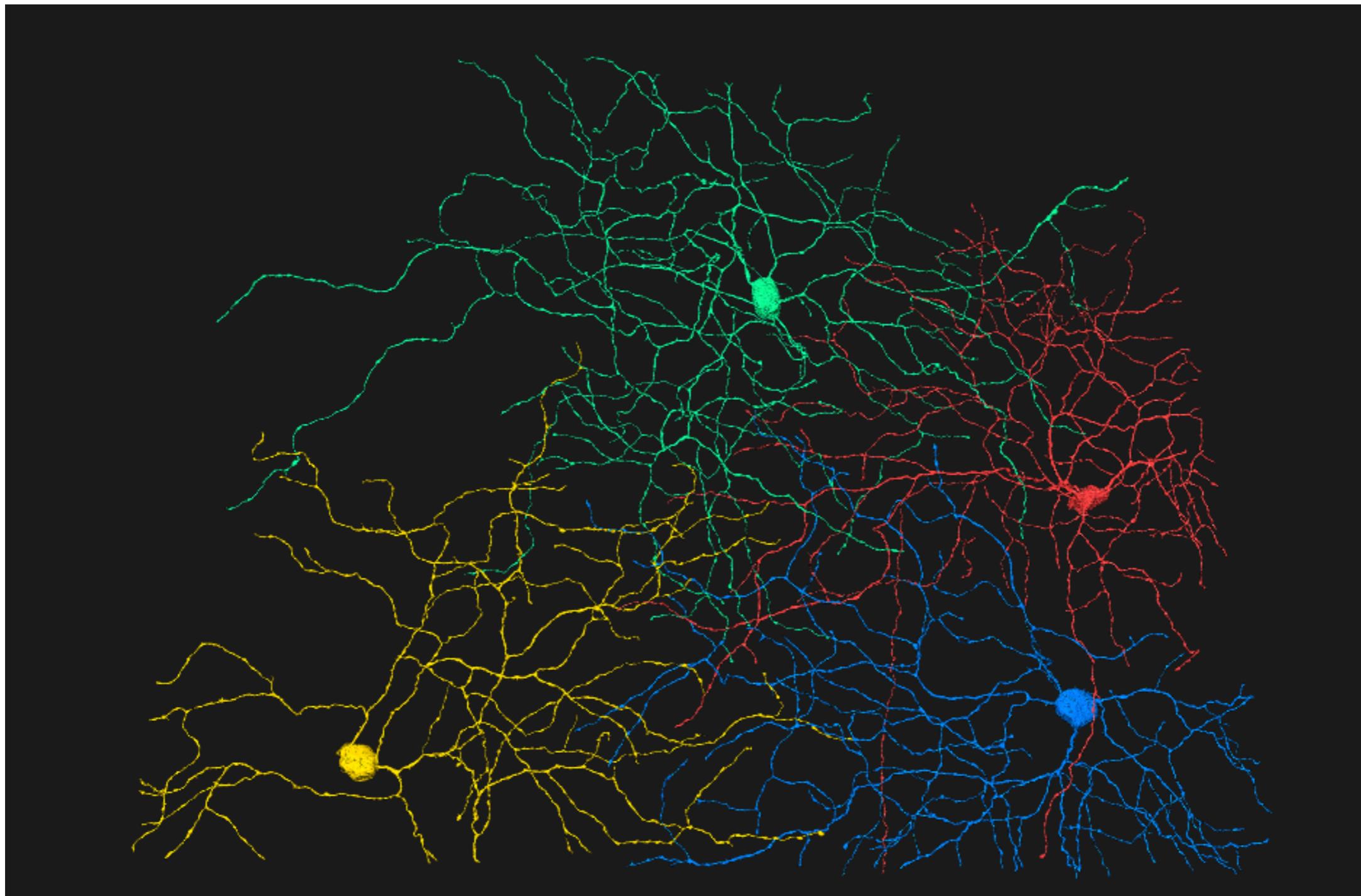
(c)



(d)

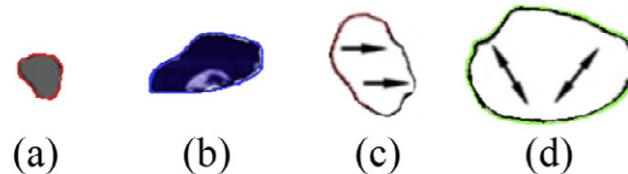
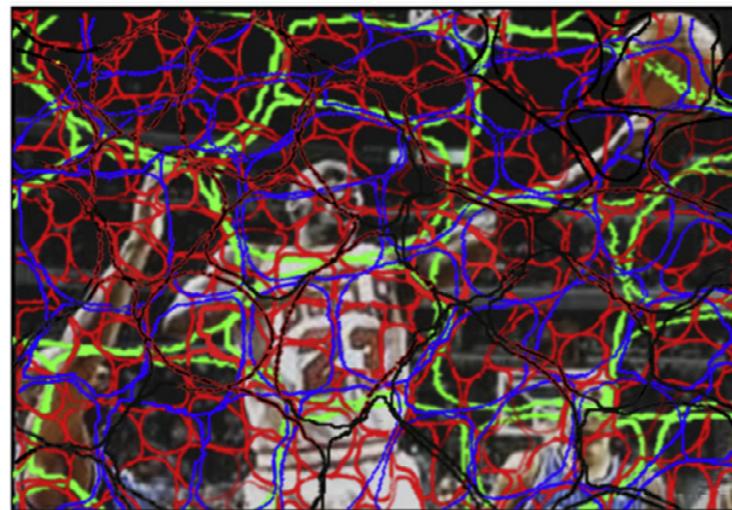
Masland (2012)

Origins in the Retina

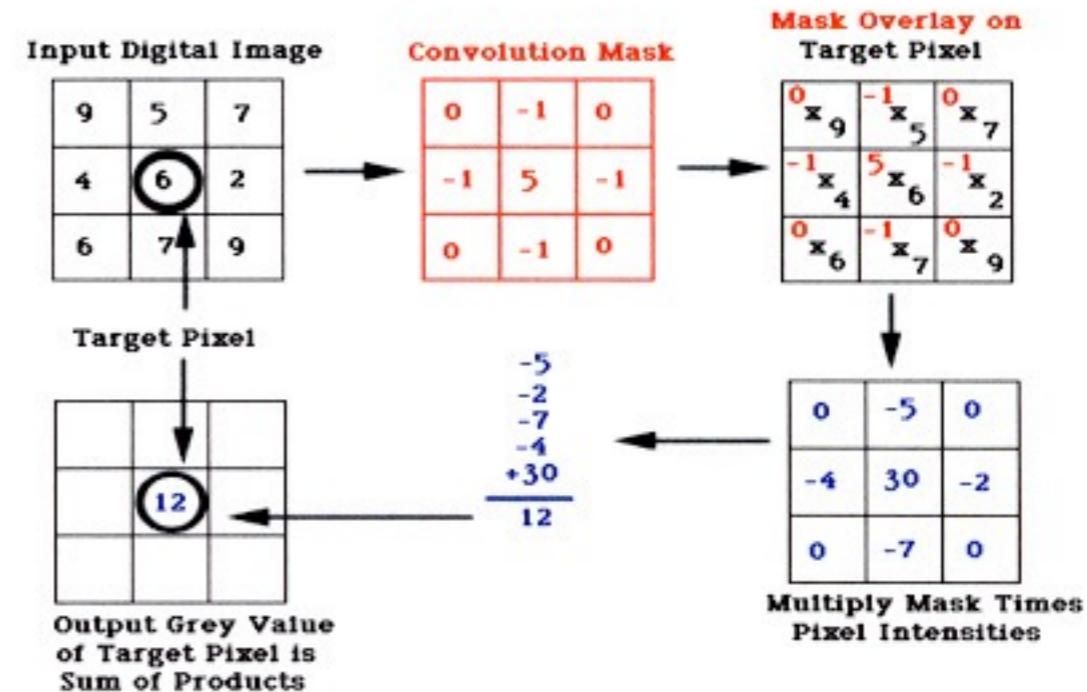


<http://museum.eyewire.org>

Origins in the Retina



SPATIAL CONVOLUTION

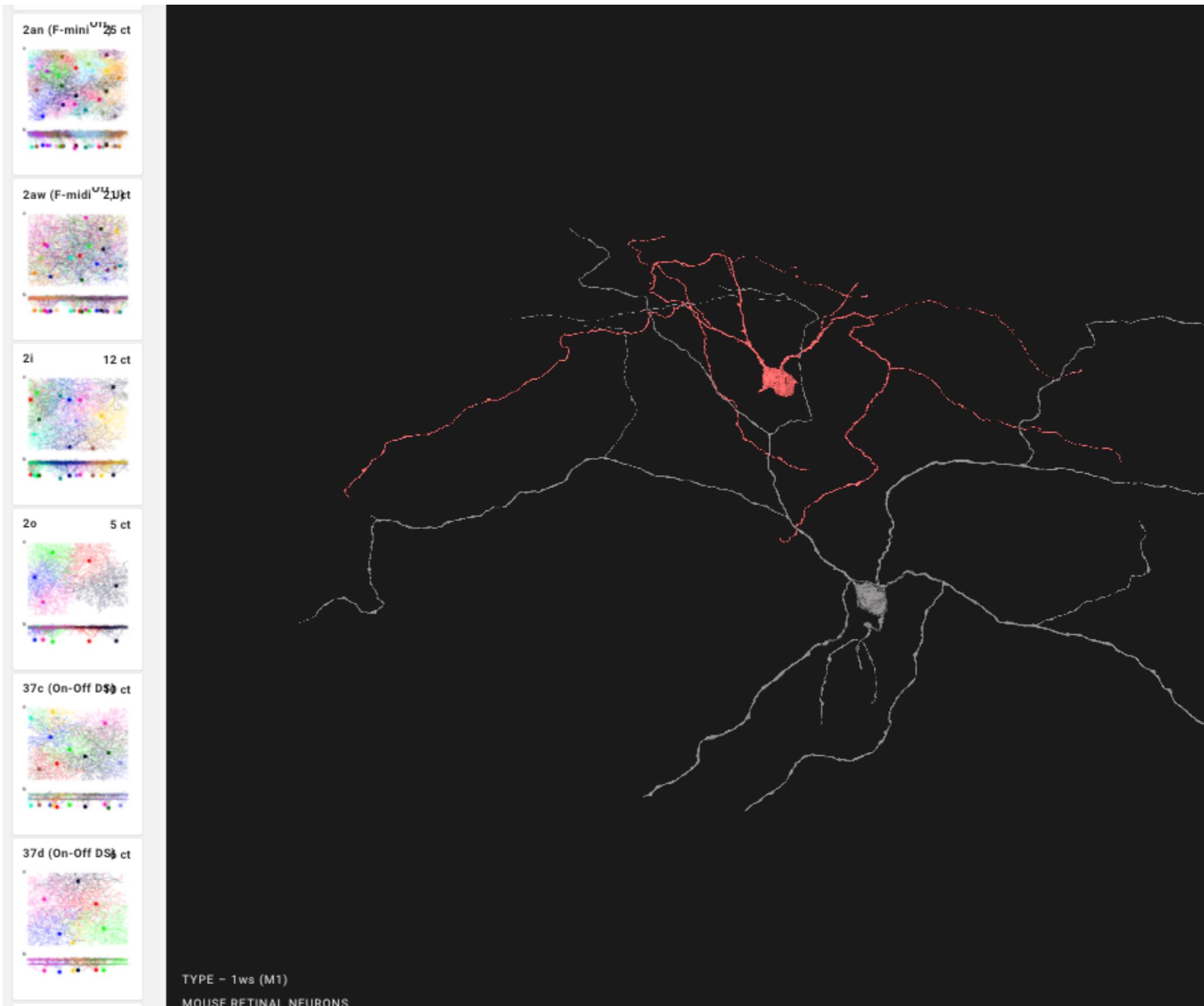


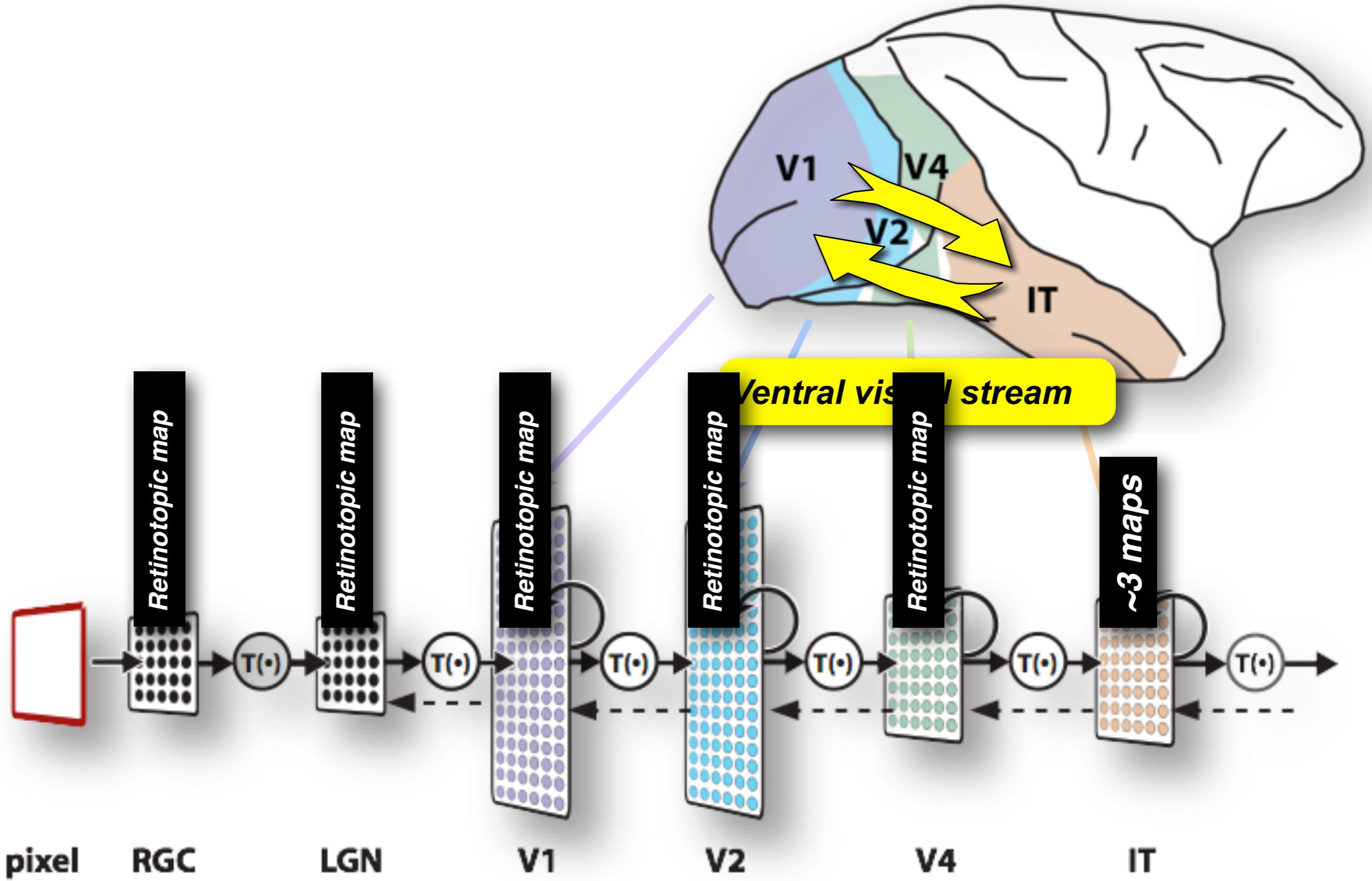
1. The convolution mask is overlaid on the original image so that the center pixel of the mask is matched with a pixel location on the image (Target Pixel- to be convolved).
2. Each pixel value in the original image is multiplied by the corresponding value in the overlying mask..
3. The grey value of the target pixel is replaced by the sum of all the products in the second step.
4. The operation is repeated for each pixel in the original image (the mask scans the entire image) and each pixel is replaced by the weighted average of its 3×3 neighbors.

Origins in the Retina

*cell types
like different
filters in a
filterbanks*

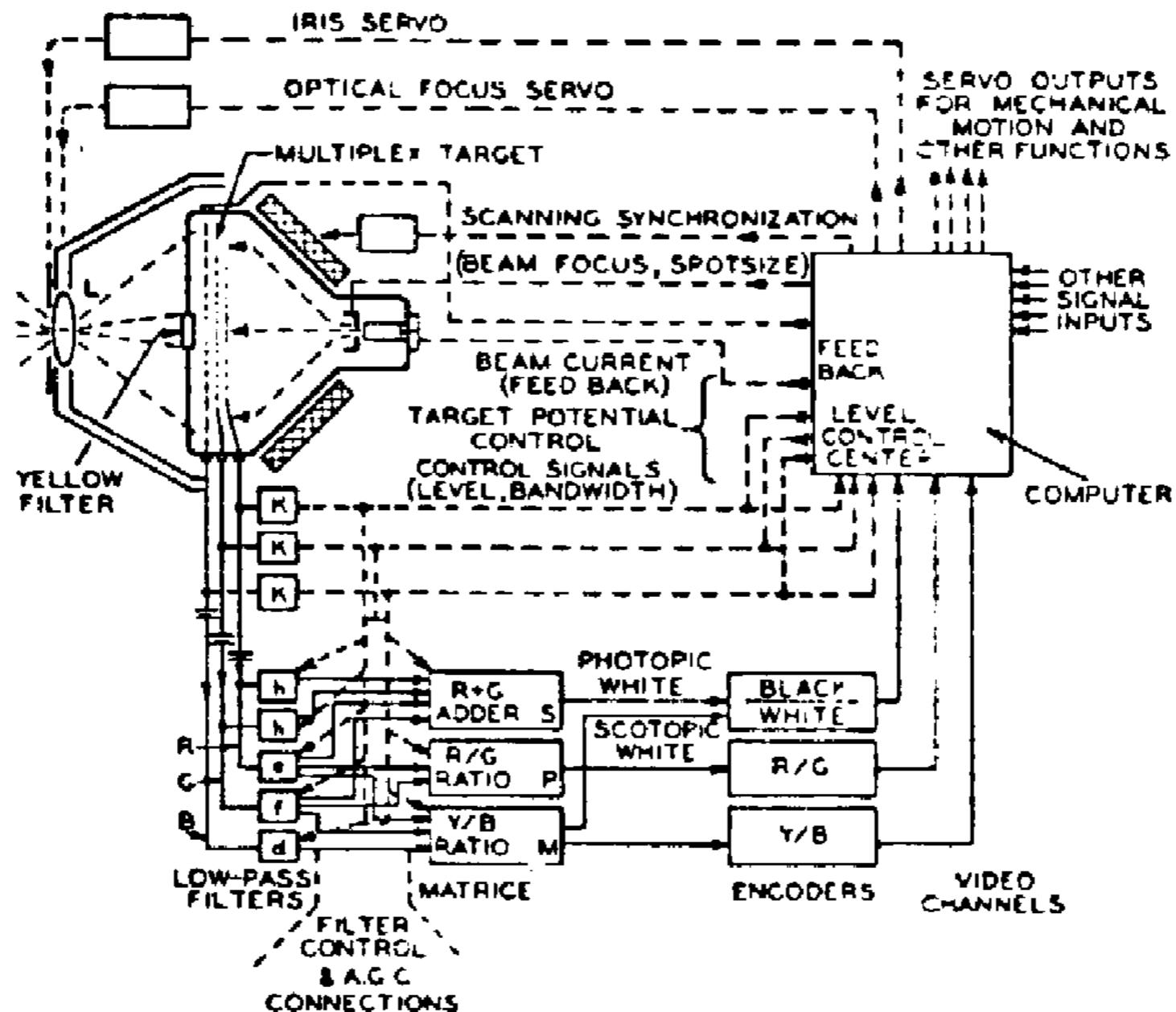
*but which
filters?*





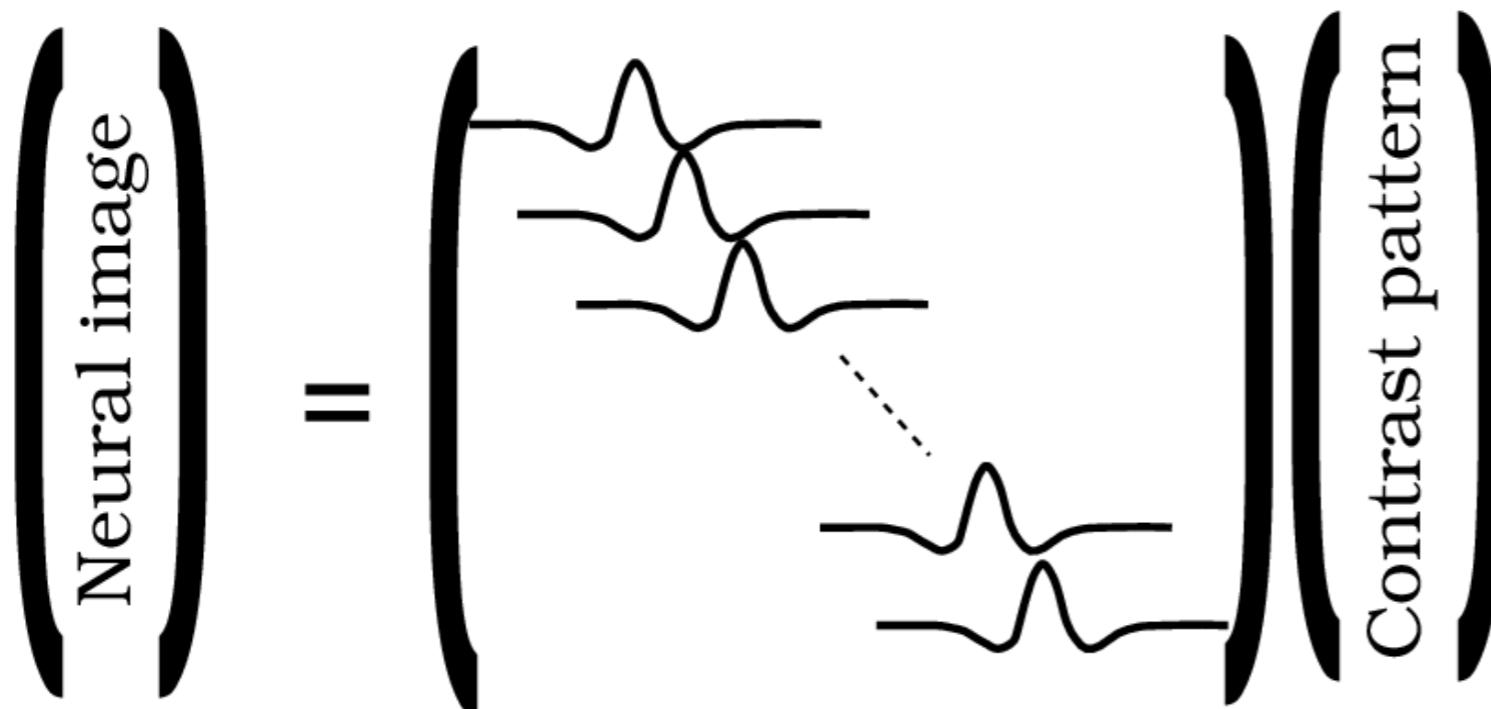
Origins in the Retina

characterizing a *transfer function* ...



Origins in the Retina

characterizing a *transfer function* . . .



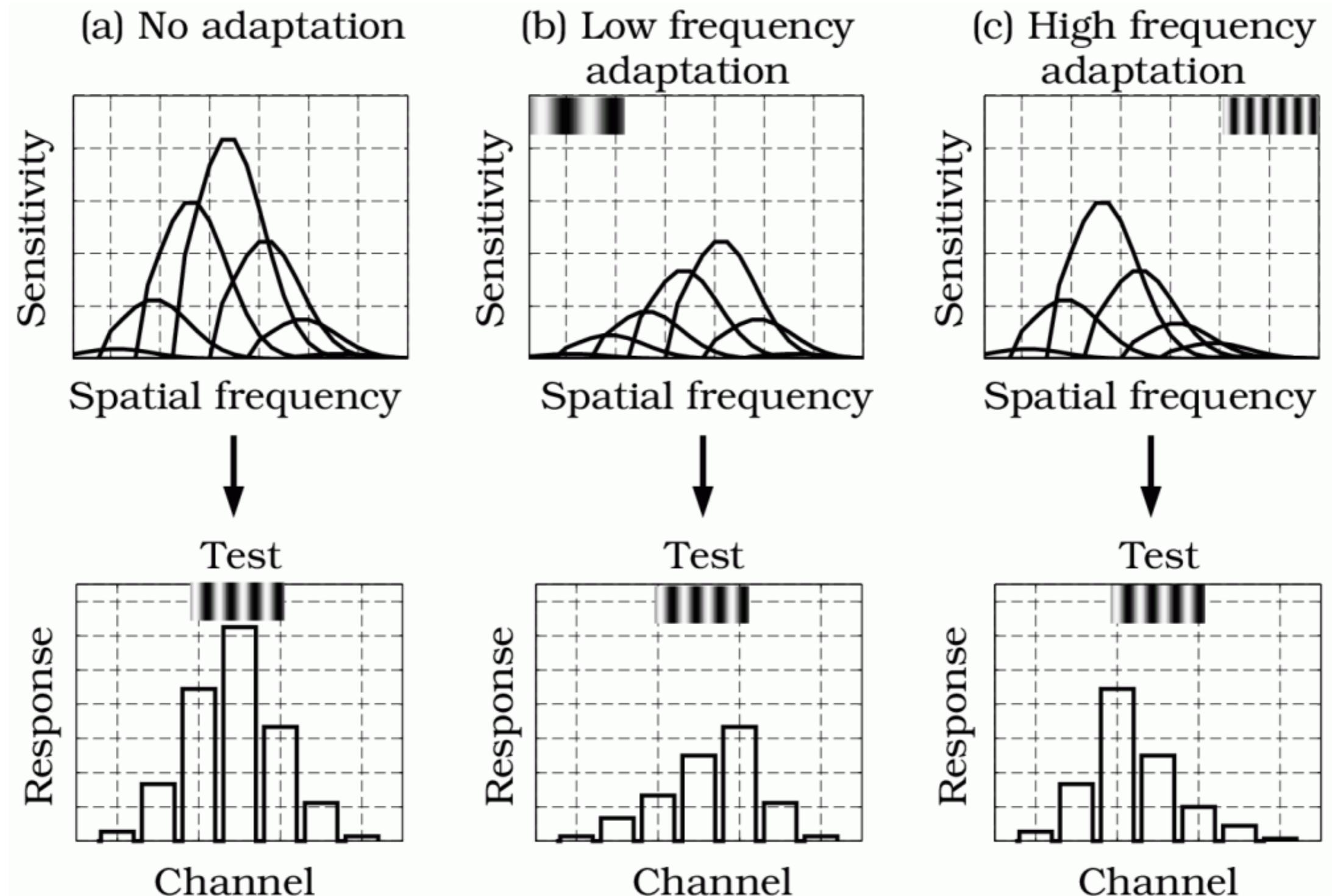
Christina Enroth-Cugell



John Robson

. . . and thus, presumably, doing linear systems (e.g fourier) analysis

Origins in the Retina



from Wandell 1996

Origins in the Retina

THE CONTRAST SENSITIVITY OF RETINAL GANGLION CELLS OF THE CAT

By CHRISTINA ENROTH-CUGELL AND J. G. ROBSON*

From the Biomedical Engineering Center, Technological Institute, Northwestern University, Evanston, Illinois, U.S.A.† and the Department of Physiology, Northwestern University Medical School, Chicago, U.S.A.

(Received 19 April 1966)



Christina Enroth-Cugell

1. Spatial summation within cat retinal receptive fields was studied by recording ... responses of ganglion cells to grating patterns
2. Summation over the receptive fields of some cells (X-cells) was found to be **approximately linear**, while for other cells (Y-cells) summation was **very non-linear**.
3. The mean discharge frequency of Y-cells ... was greatly increased when grating patterns drifted across their receptive fields.
4. In X-cells ... it was found that the contrast sensitivity function, **could be satisfactorily described by the difference of two Gaussian functions.**
5. This finding supports the hypothesis that the sensitivities of the antagonistic centre and surround summing regions of ganglion cell receptive fields fall off as Gaussian functions of the distance from the field centre.



John Robson

Old-School CV: Marr-Hildreth's "Laplacian of Gaussians"

Proc. R. Soc. Lond. B **207**, 187-217 (1980)

Printed in Great Britain

Theory of edge detection

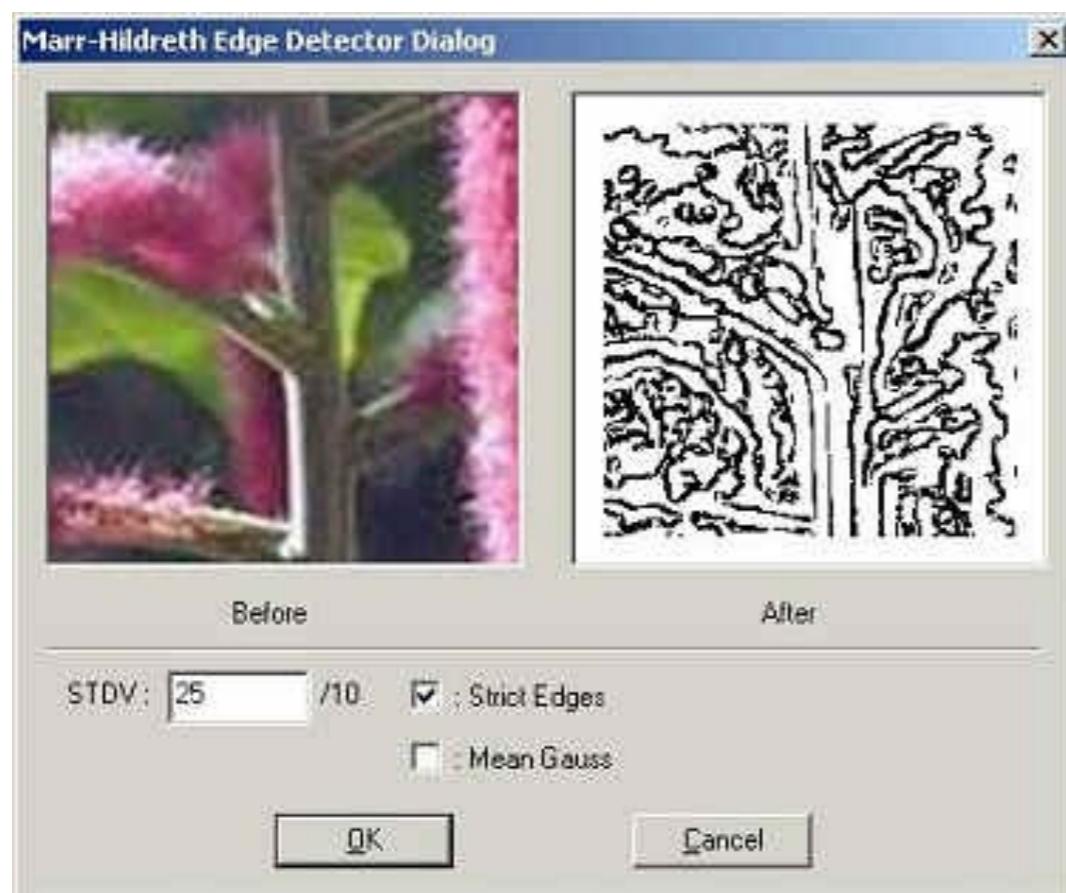
BY D. MARR AND E. HILDRETH

*M.I.T. Psychology Department and Artificial Intelligence Laboratory,
79 Amherst Street, Cambridge, Massachusetts 02139, U.S.A.*

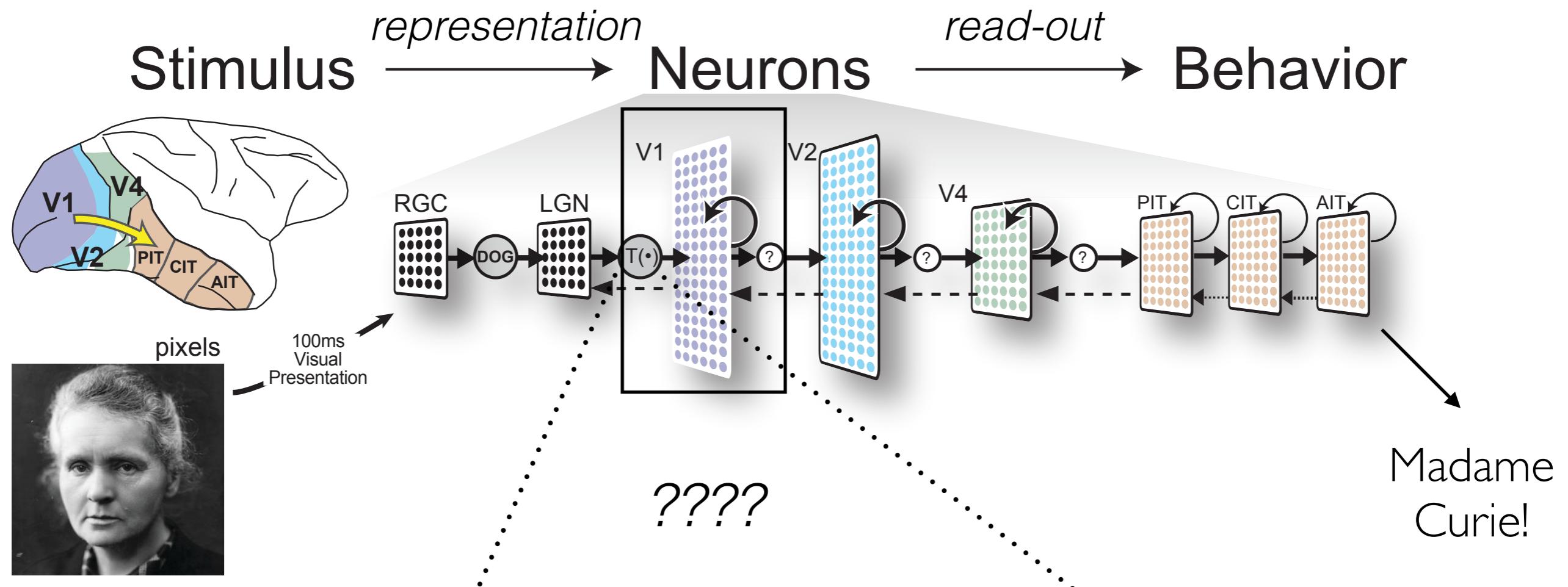
(Communicated by S. Brenner, F.R.S. – Received 22 February 1979)

$$\vec{\nabla}^2 G(x, y) * Im(x, y)$$

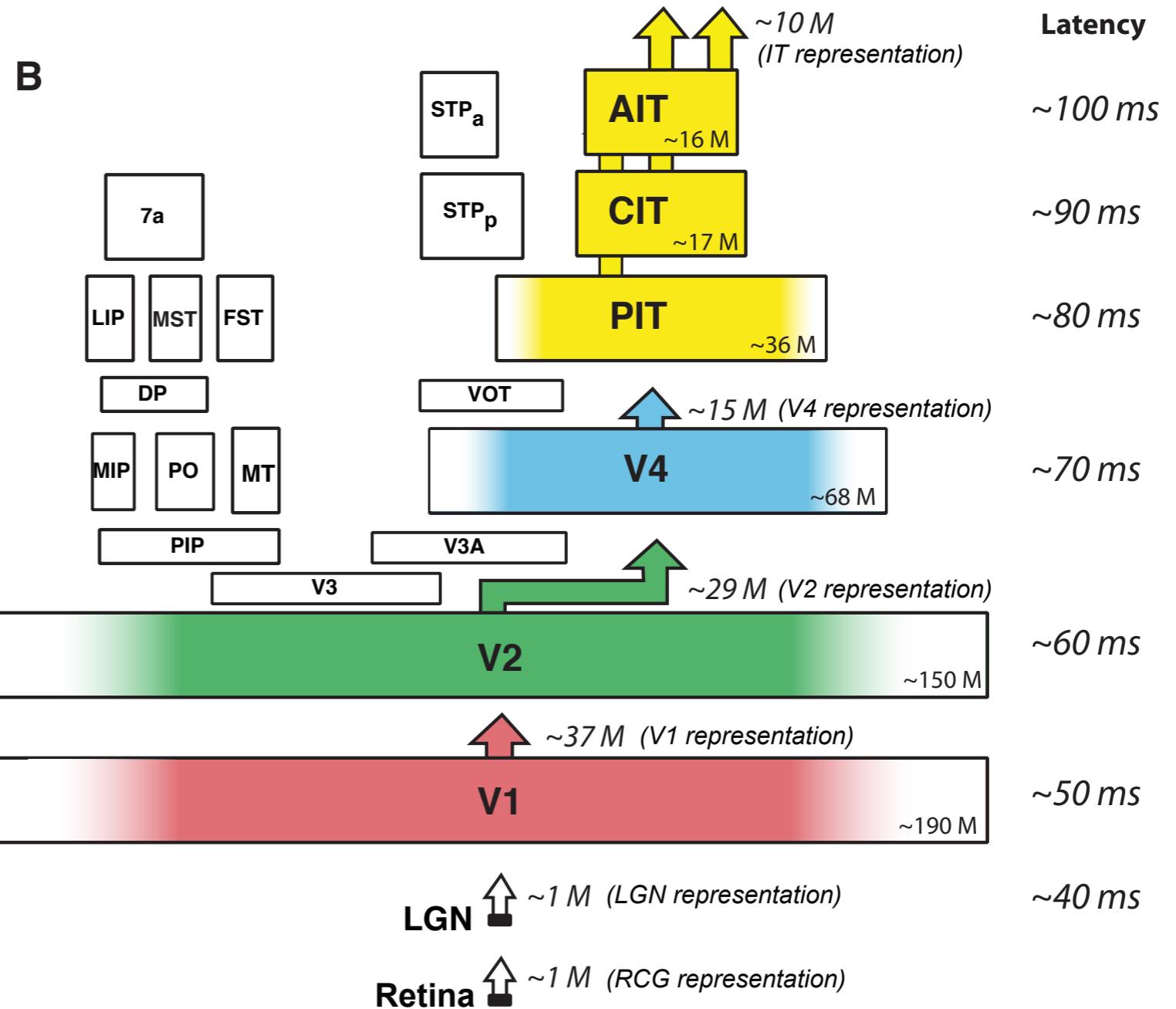
$\sim DoG$



Gabors in V1



You are here.



106

J. Physiol. (1962), **160**, pp. 106-154

With 2 plates and 20 text-figures

Printed in Great Britain

**RECEPTIVE FIELDS, BINOCULAR INTERACTION
AND FUNCTIONAL ARCHITECTURE IN
THE CAT'S VISUAL CORTEX**

BY D. H. HUBEL AND T. N. WIESEL

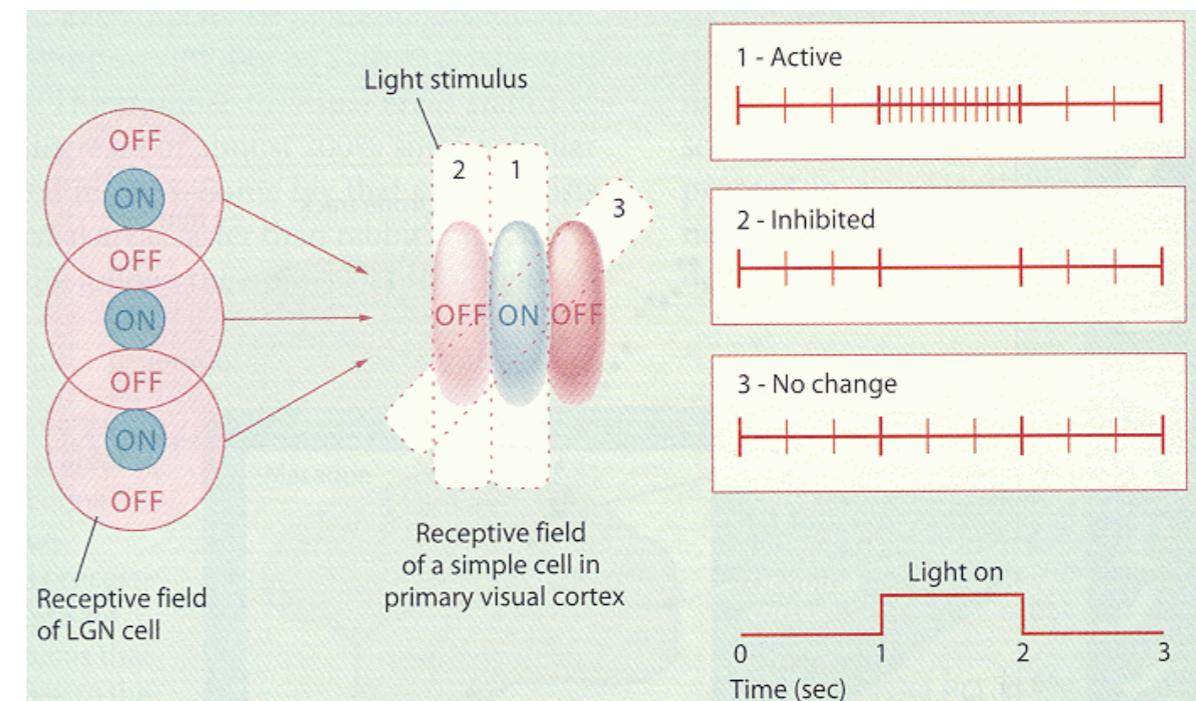
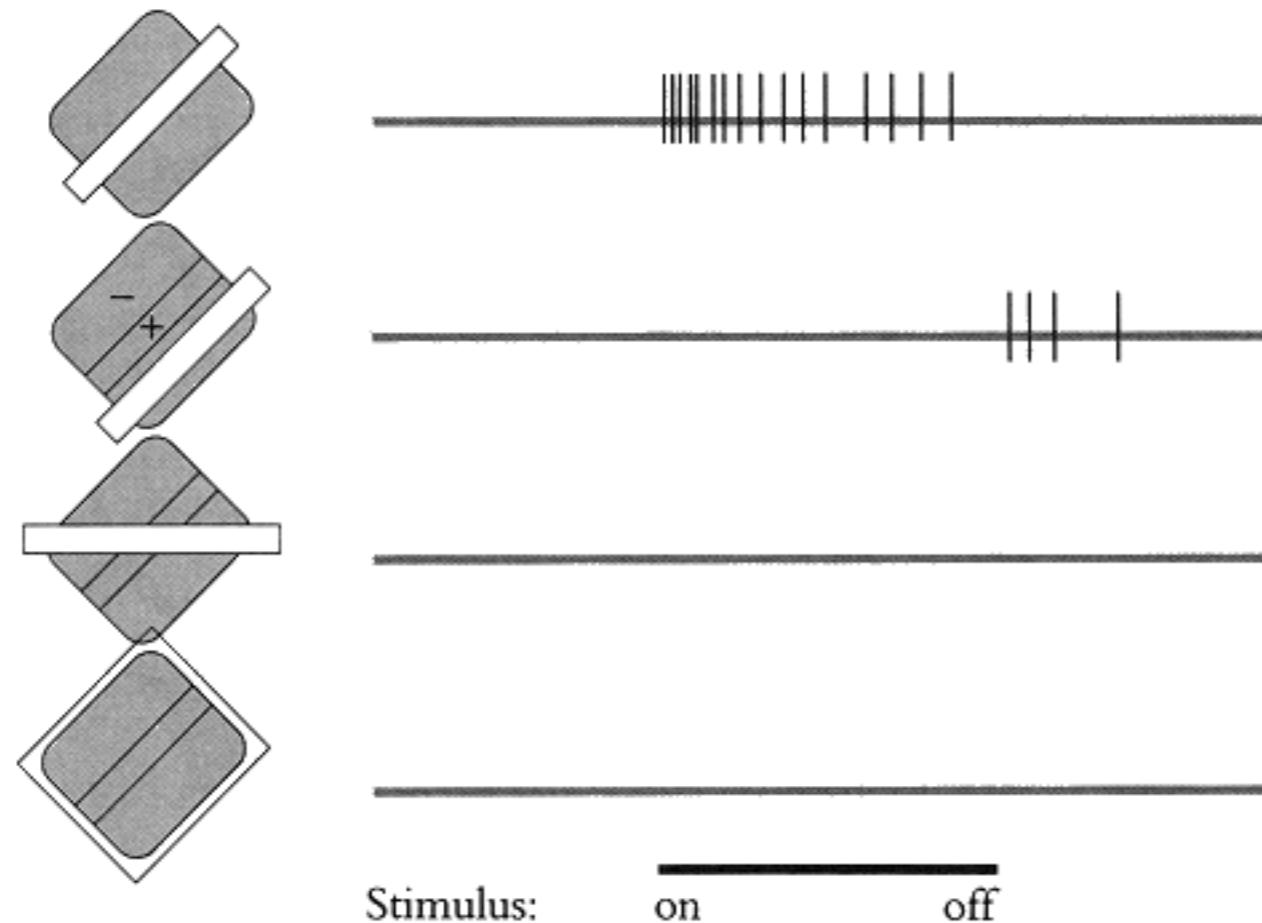
*From the Neurophysiology Laboratory, Department of Pharmacology
Harvard Medical School, Boston, Massachusetts, U.S.A.*

(Received 31 July 1961)

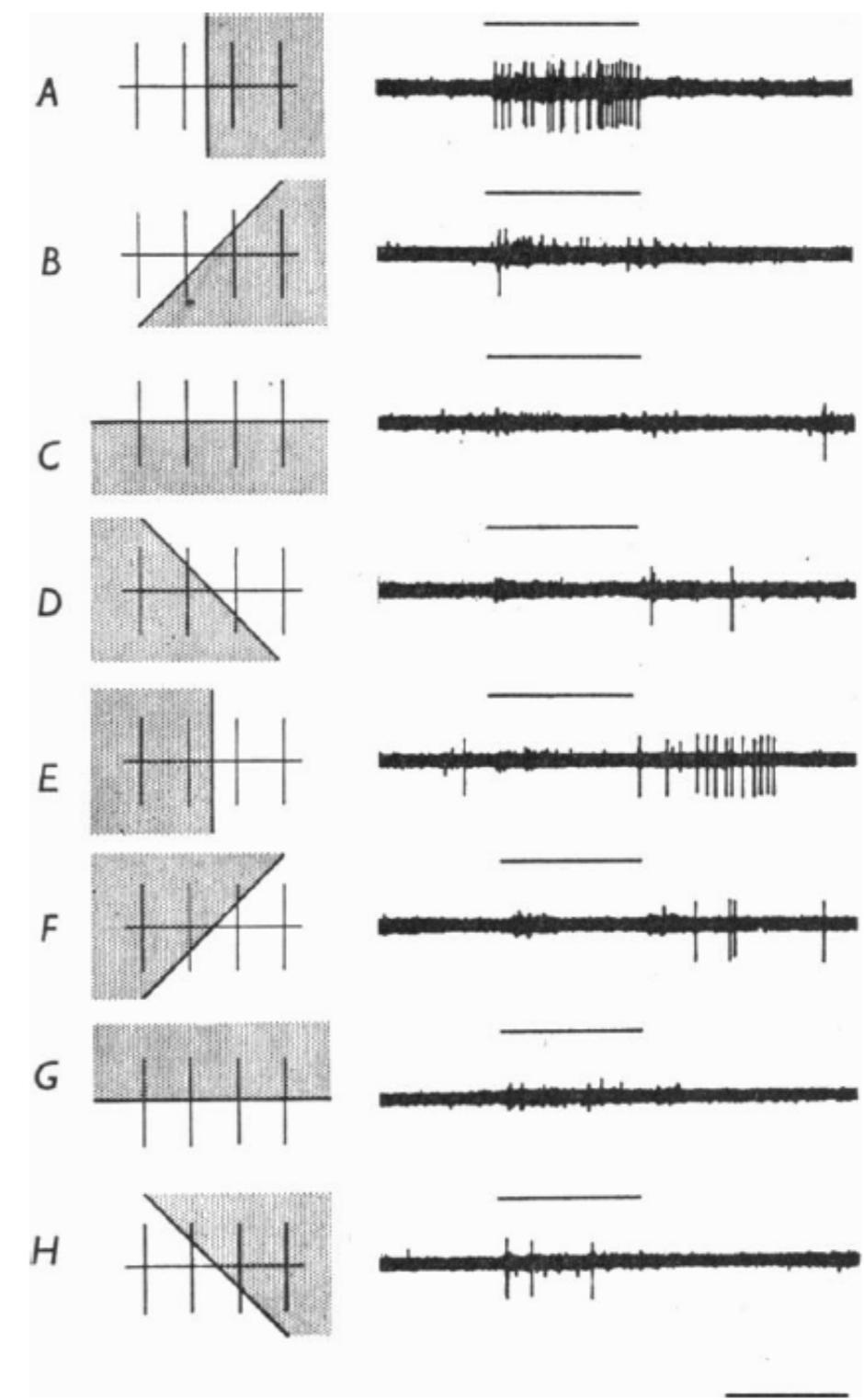
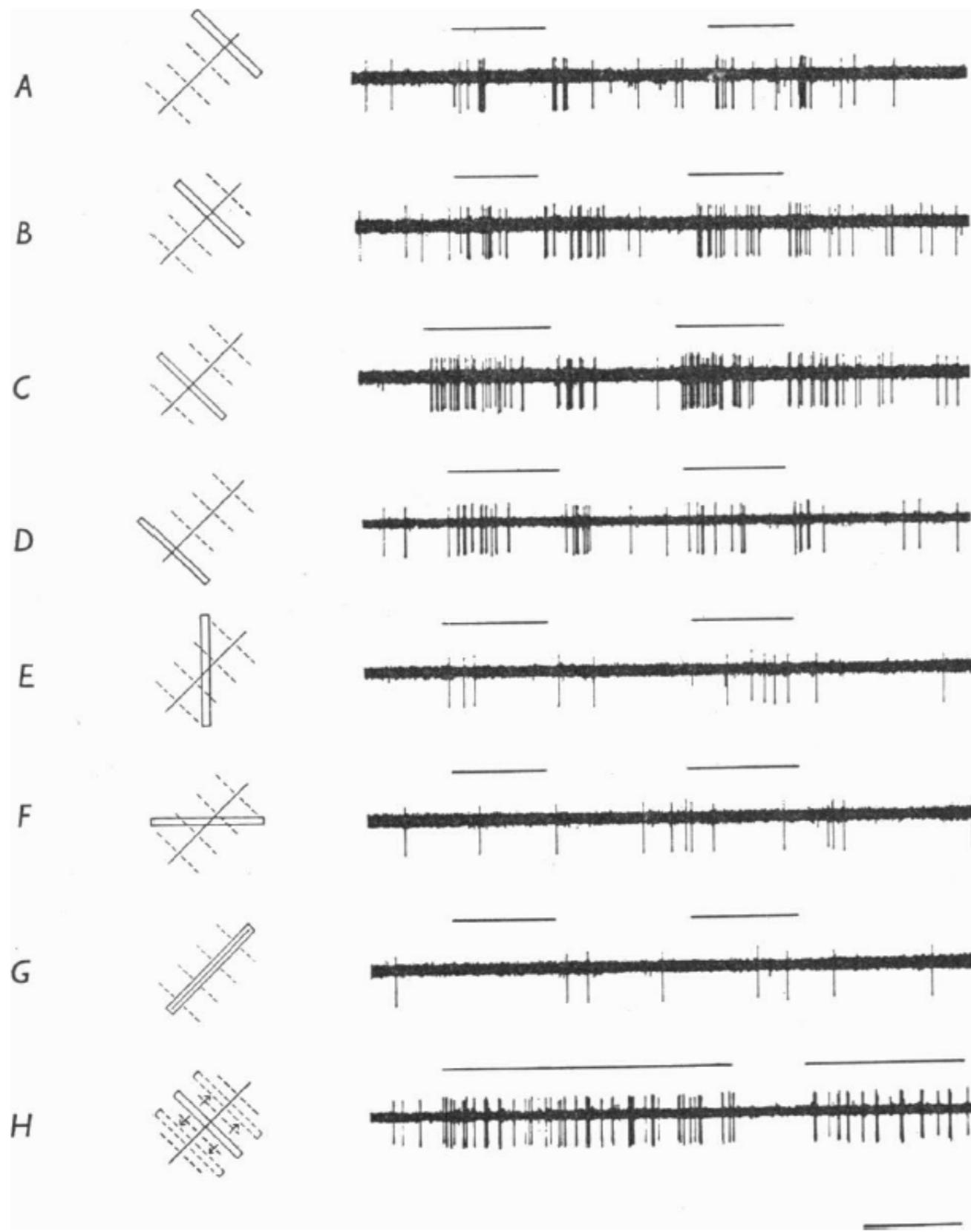
PART I

**ORGANIZATION OF RECEPTIVE FIELDS IN CAT'S
VISUAL CORTEX: PROPERTIES OF 'SIMPLE'
AND 'COMPLEX' FIELDS**

Gabors in VI

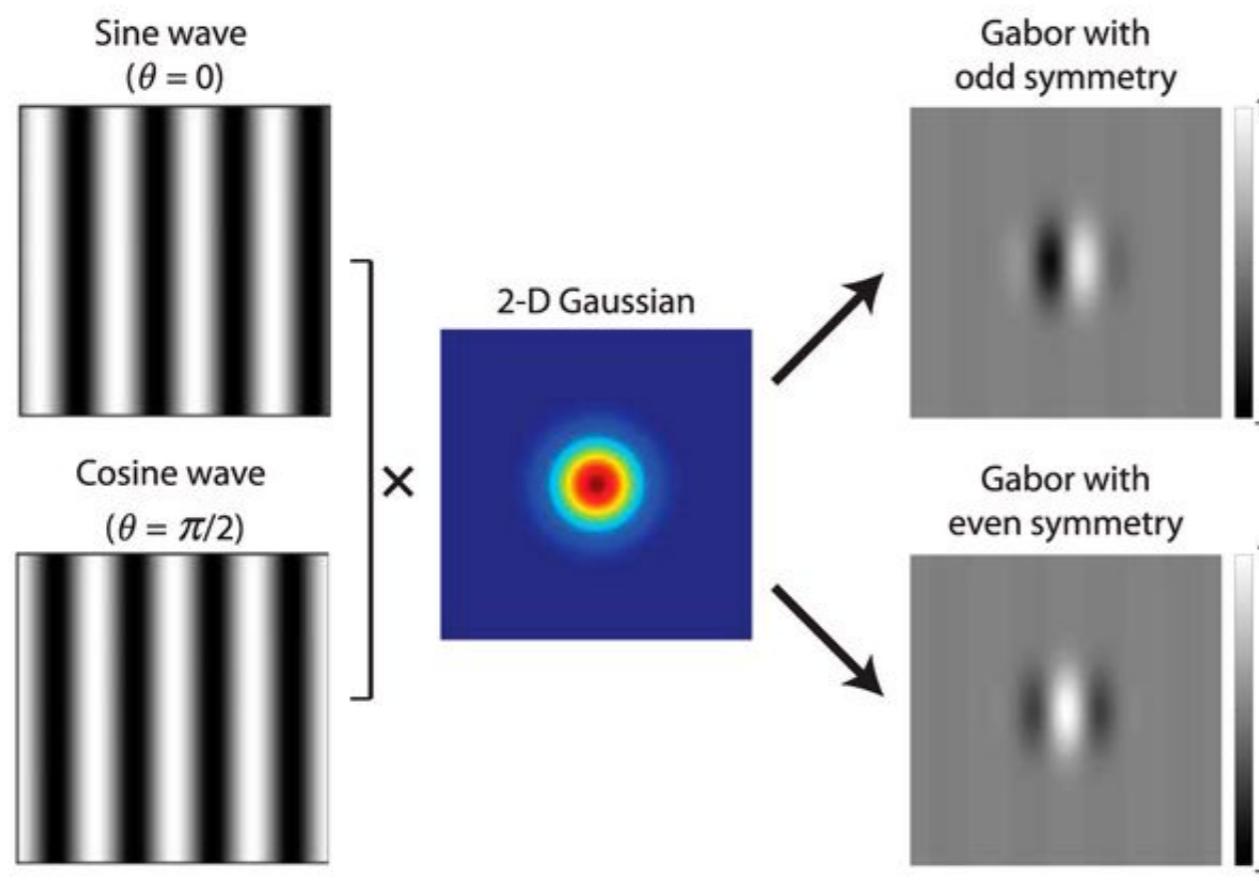


Gabors in VI

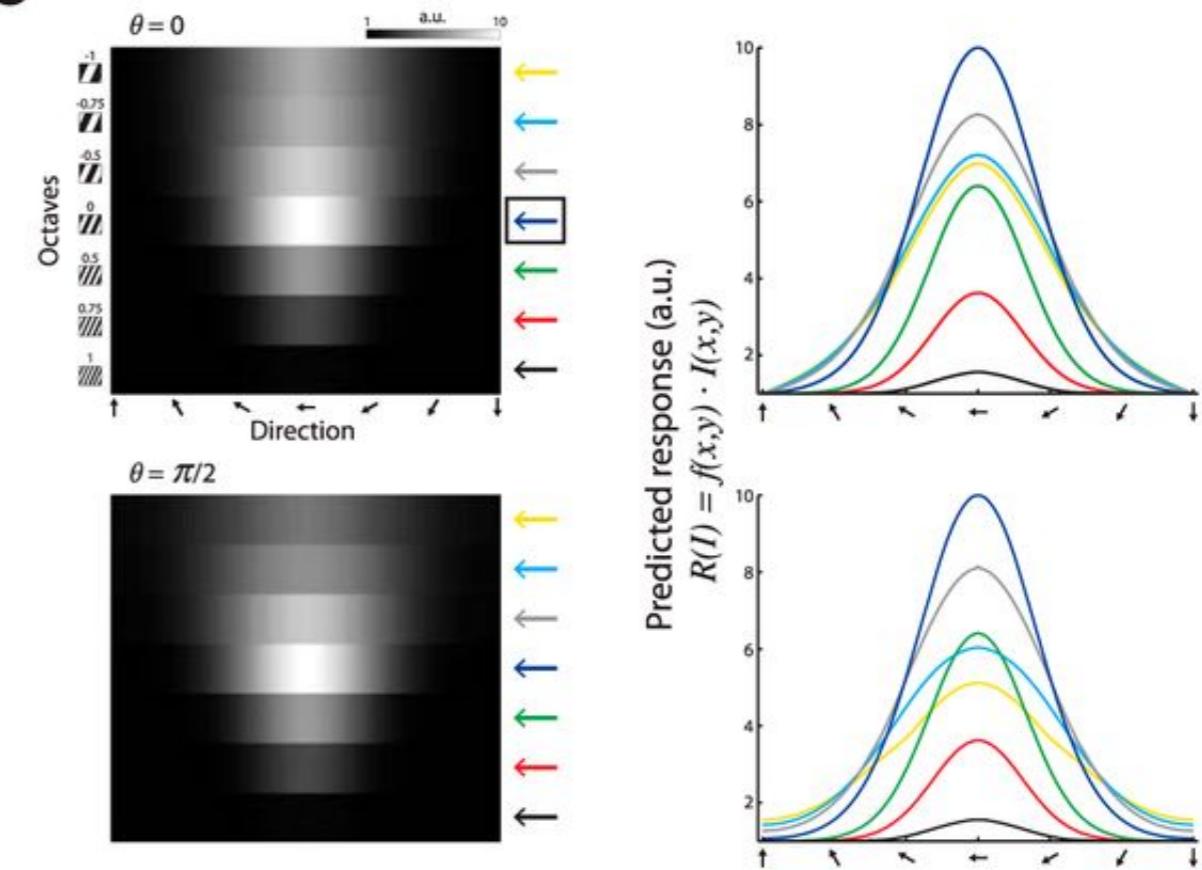


Orientation Tuning Curves

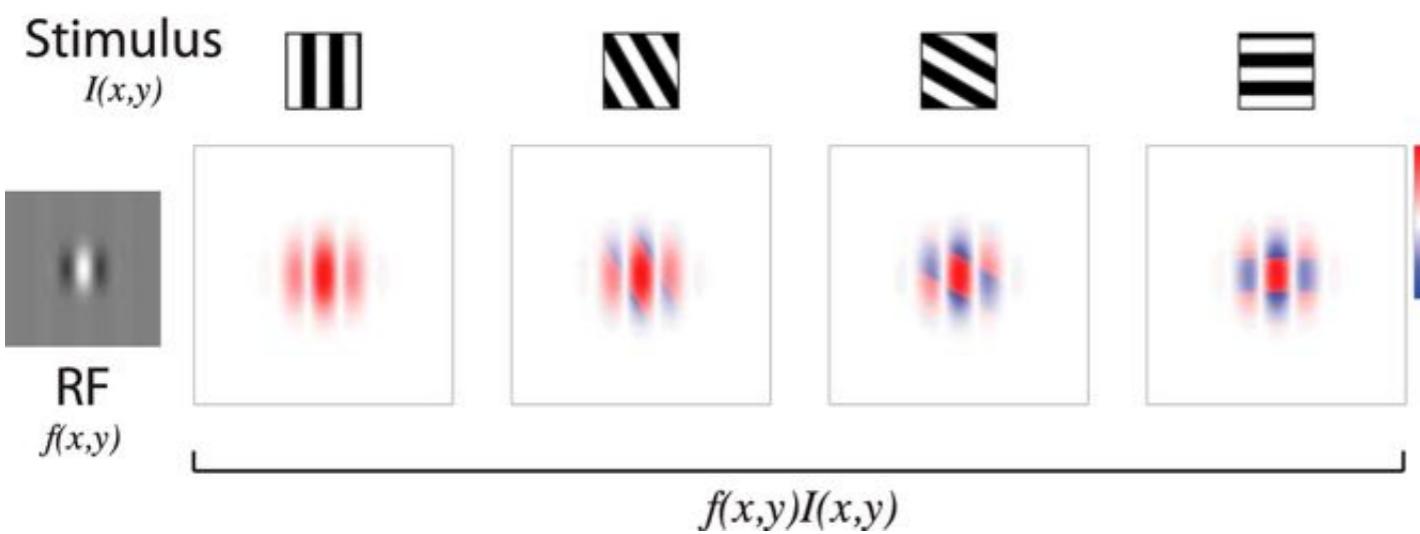
A



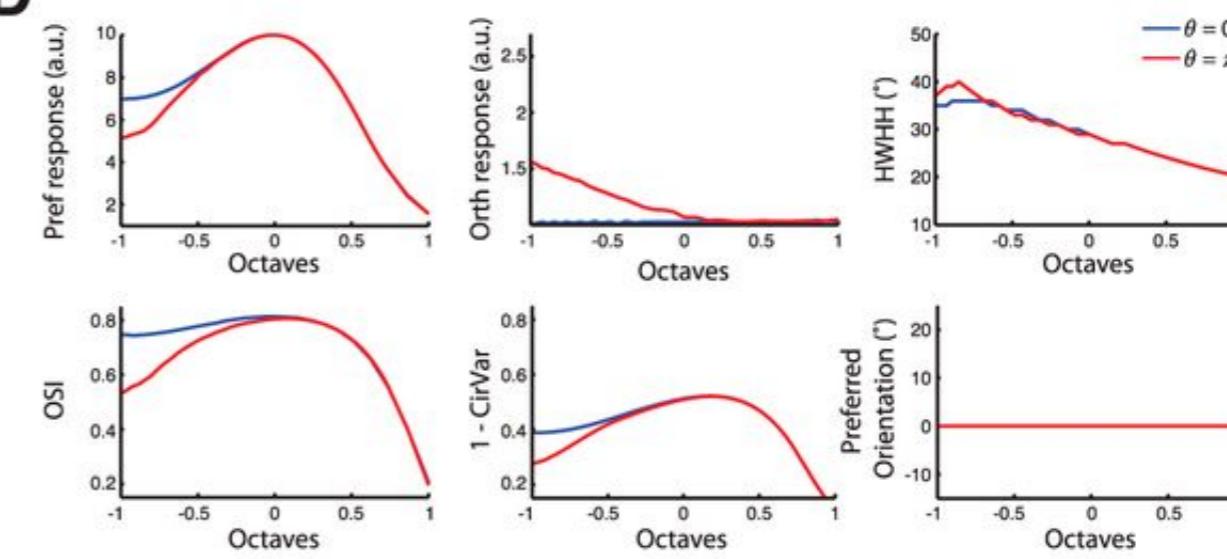
C



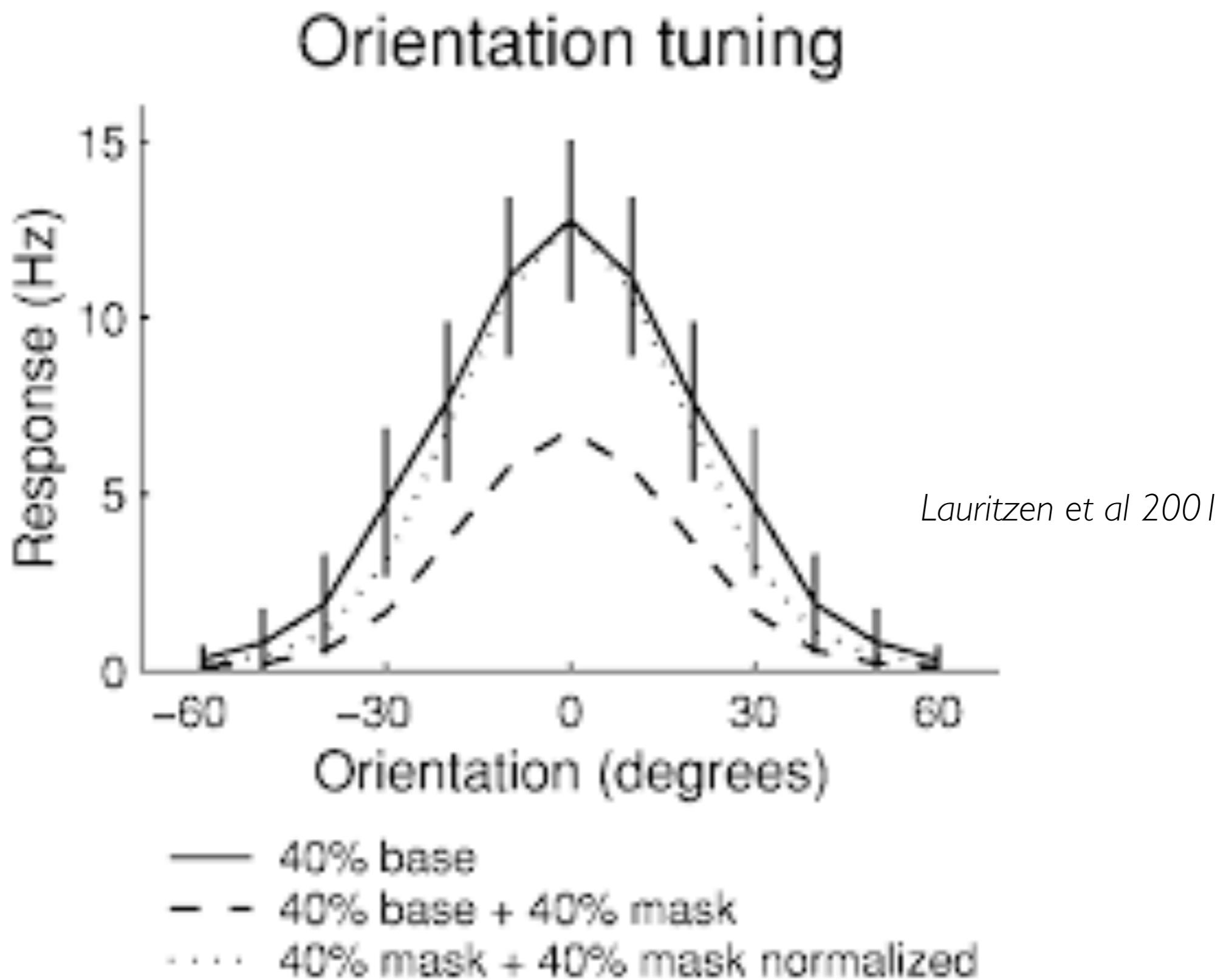
B



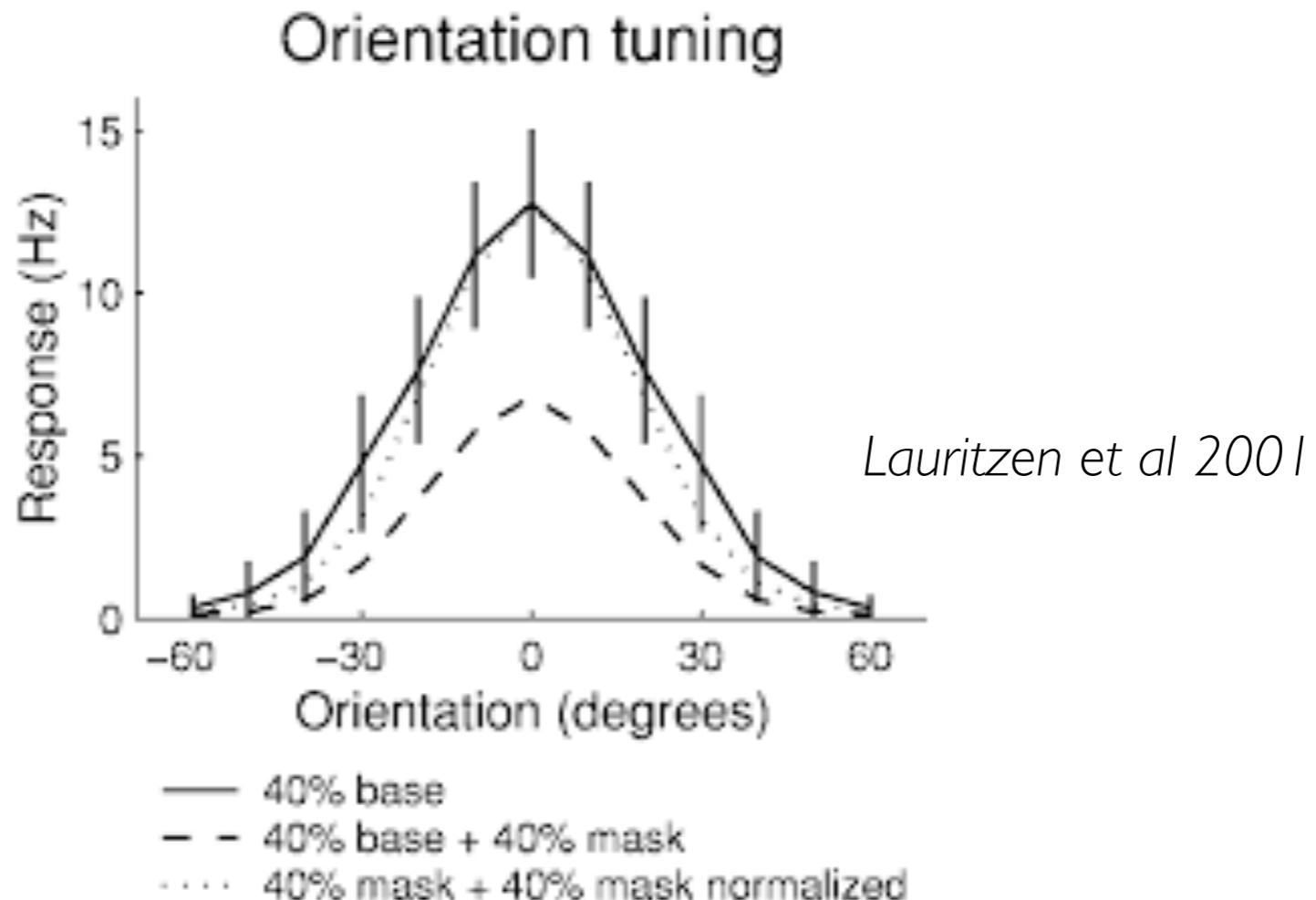
D



Orientation Tuning Curves



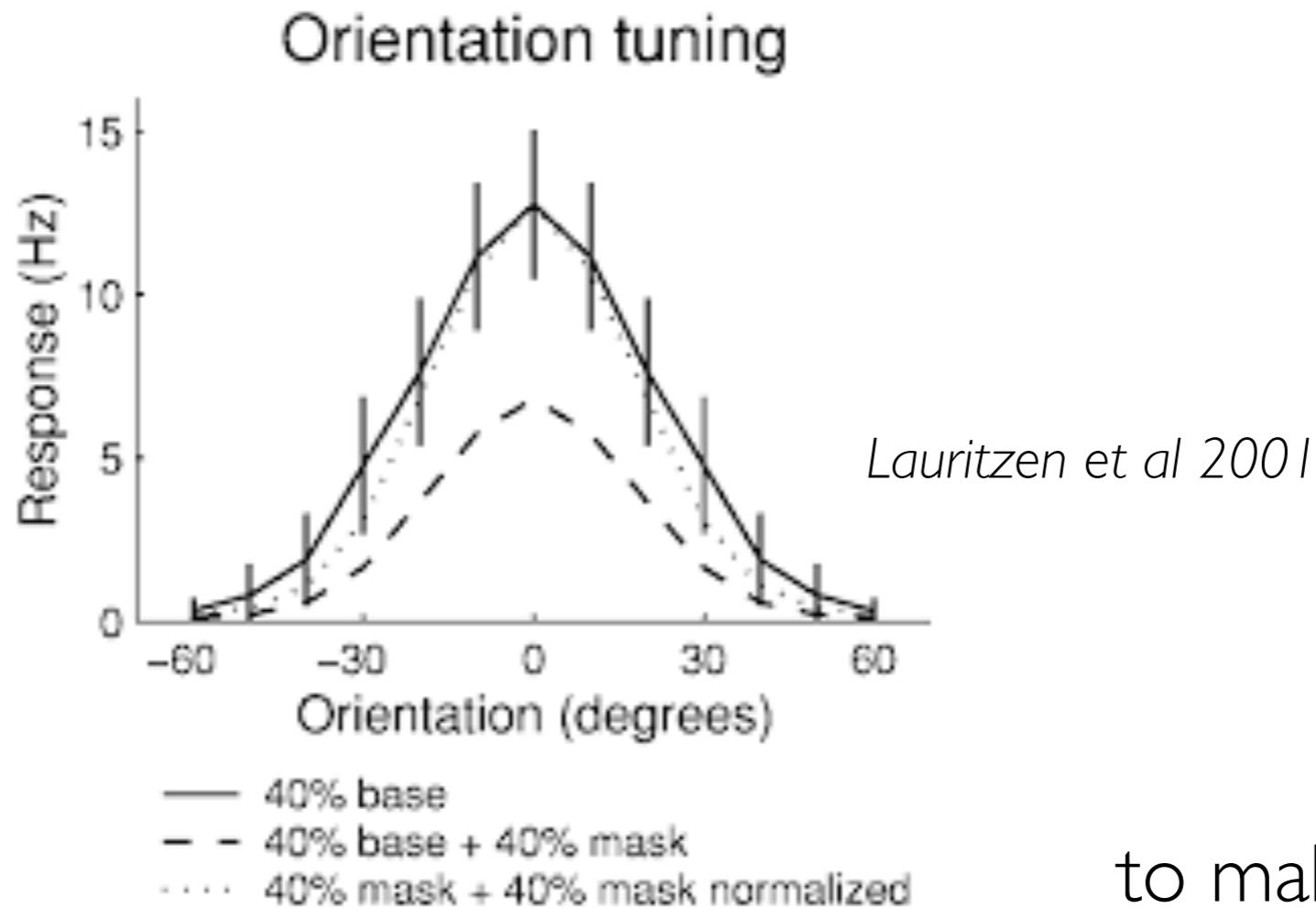
Orientation Tuning Curves



Circular Variance = $1 - \frac{\sum_k r_k e^{2i\theta_k}}{\sum_k r_k}$

r_k = neuron \mathbf{r} 's response to stimulus with pure orientation \mathbf{k}

Orientation Tuning Curves



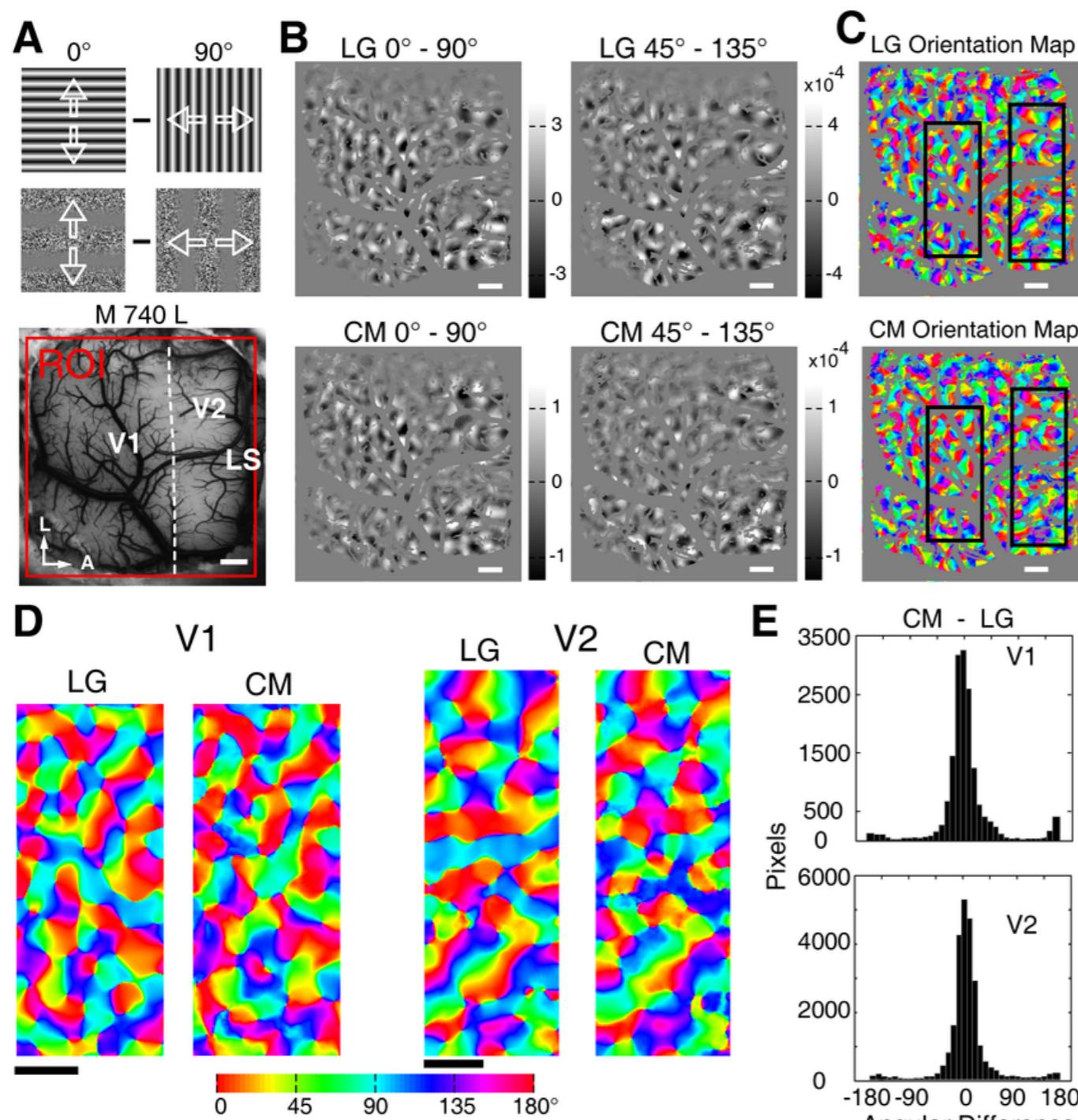
to make it “circular”

$$\text{Circular Variance} = 1 - \frac{\sum_k r_k e^{2i\theta_k}}{\sum_k r_k}$$

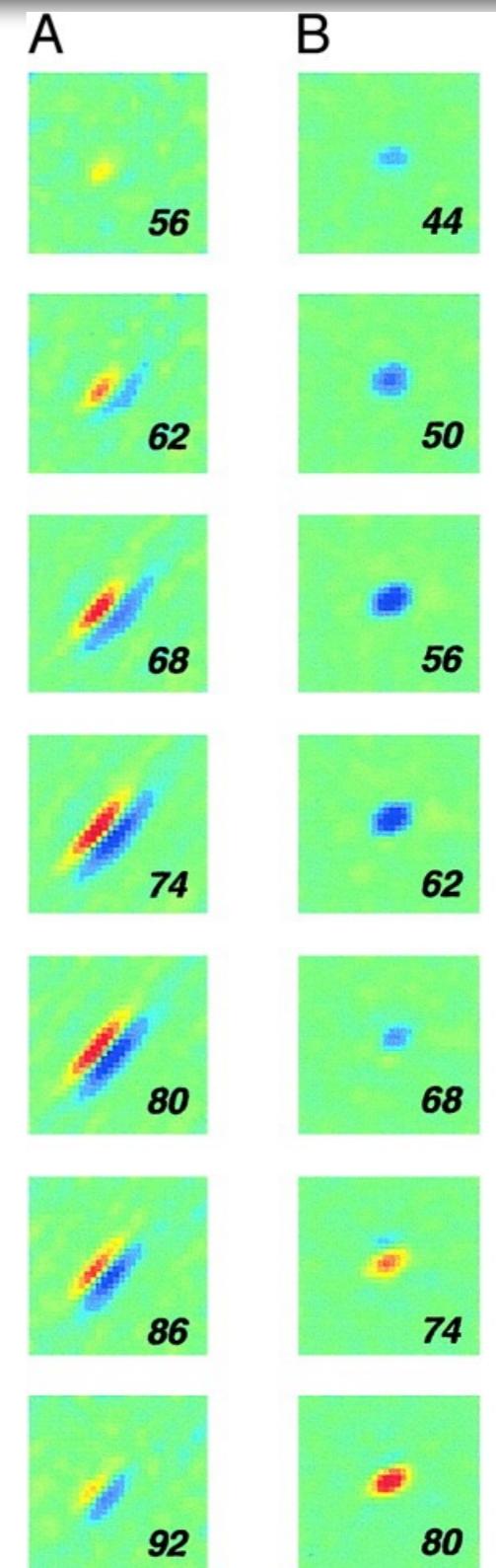
total response

r_k = neuron \mathbf{r} 's response to stimulus with pure orientation \mathbf{k}

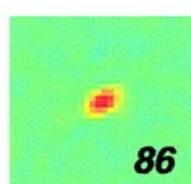
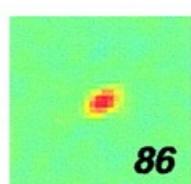
Gabors in V1



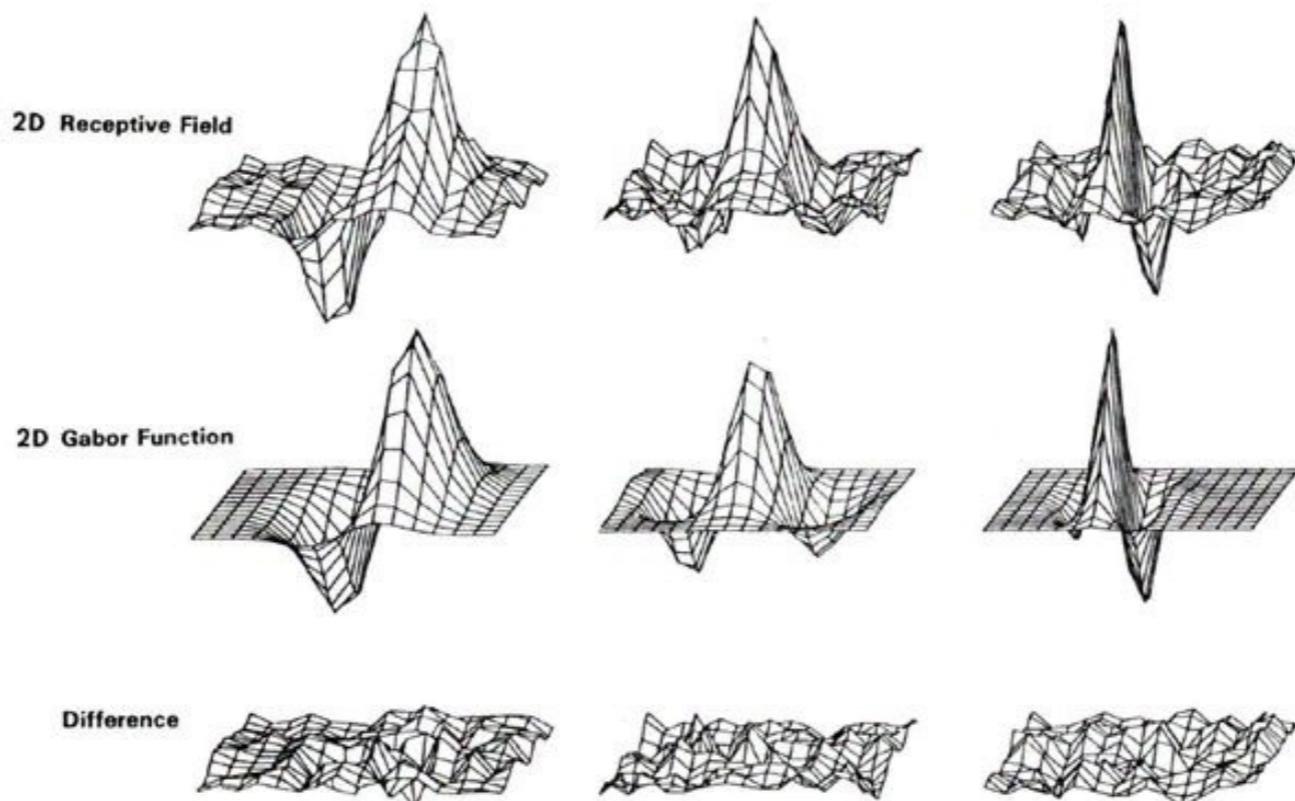
An et al 2015



Ringach 2002



Simple V1 cells Daugman, 1985



Receptive fields in primary visual cortex (Jones and Palmer, 1987)

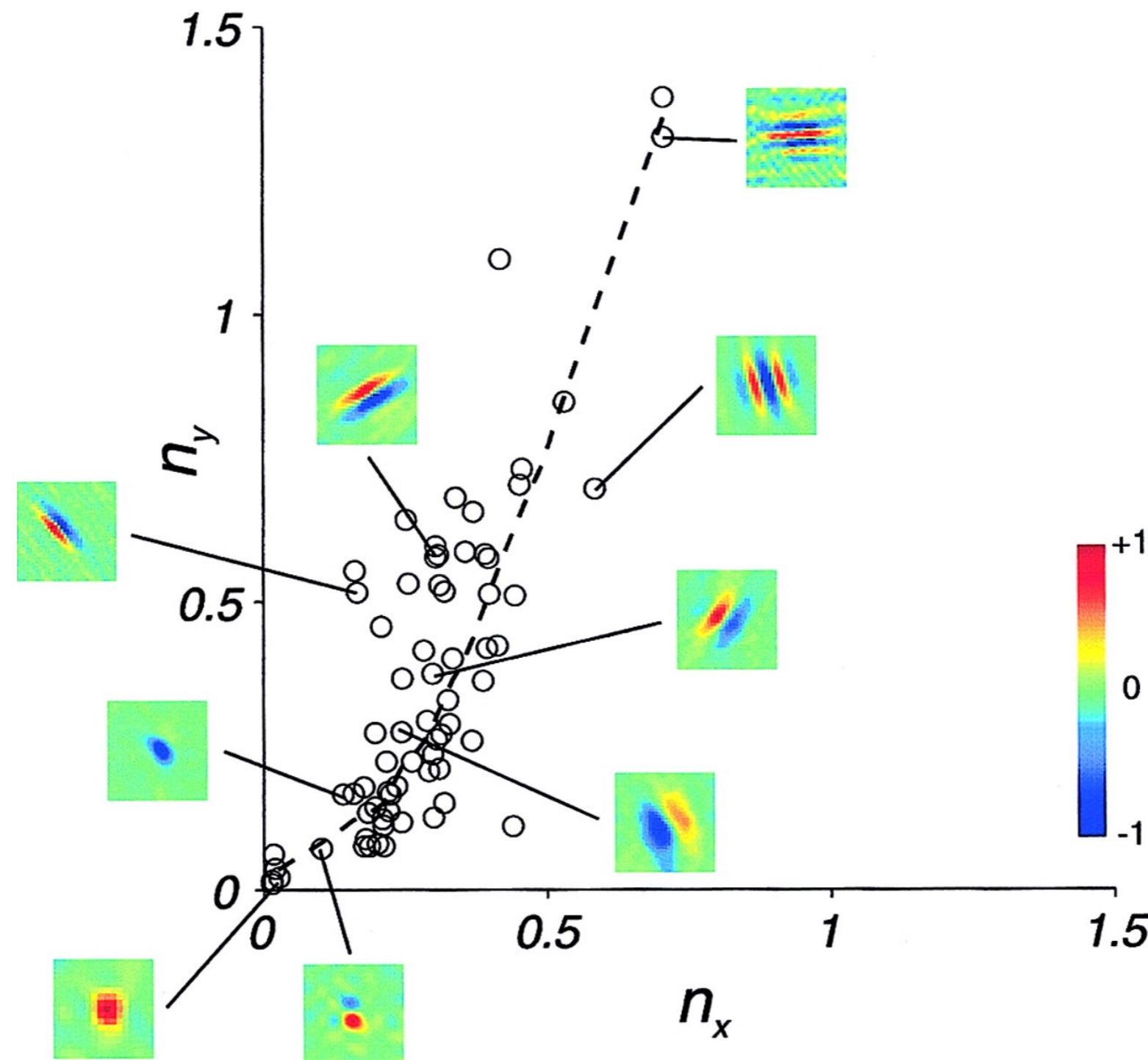
Gabor wavelets: localized sine and cosine waves

$$G(x) \propto \exp\left\{-\frac{1}{2}\left[\frac{x_1^2}{\sigma_1^2} + \frac{x_2^2}{\sigma_2^2}\right]\right\} e^{ix_1}$$

Translation, rotation, dilation of the above function

Gabors in VI

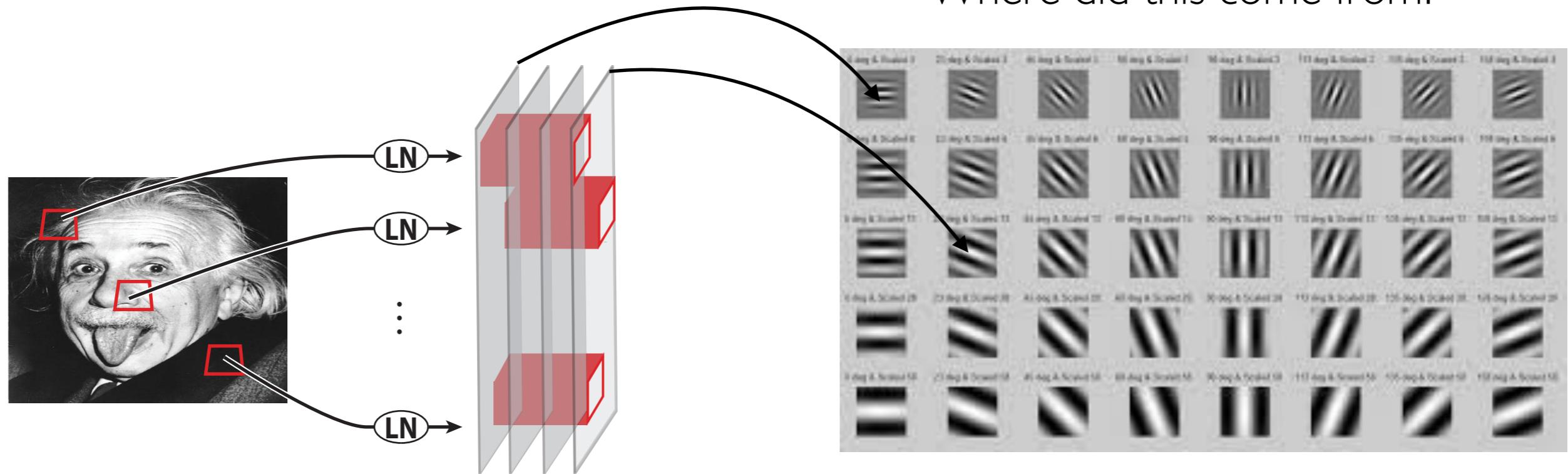
There is a frequency-orientation relationship:



from Ringach 2002

Models of VI

Where did this come from?



Two strategies to find the correct parameters.

less normative theory

more normative theory

I. Fit neural
data

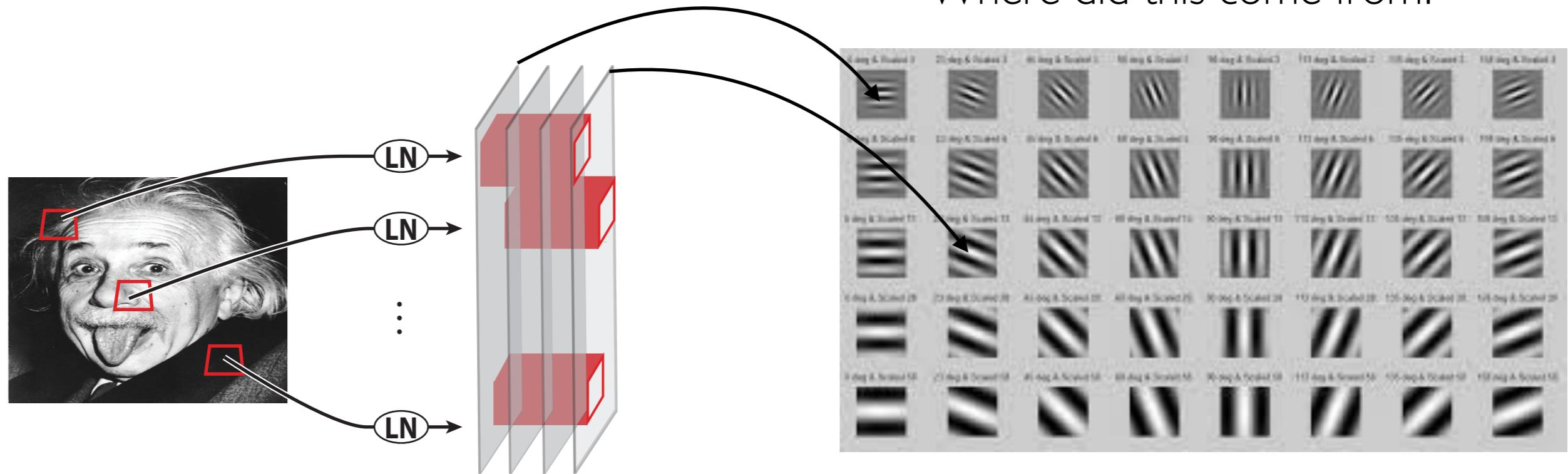
2. Solve a high-
level
ecological task

...

compare to
neural data
and
Turing Test

Models of VI

Where did this come from?

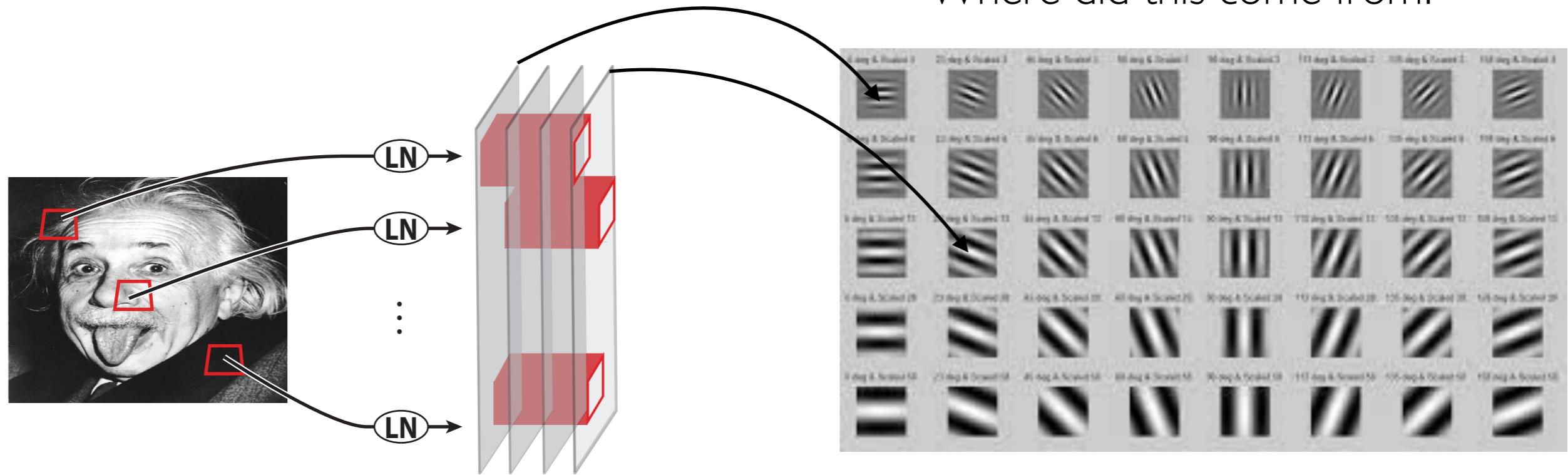


(I) “Hubel and Wiesel’s Intuition”
~1970s and formalized later

→ e.g. there is a “fixed basis set”
that just “makes sense” if we’re
smart enough

Models of VI

Where did this come from?



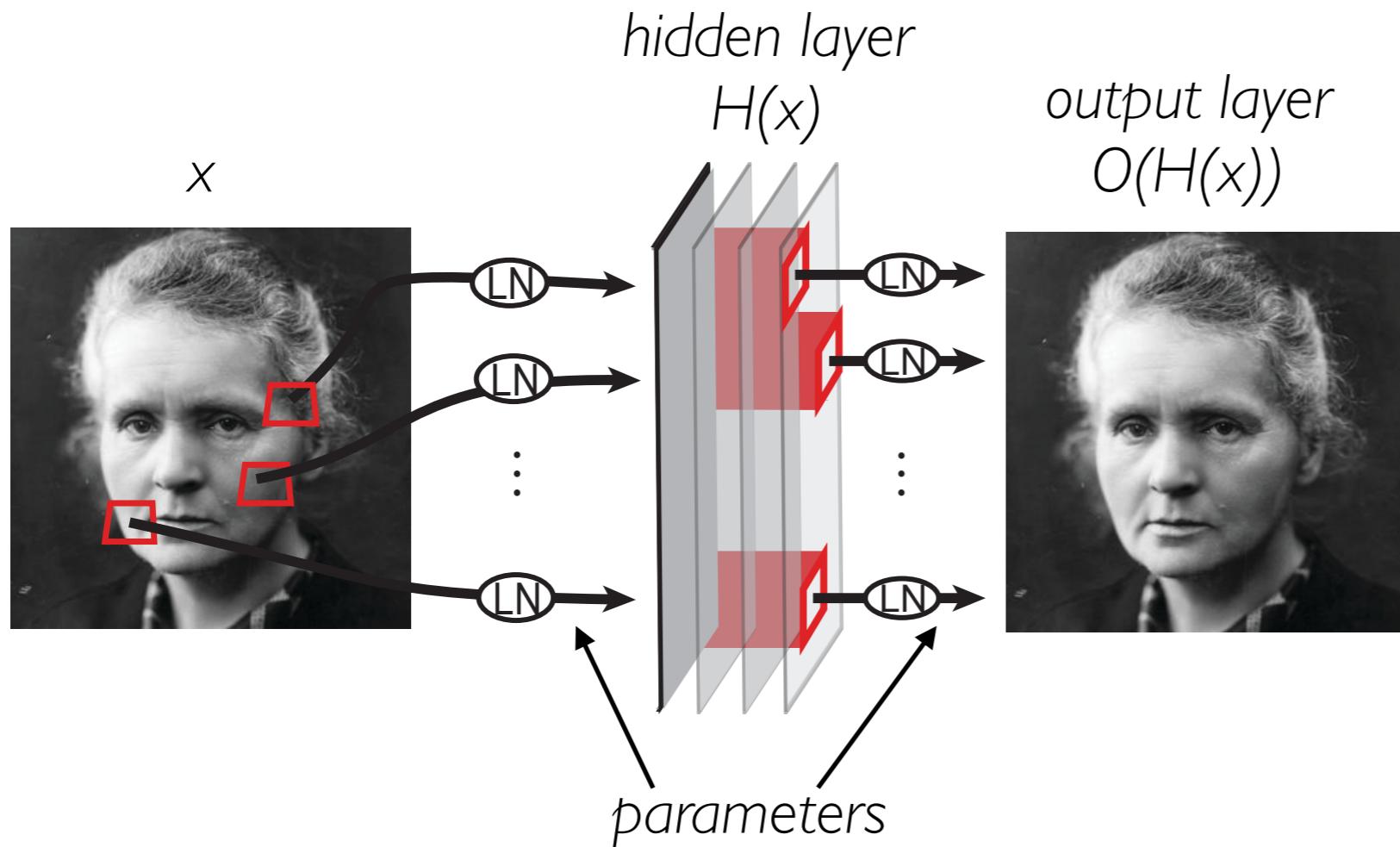
(1) “Hubel and Wiesel’s Intuition”
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→ e.g. there is a “fixed basis set”
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(2) Sparse Coding Foldiak, Olshausen,
mid 1990s

→ neurons have to represent their
environment, as efficiently as possible

Models of VI

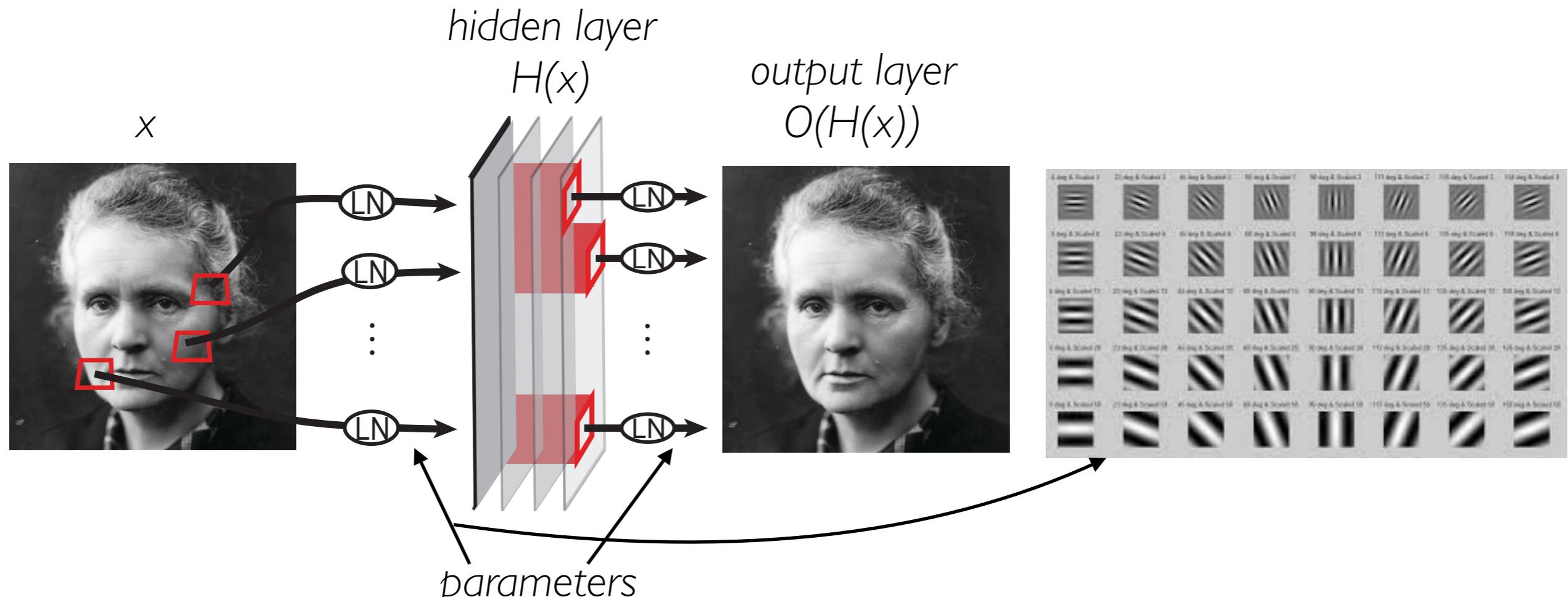


$$L(x) = |x - O(H(x))|^2 + \lambda \cdot |H(x)|$$

(2) Sparse Coding Foldiak, Olshausen,
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Models of VI

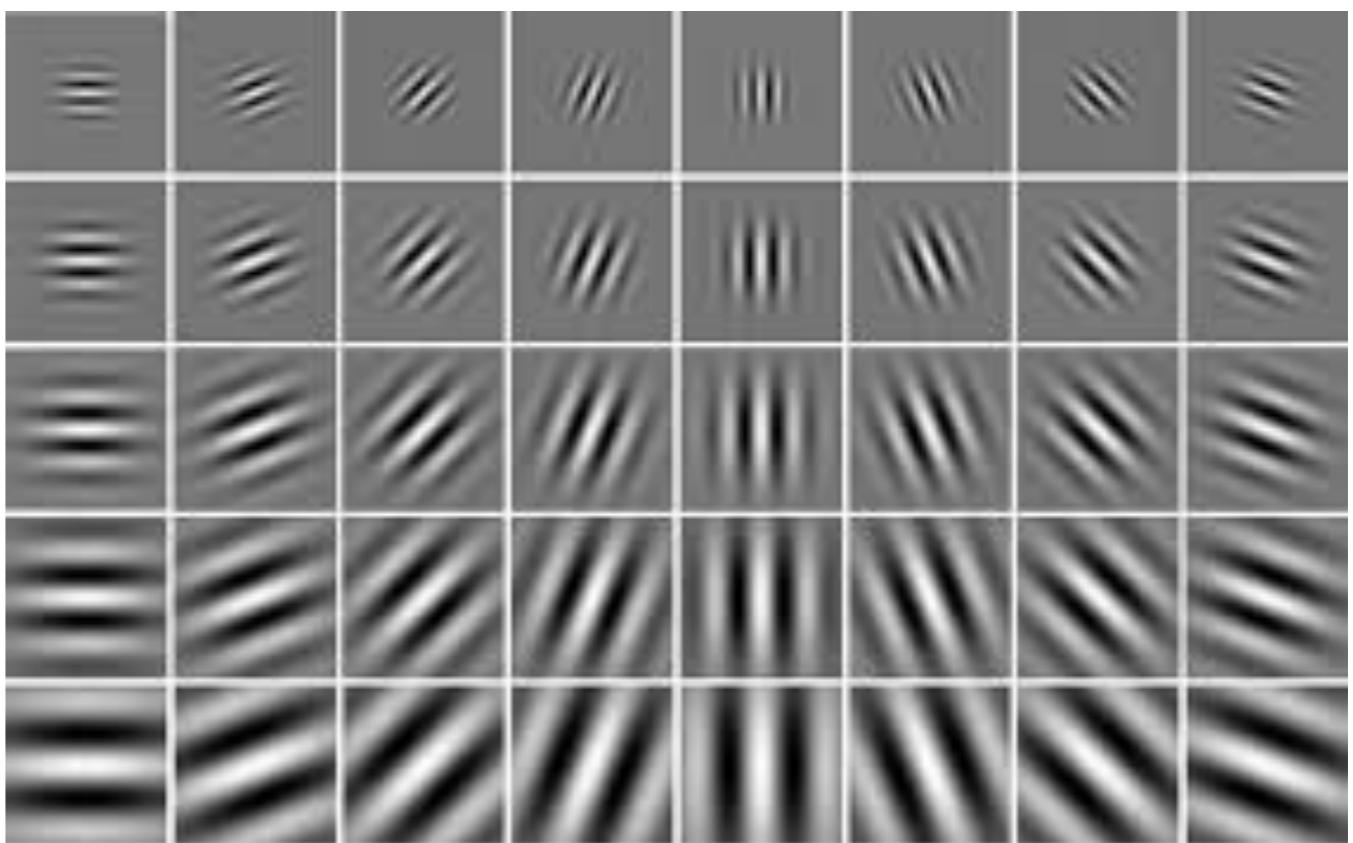
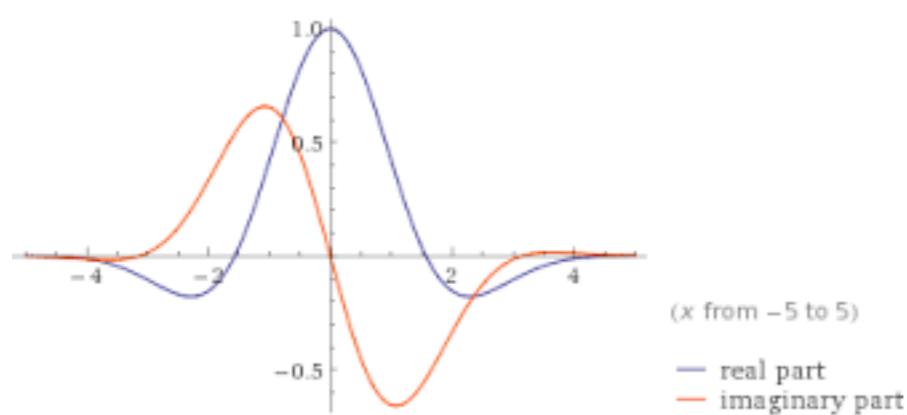


$$L(x) = |x - O(H(x))|^2 + \lambda \cdot |H(x)|$$

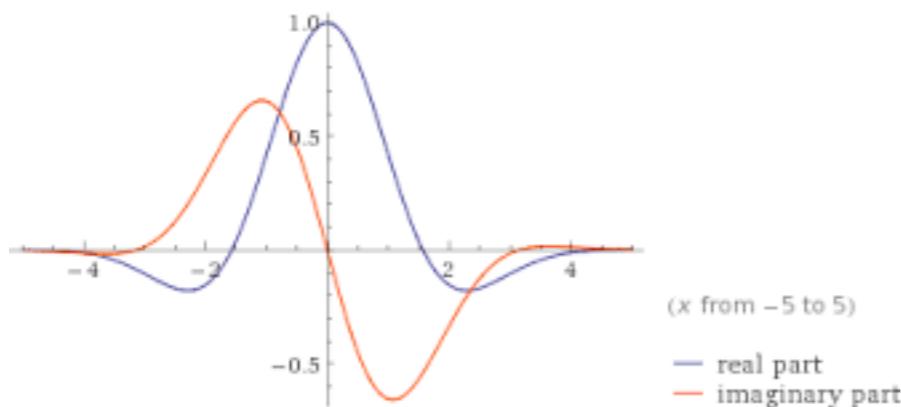
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Old-School CV part 2: The Wavelet Wave

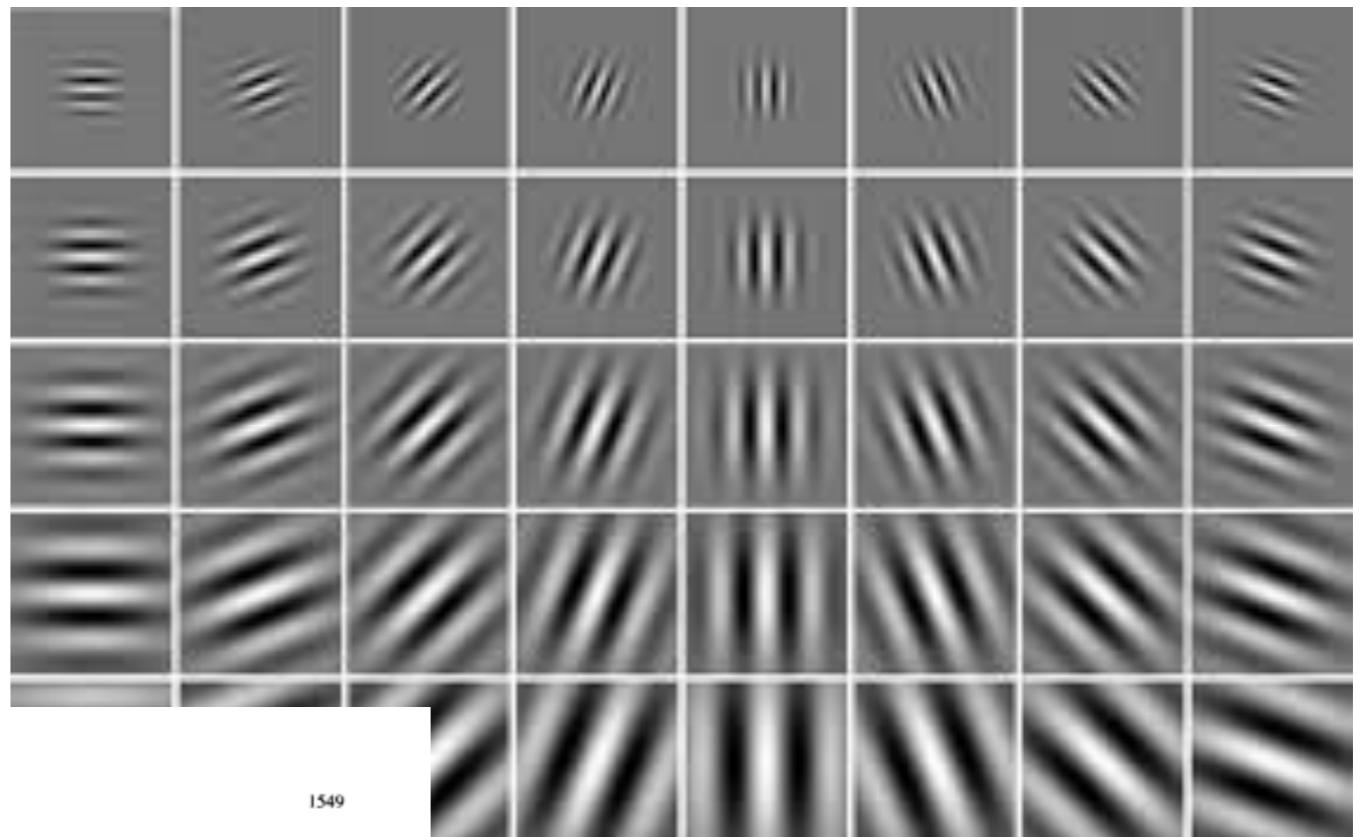


Old-School CV part 2: The Wavelet Wave



IEEE TRANSACTIONS ON IMAGE PROCESSING, VOL. 4, NO. 11, NOVEMBER 1995

1549



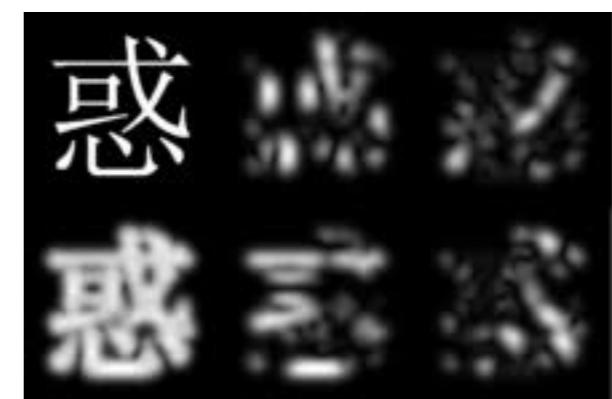
Texture Classification and Segmentation Using Wavelet Frames

Michael Unser, *Senior Member, IEEE*

Abstract—This paper describes a new approach to the characterization of texture properties at multiple scales using the wavelet transform. The analysis uses an overcomplete wavelet decomposition, which yields a description that is translation invariant. It is shown that this representation constitutes a tight frame of L_2 and that it has a fast iterative algorithm. A texture is characterized by a set of channel variances estimated at the output of the corresponding filter bank. Classification experiments with 12 Brodatz textures indicate that the discrete wavelet frame (DWF) approach is superior to a standard (critically sampled) wavelet transform feature extraction. These results also suggest that this approach should perform better than most traditional single resolution techniques (co-occurrences, local linear transform, and the like). A detailed comparison of the classification performance of various orthogonal and biorthogonal wavelet transforms is also provided. Finally, the DWF feature extraction technique is incorporated into a simple multicomponent texture segmentation algorithm, and some illustrative examples are presented.

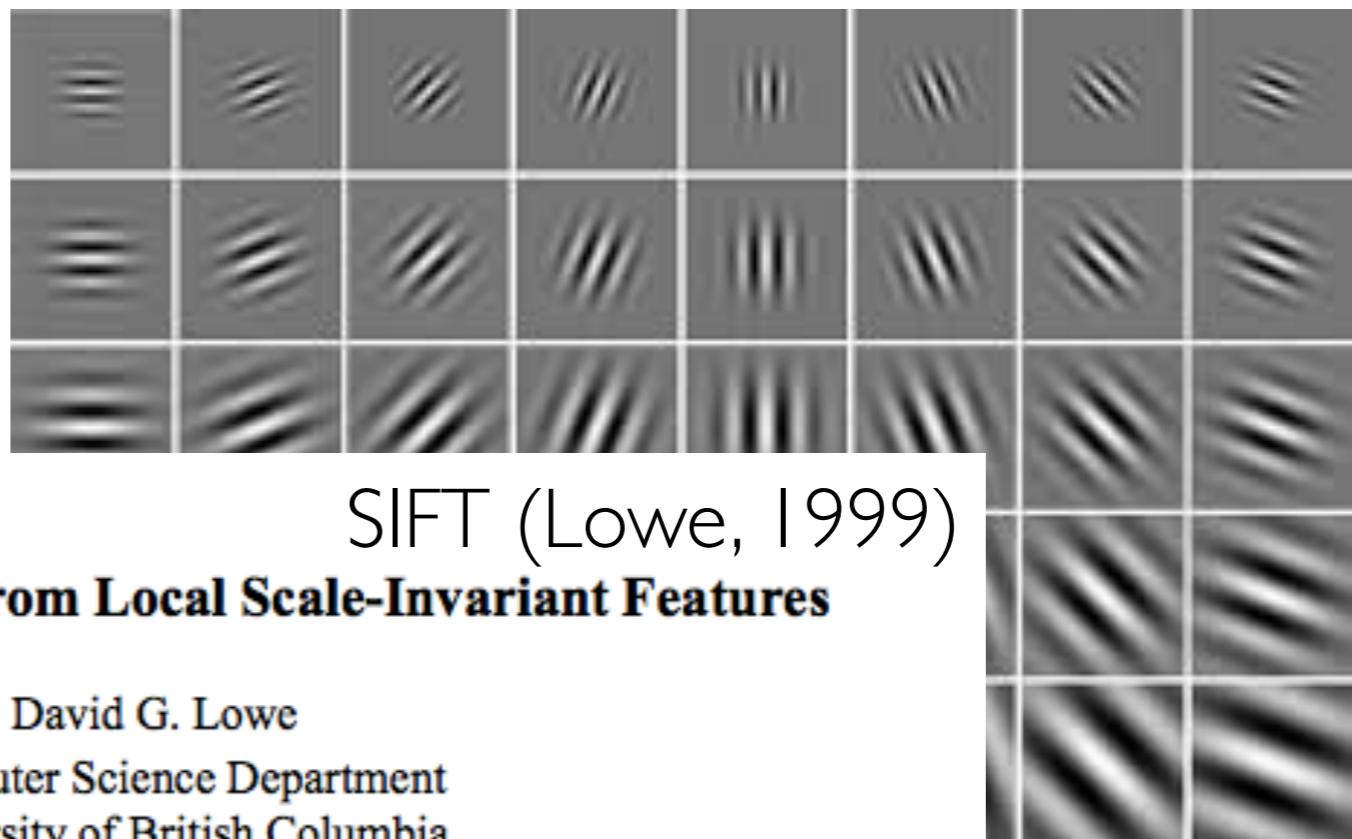
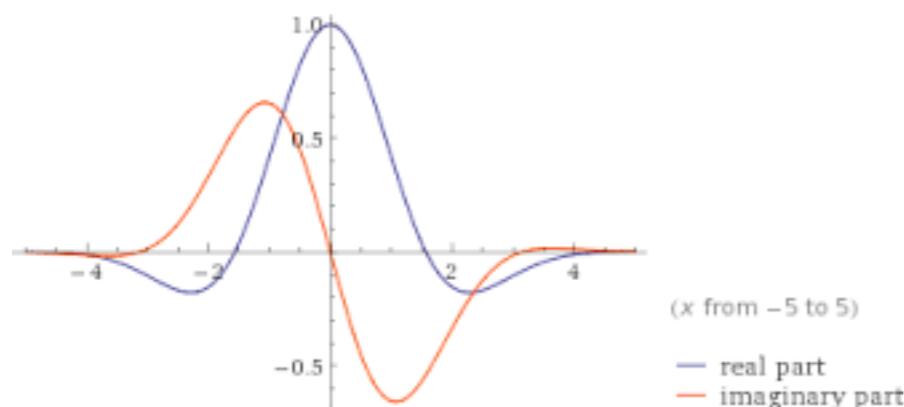
reversible, which limits their applicability for texture synthesis. Most of these problems can be avoided if one uses the wavelet transform, which provides a precise and unifying framework for the analysis and characterization of a signal at different scales [16]–[19]. The use of a pyramid-structured wavelet transform for texture analysis was first suggested in the pioneering work of Mallat [19]. This initial proposal has been followed by several studies on texture classification with a particular attention to the use of wavelet packets [20], [21], which constitute a multiband extension of the pyramid-structured wavelet transform.

In this paper, a variation of the discrete wavelet transform is introduced for characterizing texture properties. This technique is applied to the problems of texture classification and segmentation. The present analysis method, which is described in Section II, uses an overcomplete wavelet decomposition (the discrete wavelet frame (DWF) in [16]–[19]).



Many CV careers made on wavelets.

Old-School CV part 2: The Wavelet Wave



SIFT (Lowe, 1999)

Object Recognition from Local Scale-Invariant Features

David G. Lowe

Computer Science Department
University of British Columbia
Vancouver, B.C., V6T 1Z4, Canada
lowe@cs.ubc.ca

IEEE TRANSACTIONS ON IMAGE PROCESSING

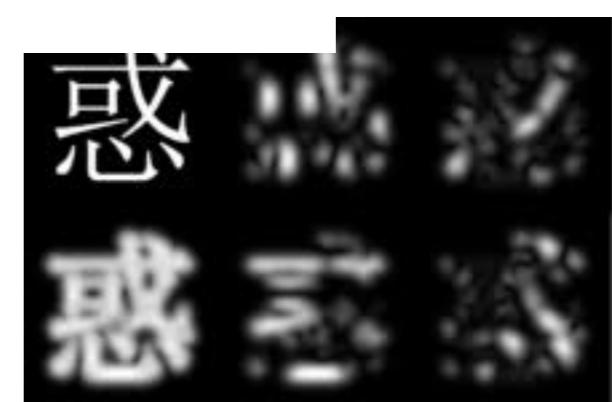
Segmentation

Michael Unser, *Senior Member, IEEE*

Abstract—This paper describes a new approach to the characterization of texture properties at multiple scales using the wavelet transform. The analysis uses an overcomplete wavelet decomposition, which yields a description that is translation invariant. It is shown that this representation constitutes a tight frame of L_2 and that it has a fast iterative algorithm. A texture is characterized by a set of channel variances estimated at the output of the corresponding filter bank. Classification experiments with 12 Brodatz textures indicate that the discrete wavelet frame (DWF) approach is superior to a standard (critically sampled) wavelet transform feature extraction. These results also suggest that this approach should perform better than most traditional single resolution techniques (co-occurrences, local linear transform, and the like). A detailed comparison of the classification performance of various orthogonal and biorthogonal wavelet transforms is also provided. Finally, the DWF feature extraction technique is incorporated into a simple multicomponent texture segmentation algorithm, and some illustrative examples are presented.

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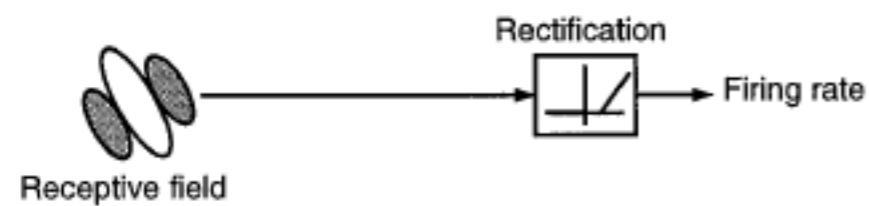
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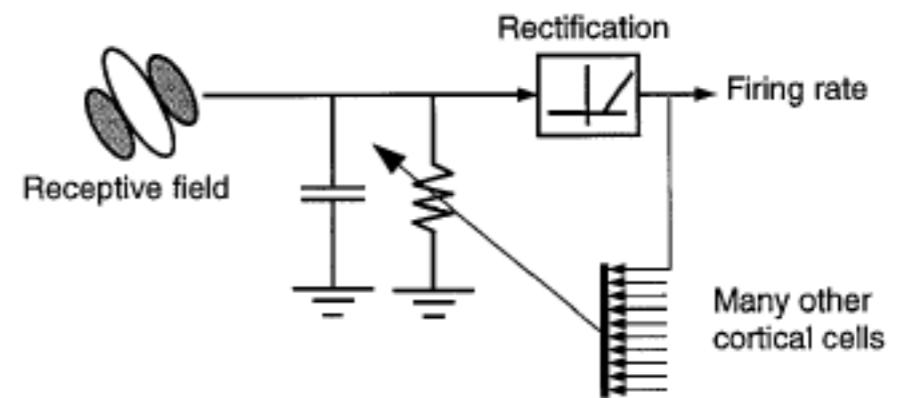
Many CV careers made on
wavelets.



A Linear model



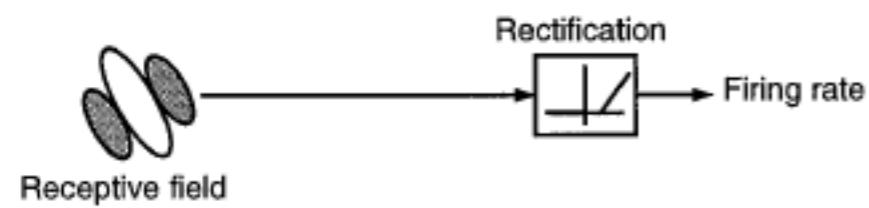
B Normalization model



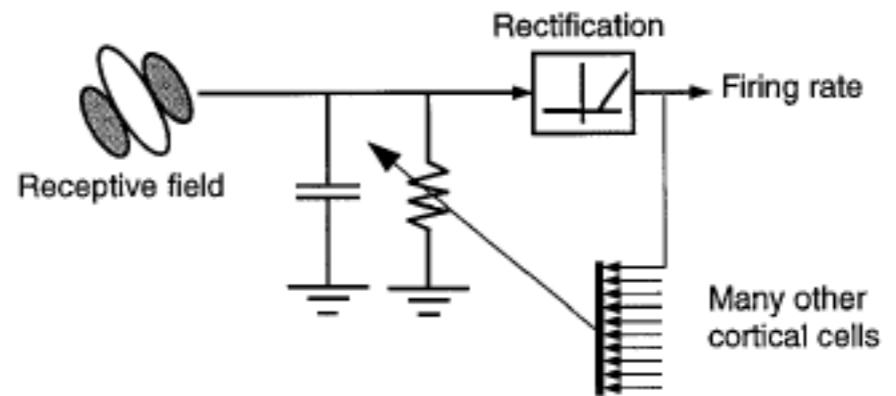


Carandini, Heeger and Movshon (1997)

A Linear model



B Normalization model



$$C \frac{dV}{dt} + gV = I$$

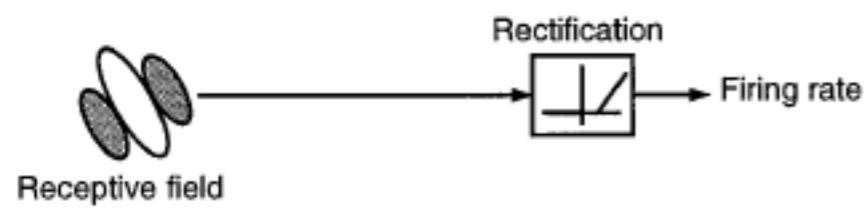
$$g = \frac{g_0}{\sqrt{1 - k \cdot \sum_{r \in R_x} r}}$$

$$R = \max(0, V)$$

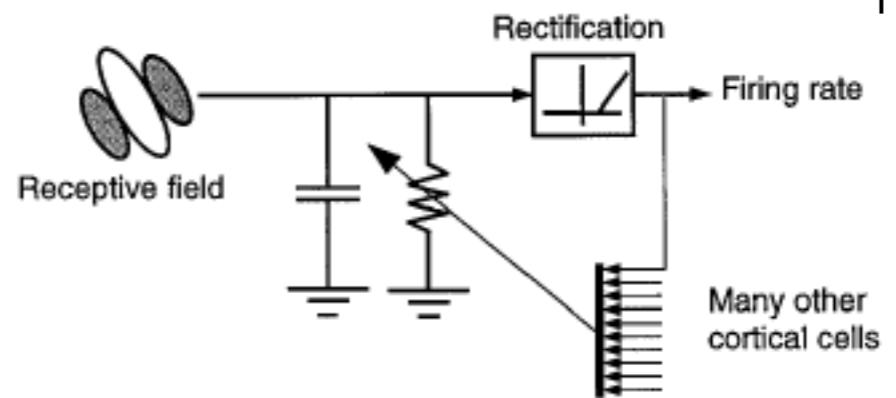


Carandini, Heeger and Movshon (1997)

A Linear model



B Normalization model



$$C \frac{dV}{dt} + gV = I$$

$$g = \frac{g_0}{\sqrt{1 - k \cdot \sum_{r \in R_x} r}}$$

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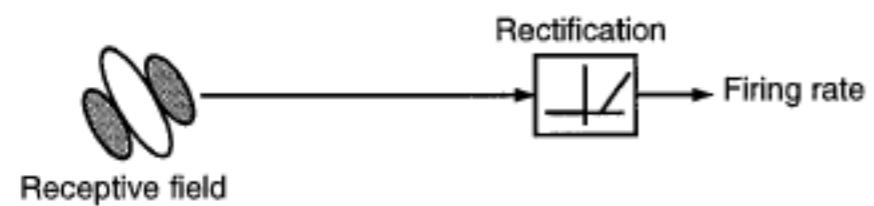
measure R from neural data

solve diff eq for equilibrium, estimate free parameters: C, k, g_0

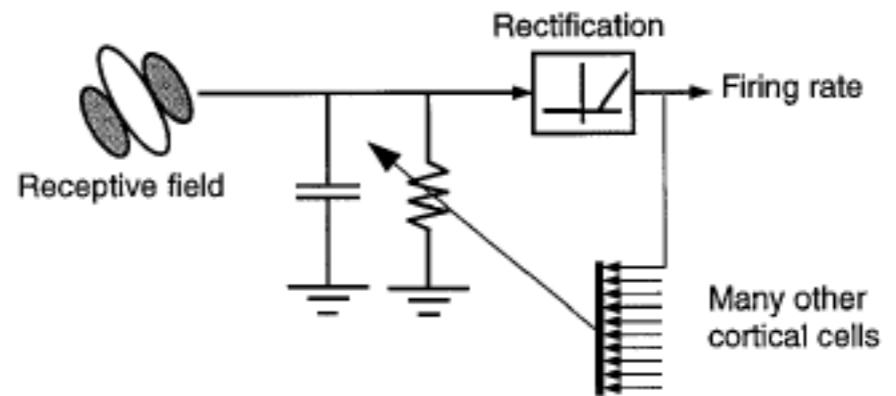


Carandini, Heeger and Movshon (1997)

A Linear model



B Normalization model



$$y = R [W * x]$$

$$y = R [\text{norm}(W * x)]$$

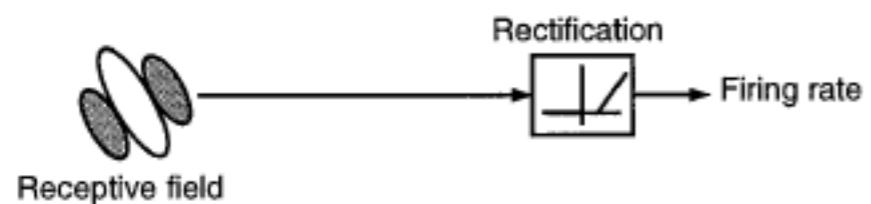
OR: derive this expression: \longrightarrow
(basically)

$$\text{norm}(x) \sim \frac{x}{\left(\gamma + \alpha \cdot \sum_{r \in R_x} x_r^2 \right)^\beta}$$

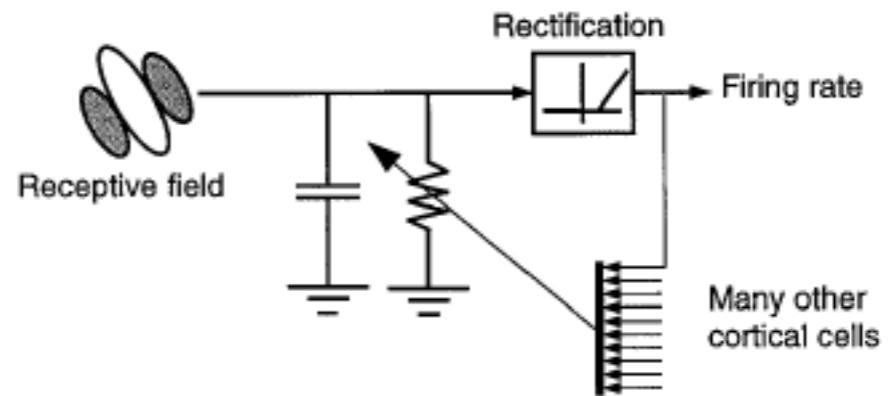


Carandini, Heeger and Movshon (1997)

A Linear model



B Normalization model



$$y = R [W * x]$$

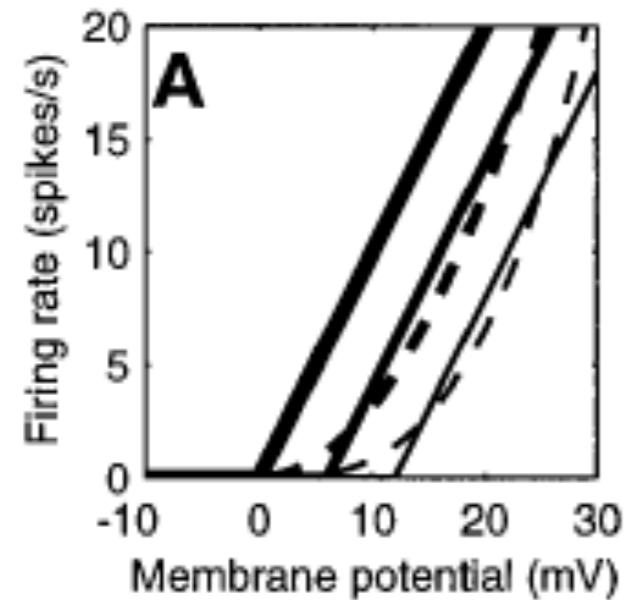
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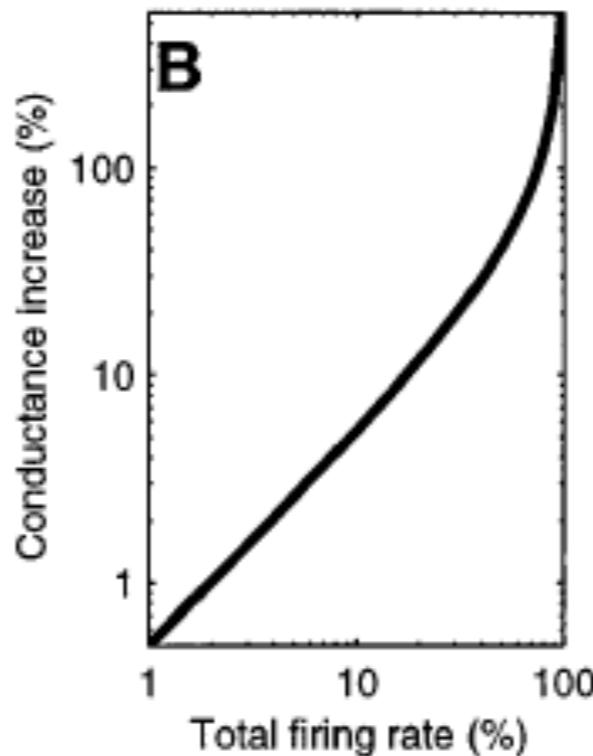
$$\text{norm}(x) \sim \frac{x}{\left(\gamma + \alpha \cdot \sum_{r \in R_x} x_r^2 \right)^\beta}$$

NB: (1) derivation involves “reasonable” assumption that “the normalization pool to contain quadruples of cells with the same amplitude response but with phases 90° apart.” (2) **The above is how we now define local response normalization**

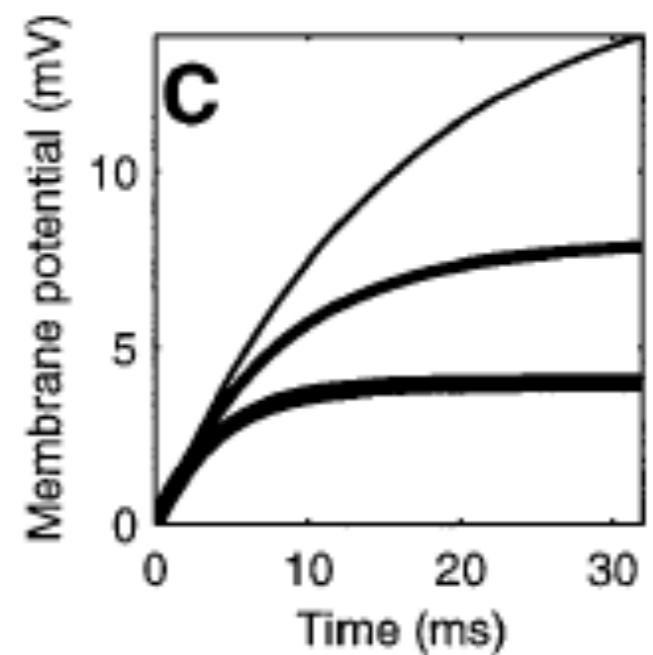
Interrelations and effects of the principal variables in the normalization model.



Relation between
membrane potential
and
firing rate.



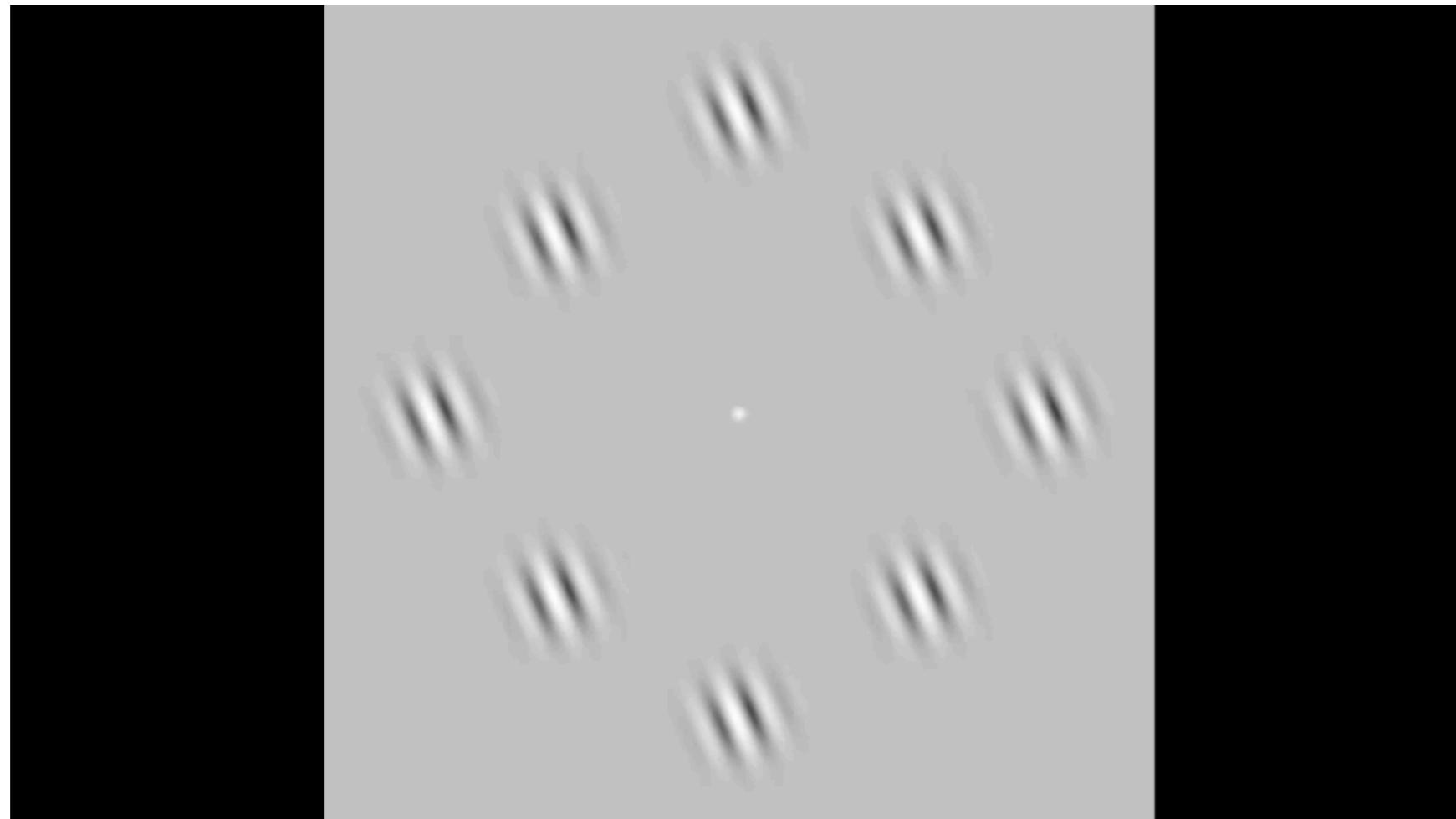
Relation between
pool activity and
membrane
conductance.



Effects of
conductance on
the size and time
course of the
membrane
potential.

Responses to drifting sine gratings of different contrasts

Carandini, Heeger and Movshon (1997)



The **I** in this equation:

$$C \frac{dV}{dt} + gV = I$$

is a sinusoid

$$\text{neural response} \sim A * \sin(w t + d)$$

A = amplitude of cell

w = frequency of the drift

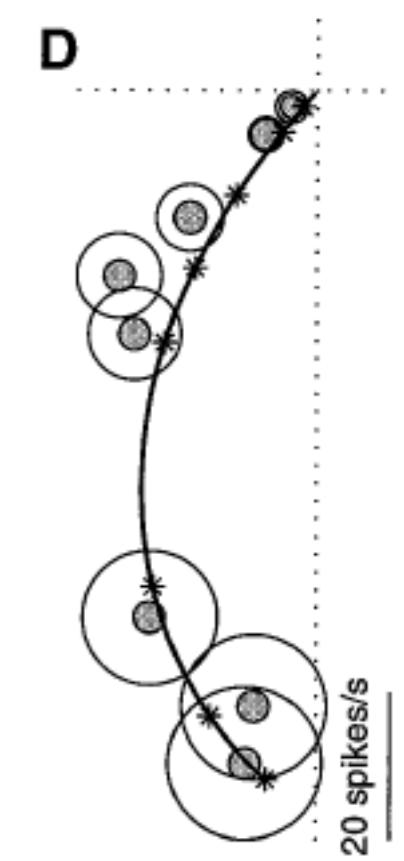
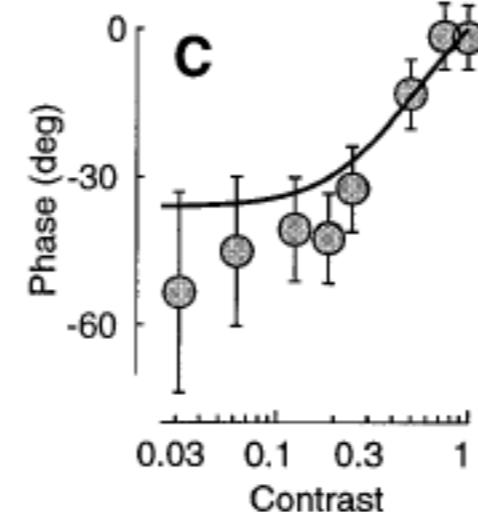
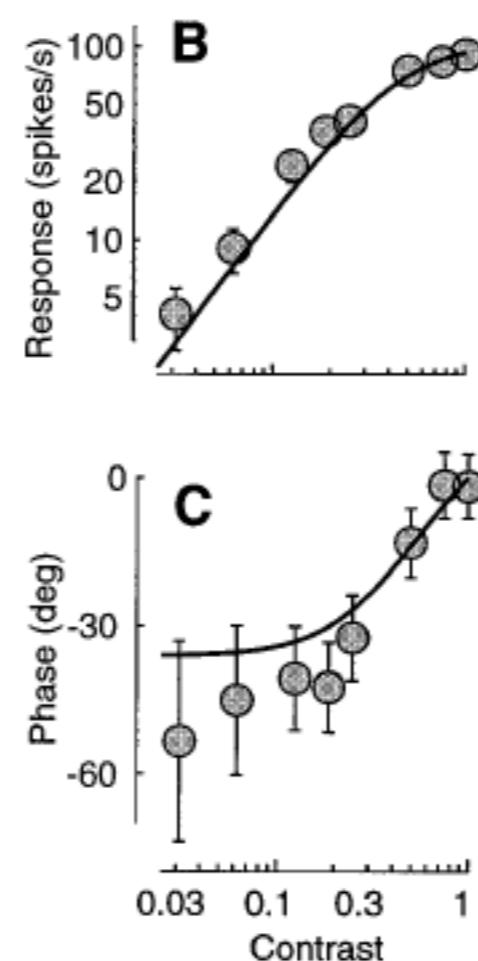
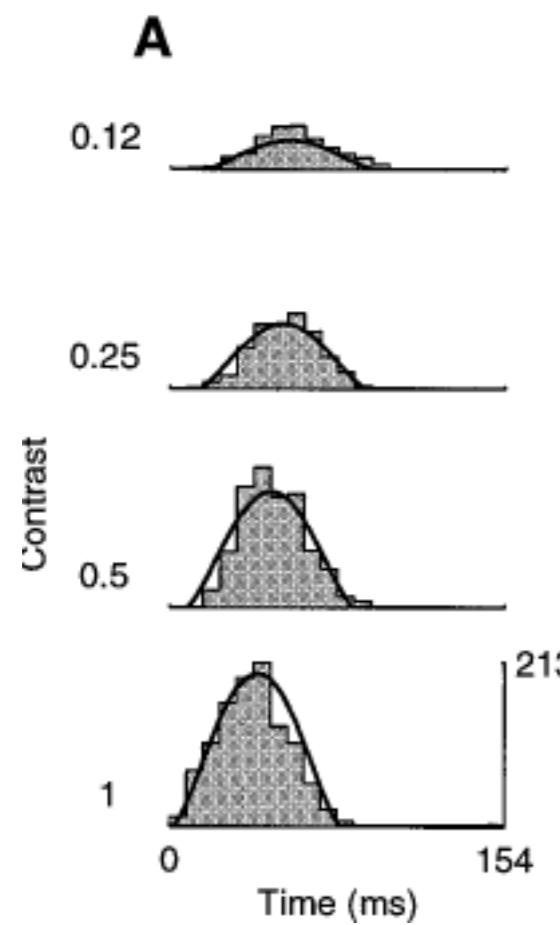
d = phase of cell

A, d are fit to the data

What functions are A and d of a stimulus parameter — contrast?

the parameters **C, k, A, d** (basically) are fit to the neuron over a bunch of stimulus conditions

histogram of responses for different contrasts

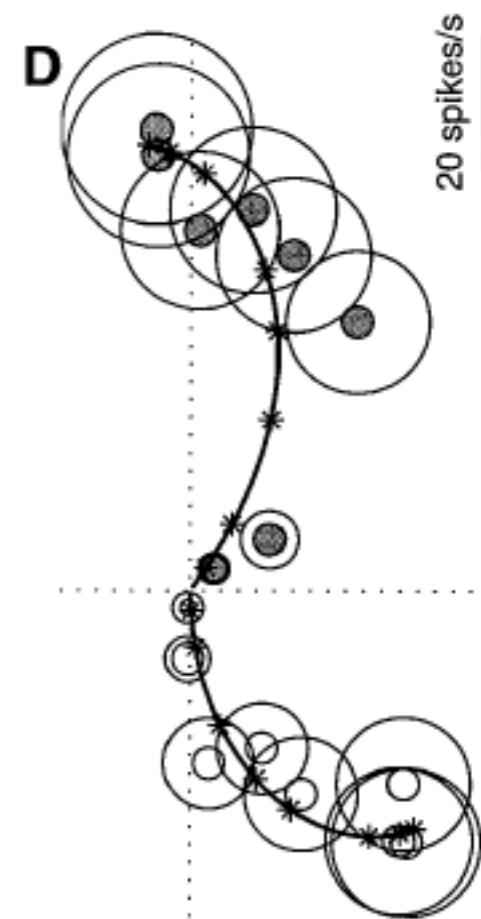
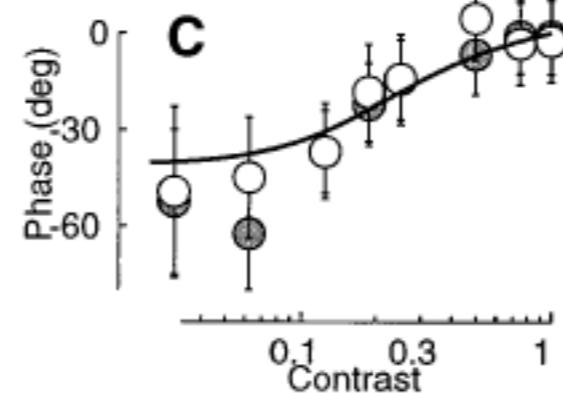
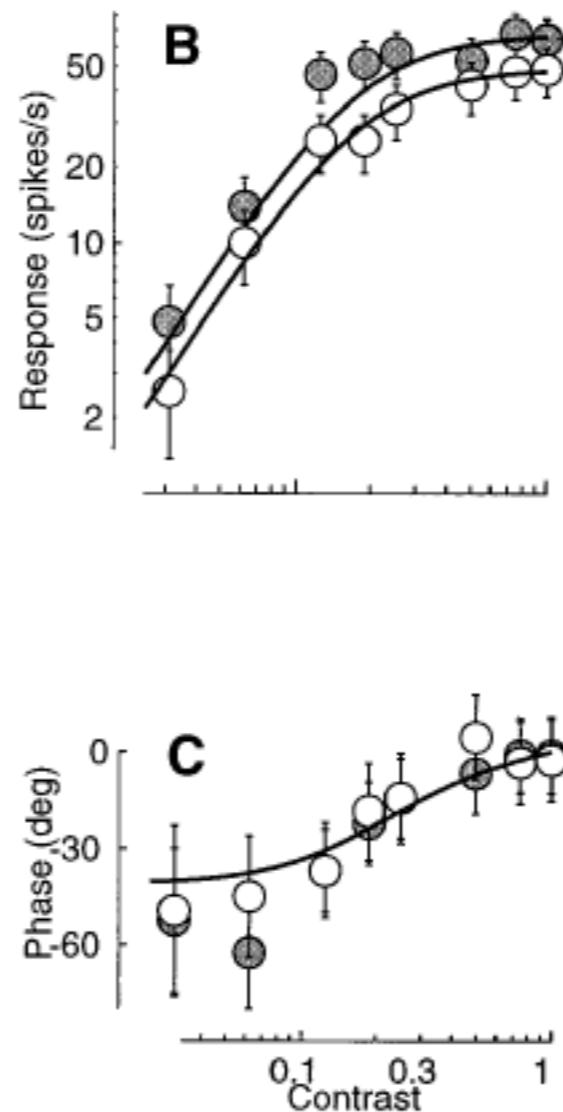
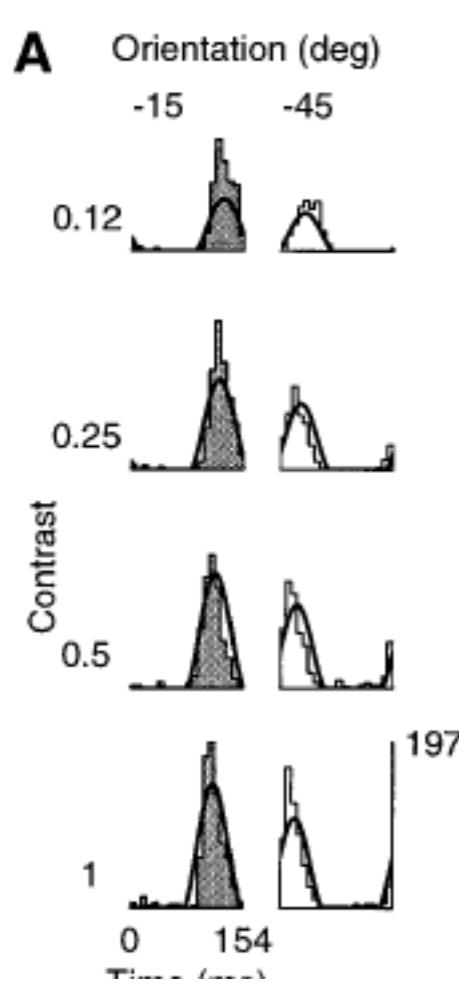


response vs phase

each point is response to a different sinusoid

Now as a function of grating orientation

Carandini, Heeger and Movshon (1997)

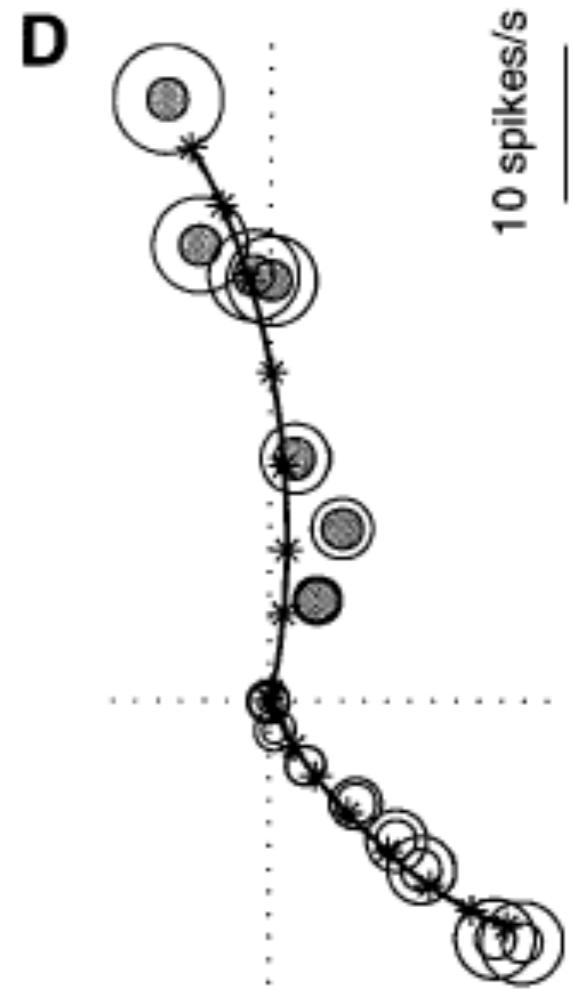
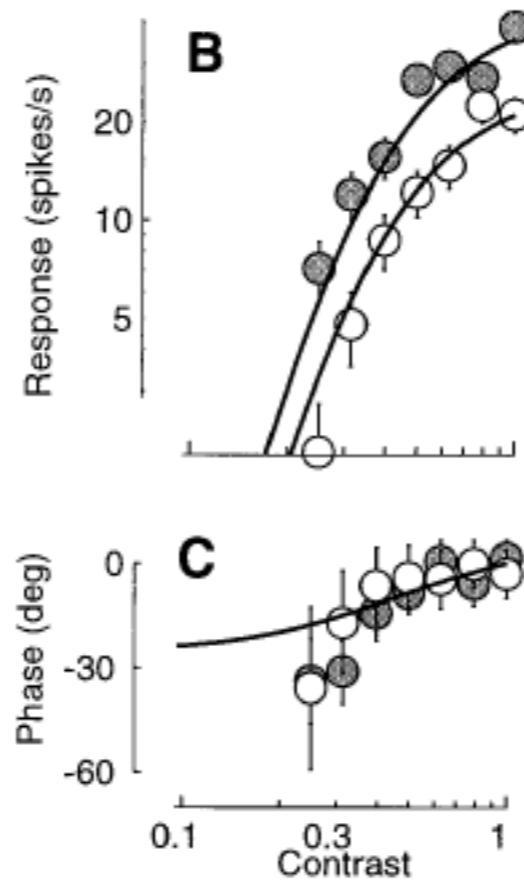
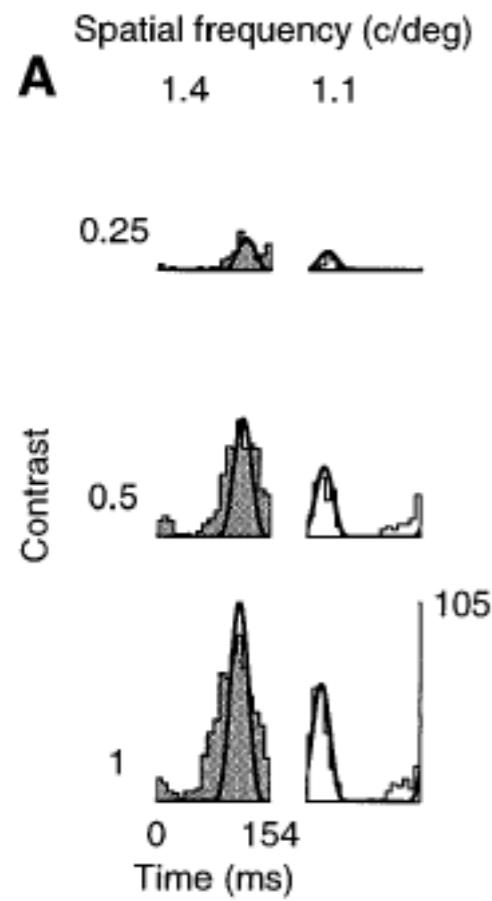


response vs phase

gray = -15deg, white = -45deg

Now as a function of spatial frequency

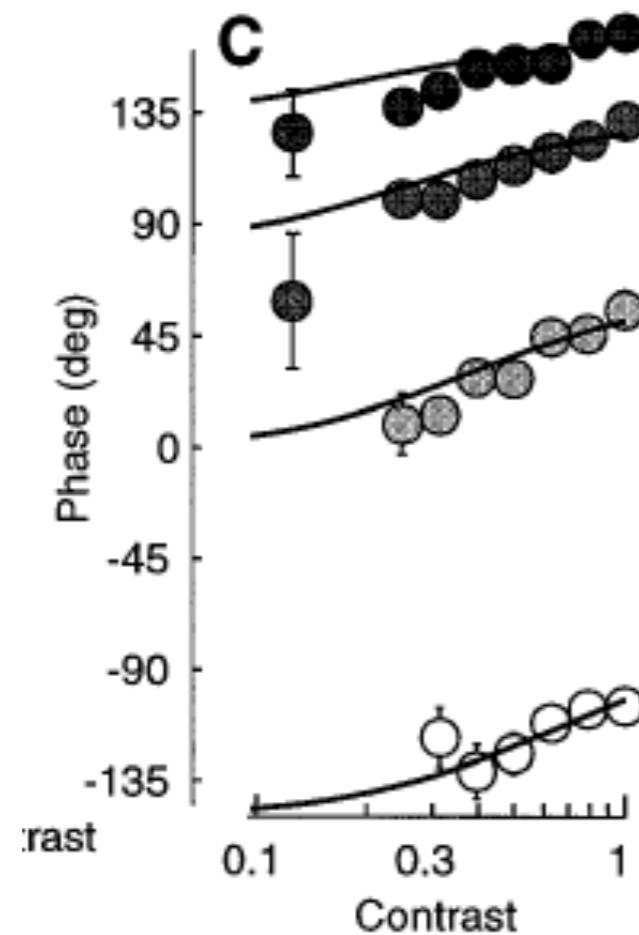
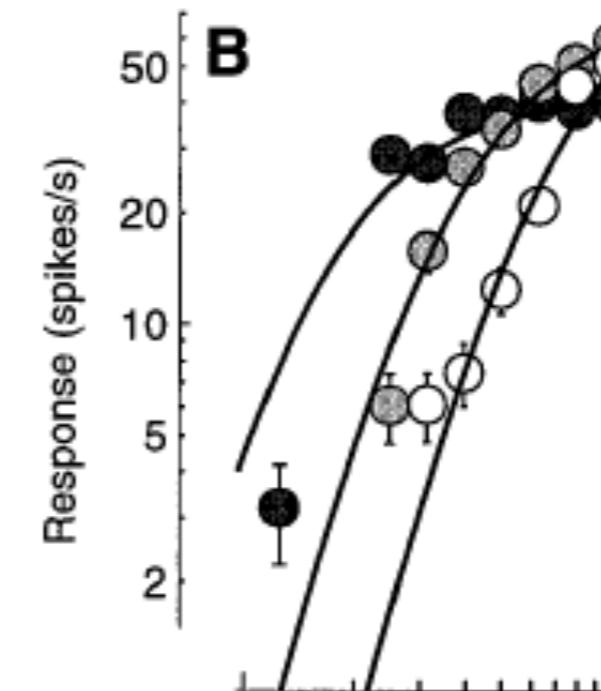
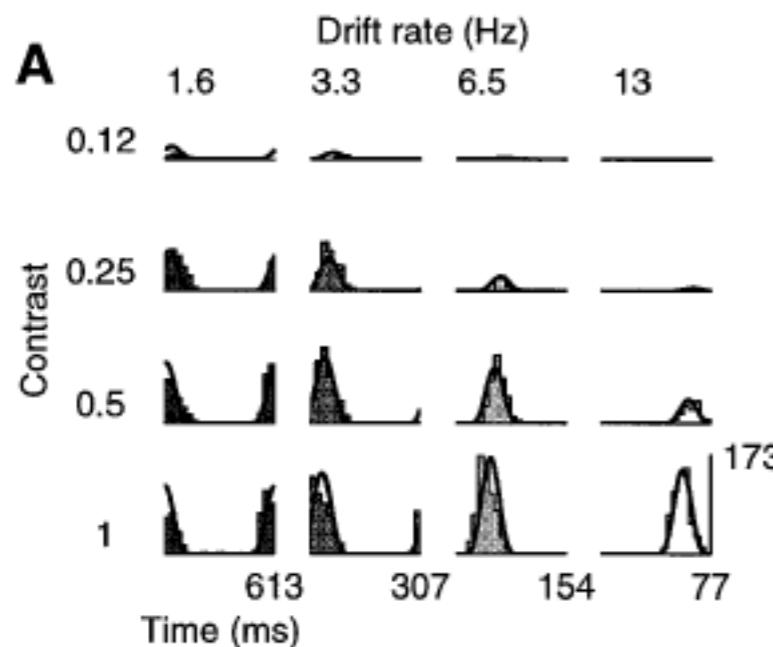
Carandini, Heeger and Movshon (1997)



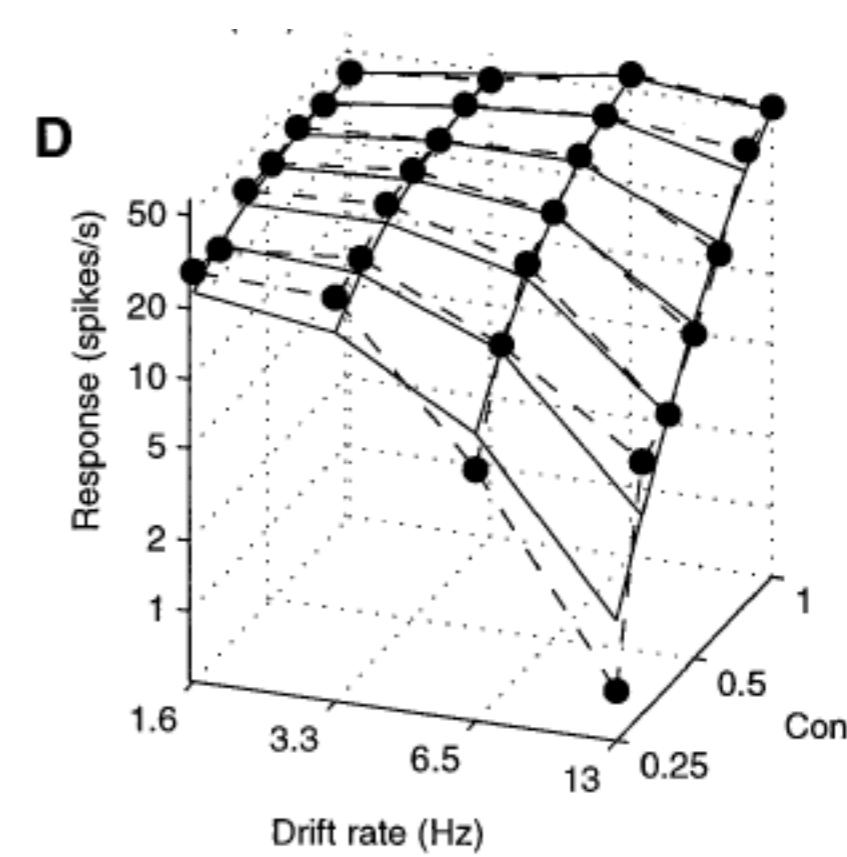
gray = 1.4 cyc/deg, white = 1.1 cyc/deg

Now as a function of temporal frequency

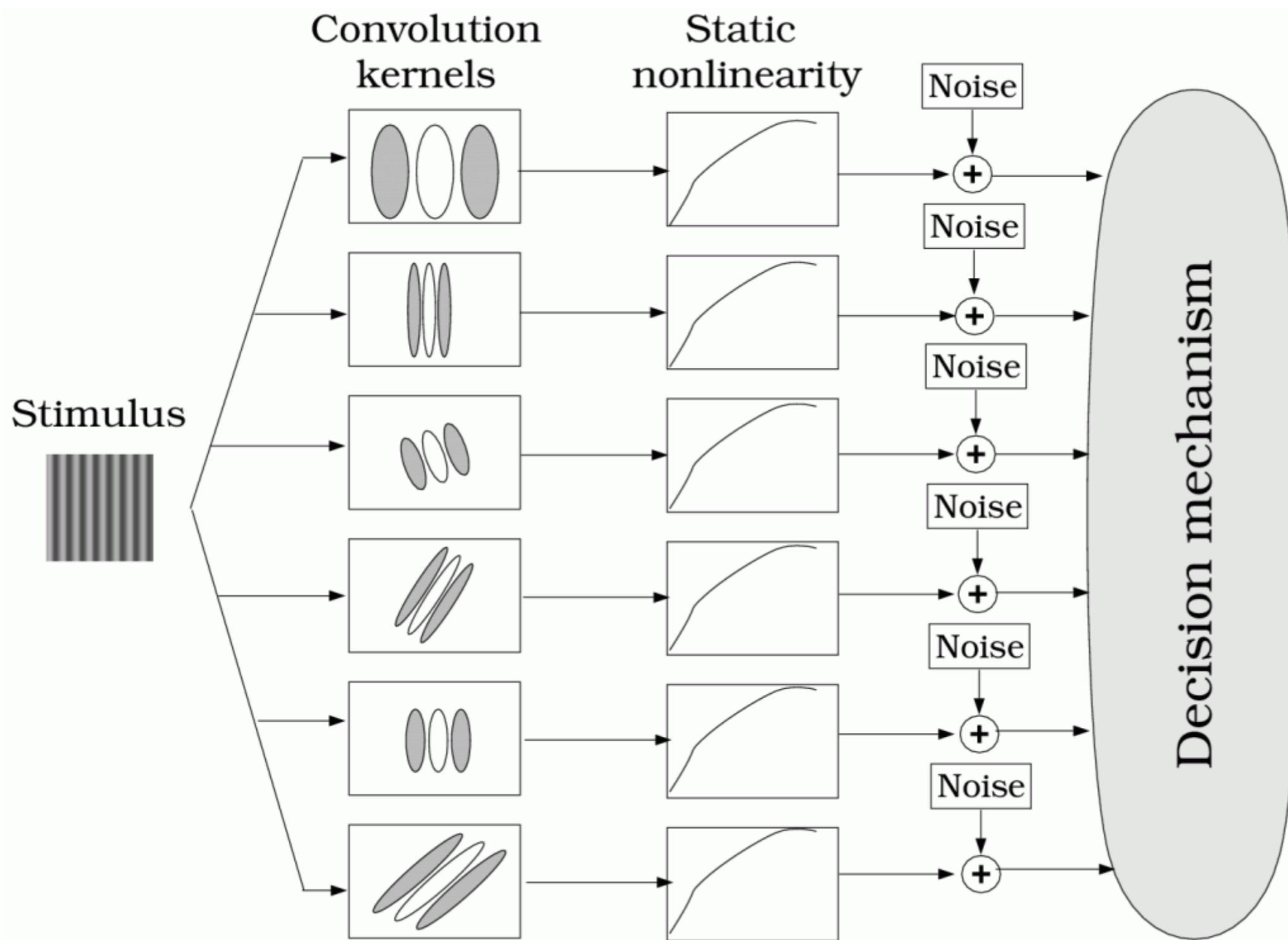
Carandini, Heeger and Movshon (1997)



Colors
as in
panel **A**



Goal: Predictive Model of Ventral Stream



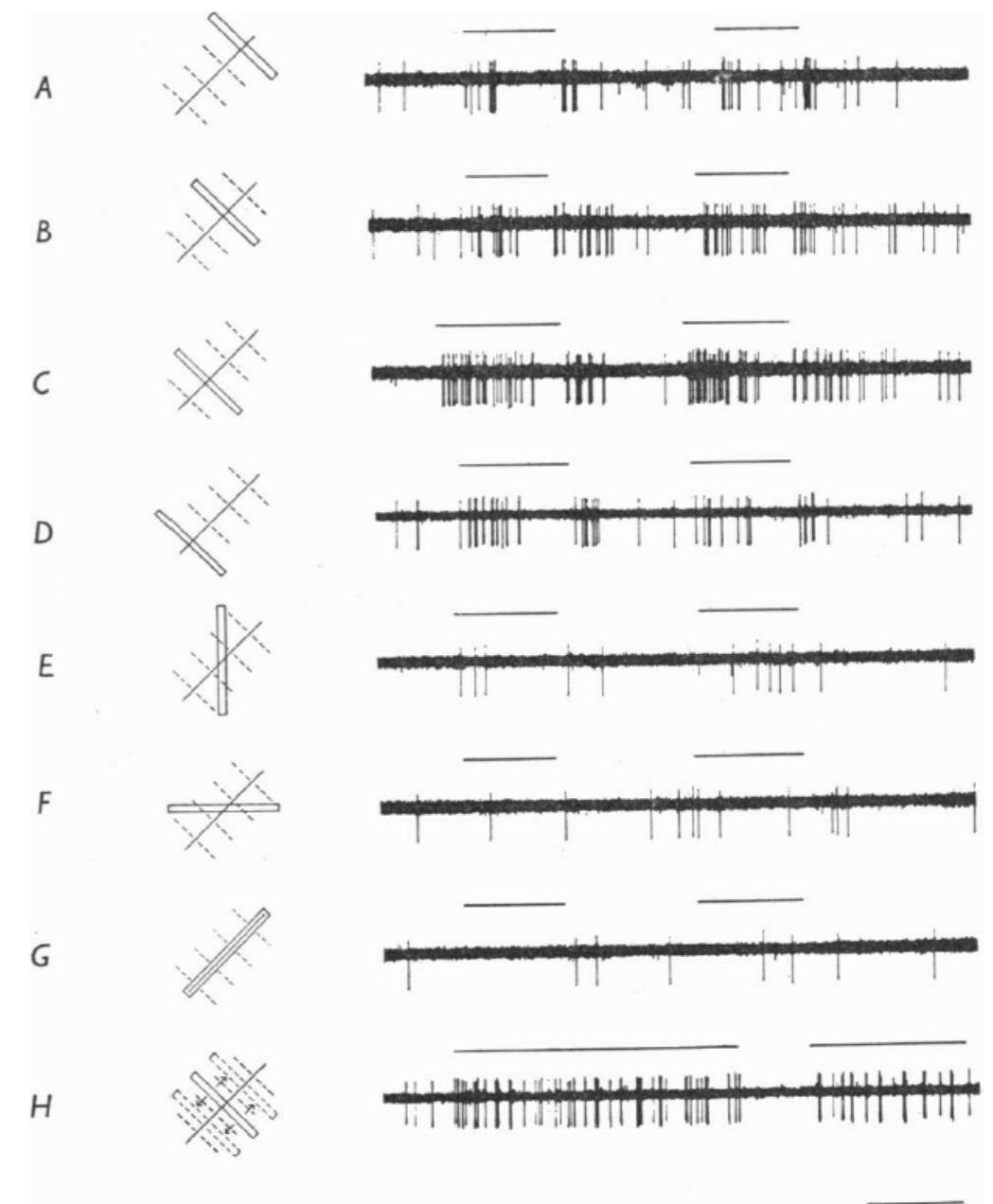
from Wandell 1996

Pooling

More generally, it was realized in computer vision that **pooling** was a good idea.

recall Hubel & Wiesel's complex cell >>

$$y = \left(\frac{1}{|N_r|} \sum_{i \in N_r} x_i^p \right)^{1/p}$$

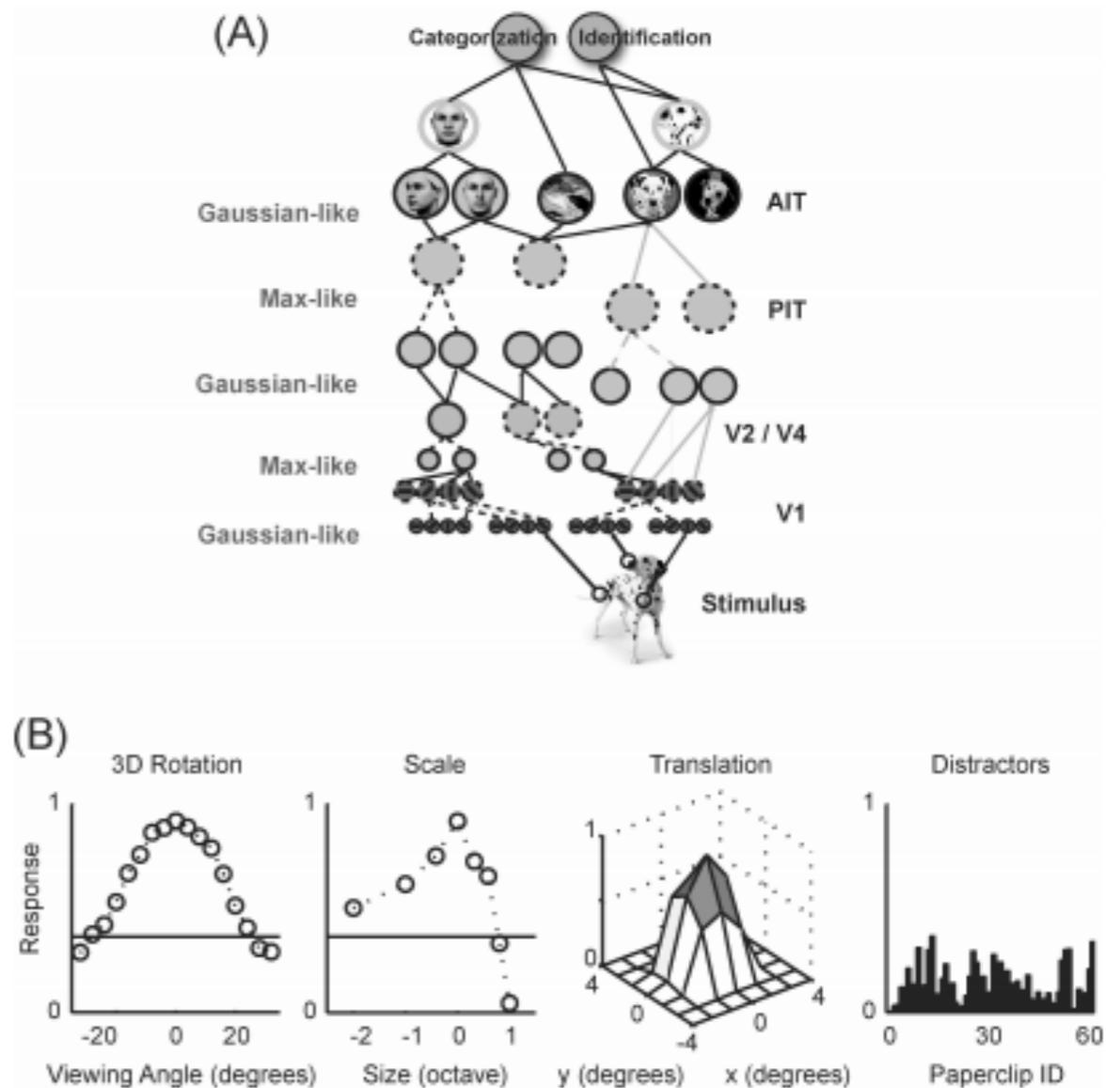


(Actually, if you're running a CNN, you basically **have** to do pooling + downsampling, for memory reasons.)

Pooling

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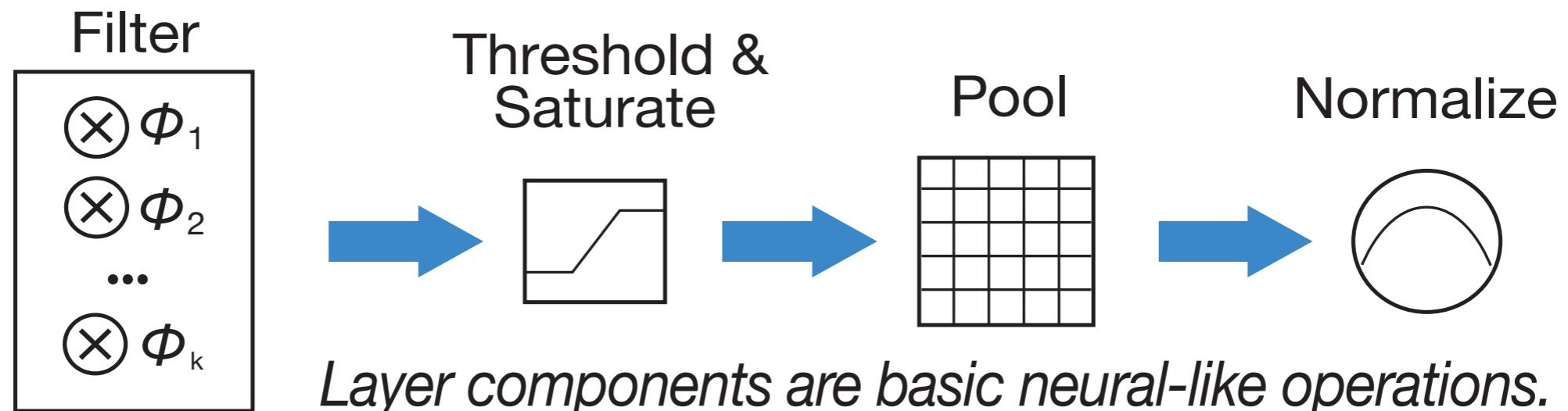


from Kouh and Poggio (2008)

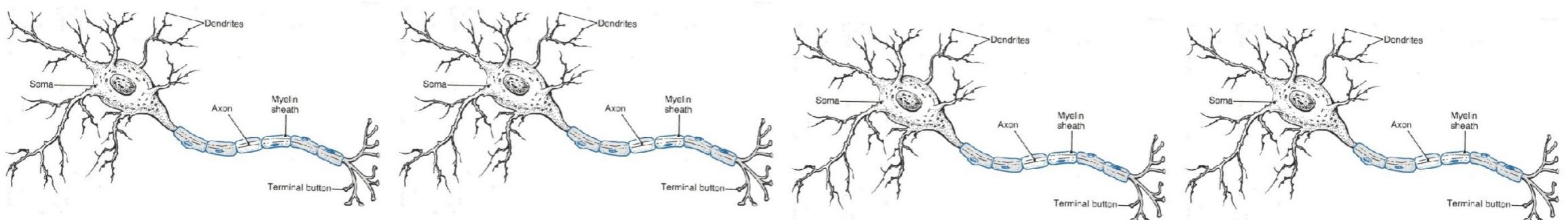
(Actually, if you're running a CNN, you basically **have** to do pooling + downsampling, for memory reasons.)

Linear-Nonlinear Operations

- Linear-Nonlinear neurally-plausible **basic operations** within layer

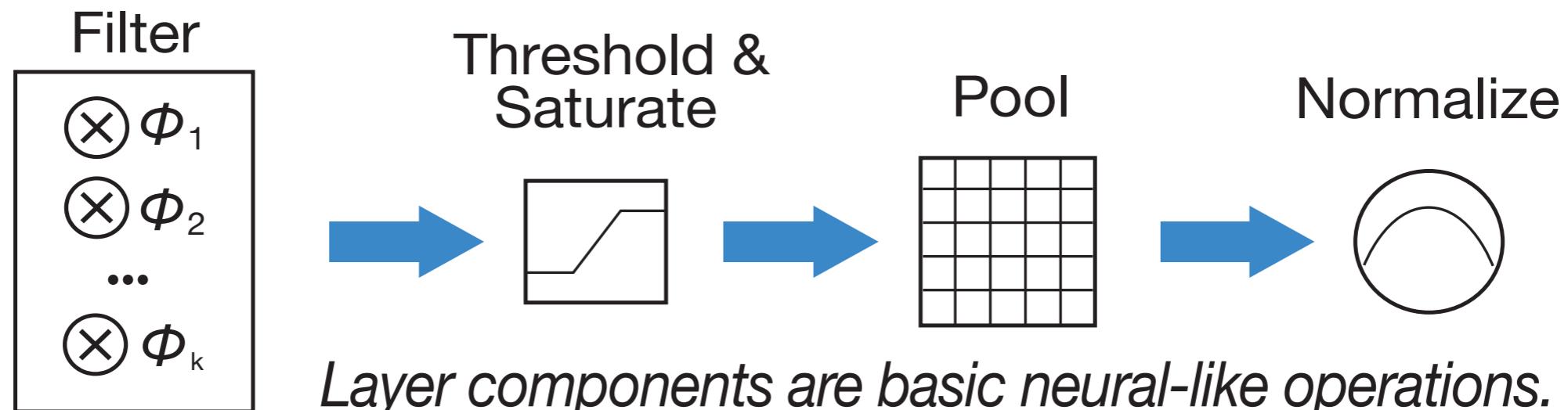


Layer components are basic neural-like operations.



Linear-Nonlinear Operations

- Linear-Nonlinear neurally-plausible **basic operations** within layer



neuro:

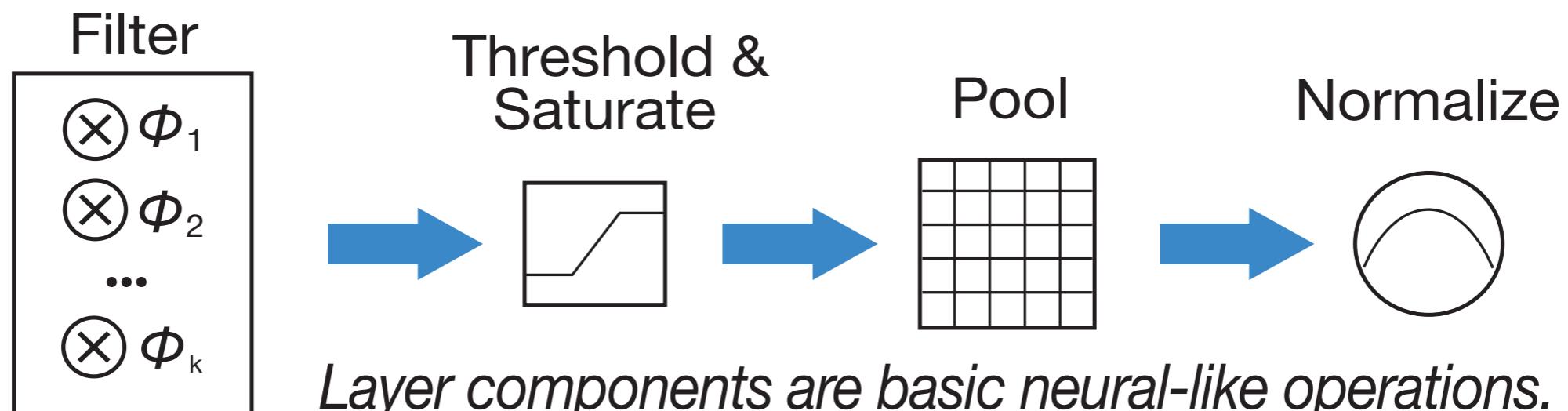
synaptic
weights
patterns

data:

untangling
through
dimension
expansion

Linear-Nonlinear Operations

- Linear-Nonlinear neurally-plausible **basic operations** within layer



neuro:

synaptic
weights
patterns

data:

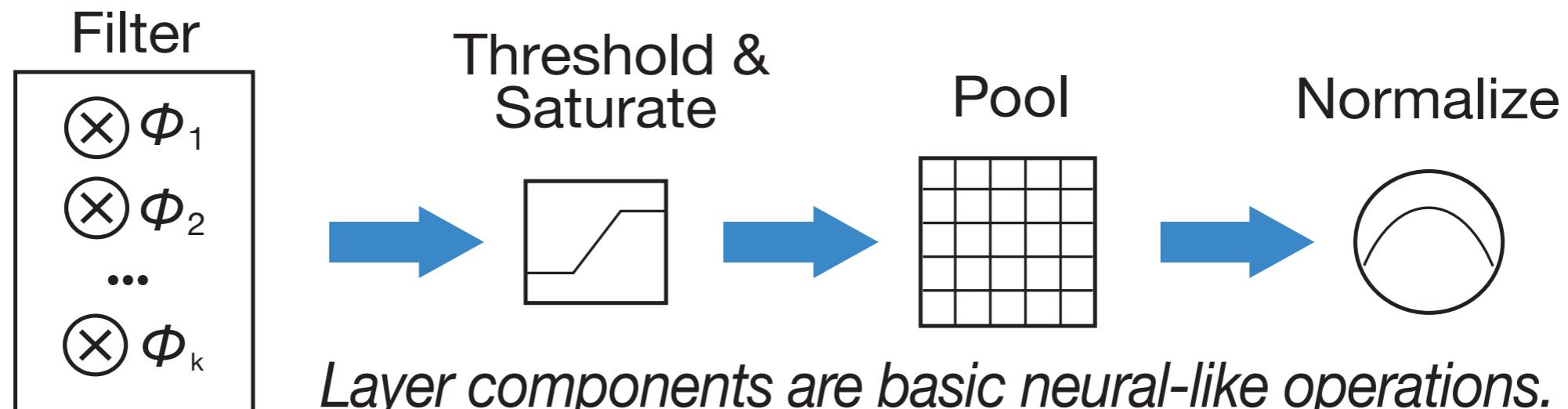
untangling
through
dimension
expansion

single-unit
activations

“AND” operation
by limiting dynamic
range

Linear-Nonlinear Operations

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Layer components are basic neural-like operations.

neuro:

synaptic
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untangling
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single-unit
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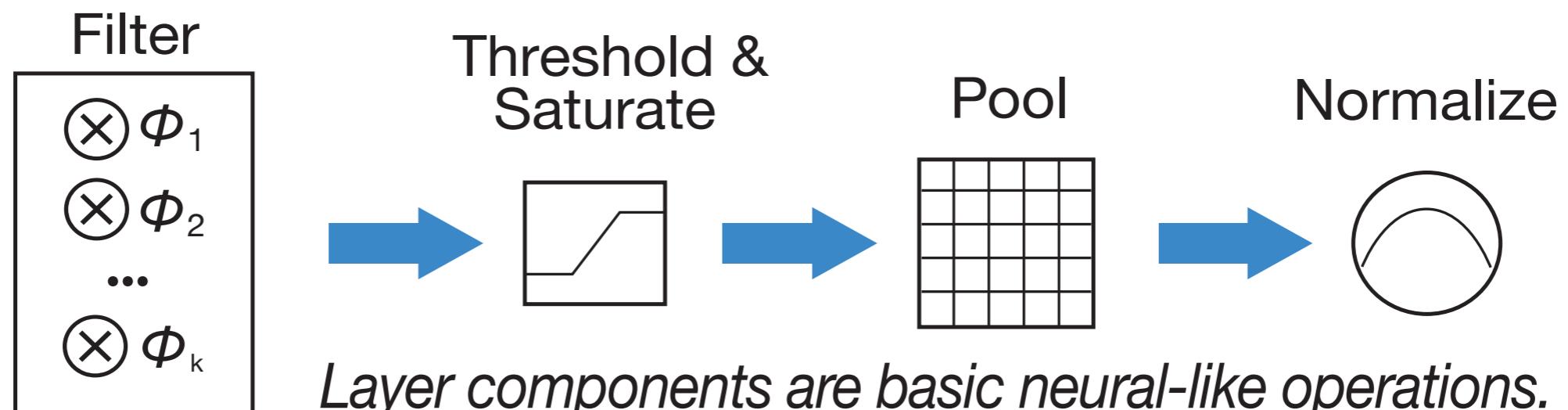
complex cells

“AND” operation
by limiting dynamic
range

adding robustness
by dimension
reduction

Linear-Nonlinear Operations

- Linear-Nonlinear neurally-plausible **basic operations** within layer

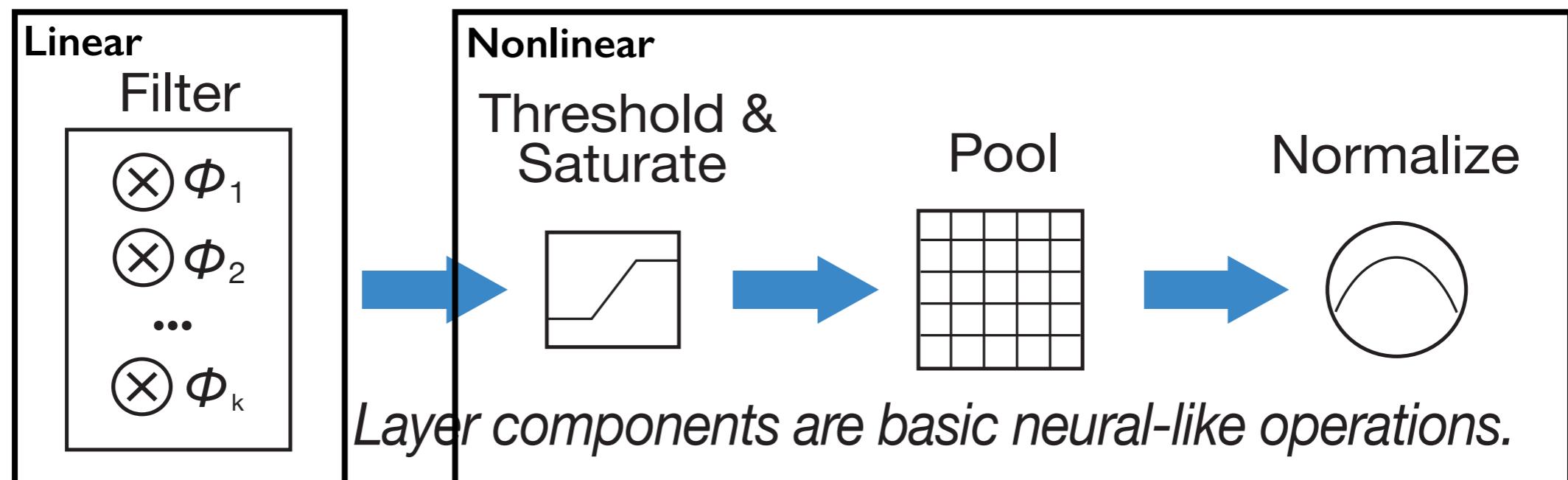


Layer components are basic neural-like operations.

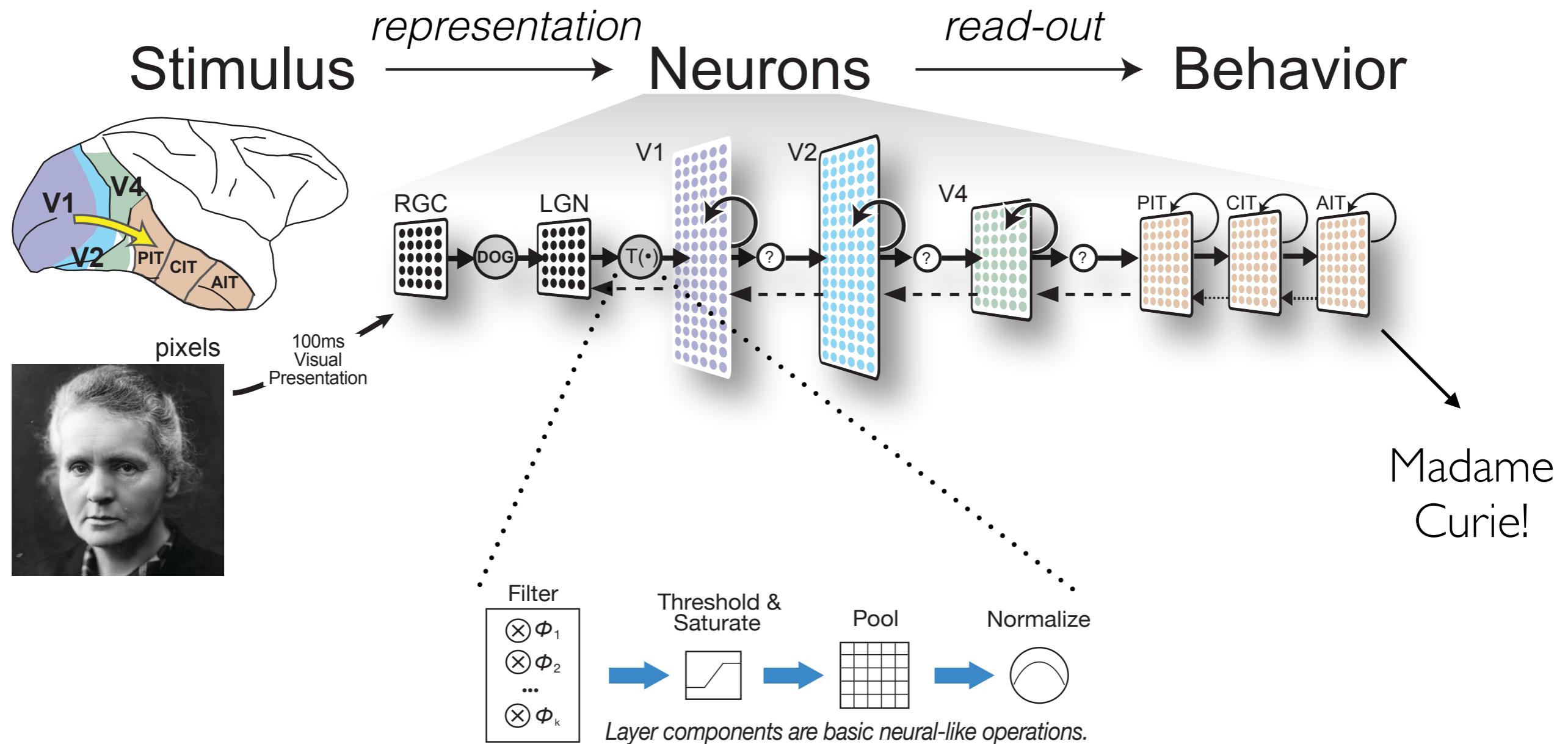
neuro:	synaptic weights patterns	single-unit activations	complex cells	competitive inhibition
data:	untangling through dimension expansion	“AND” operation by limiting dynamic range	adding robustness by dimension reduction	put results back into standard range

Linear-Nonlinear Operations

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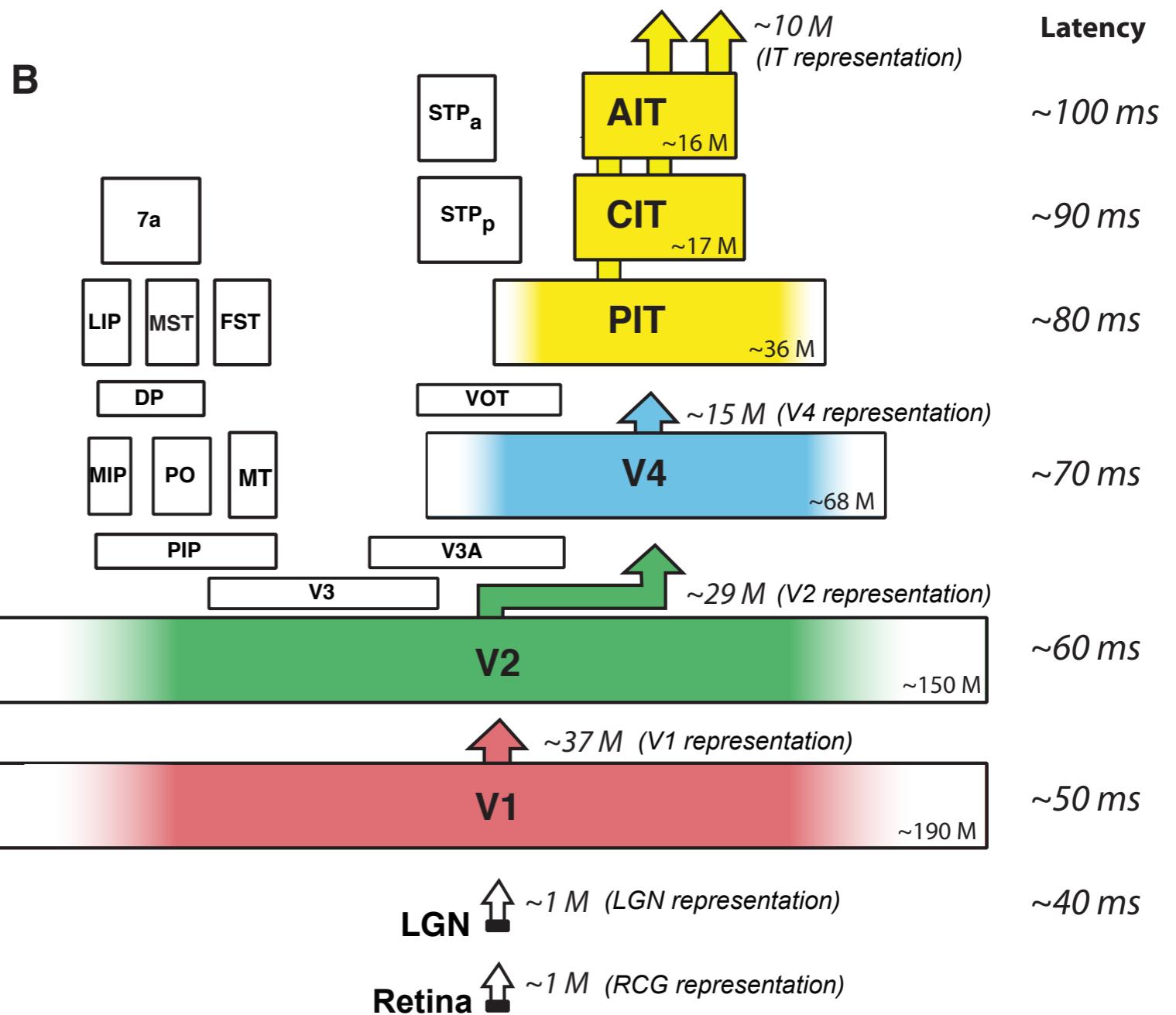


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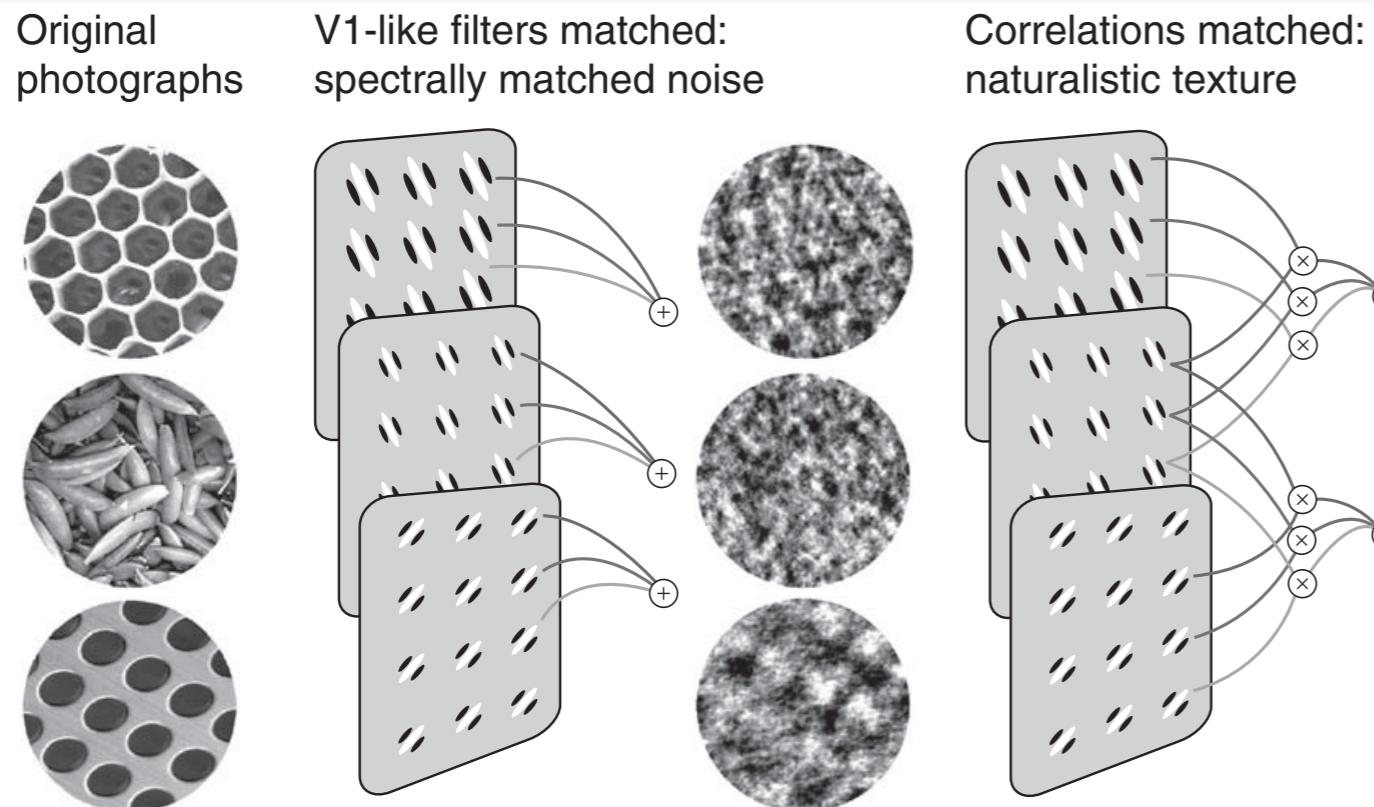


Linear-Nonlinear neurally-plausible **basic operations** within layer

You are here.



Area V2 (first cortical area after V1):



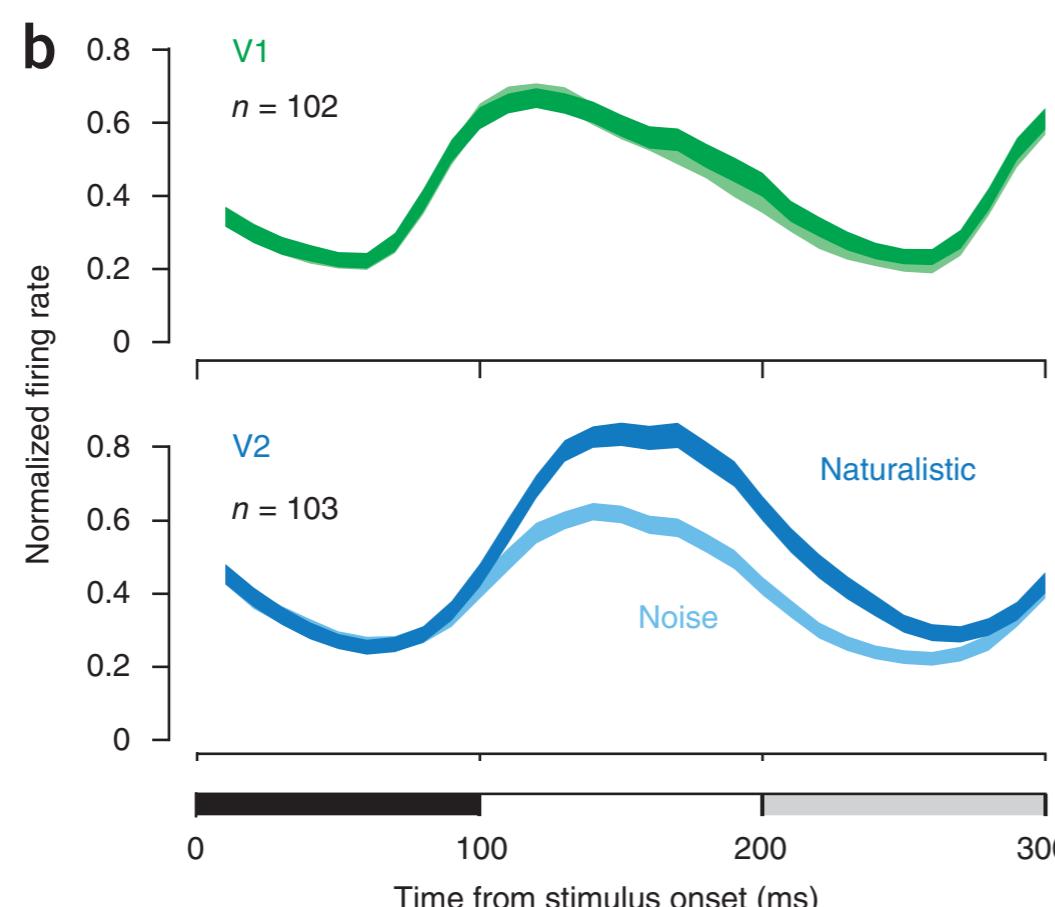
Eero Simoncelli



Tony Movshon



Jeremy Freeman

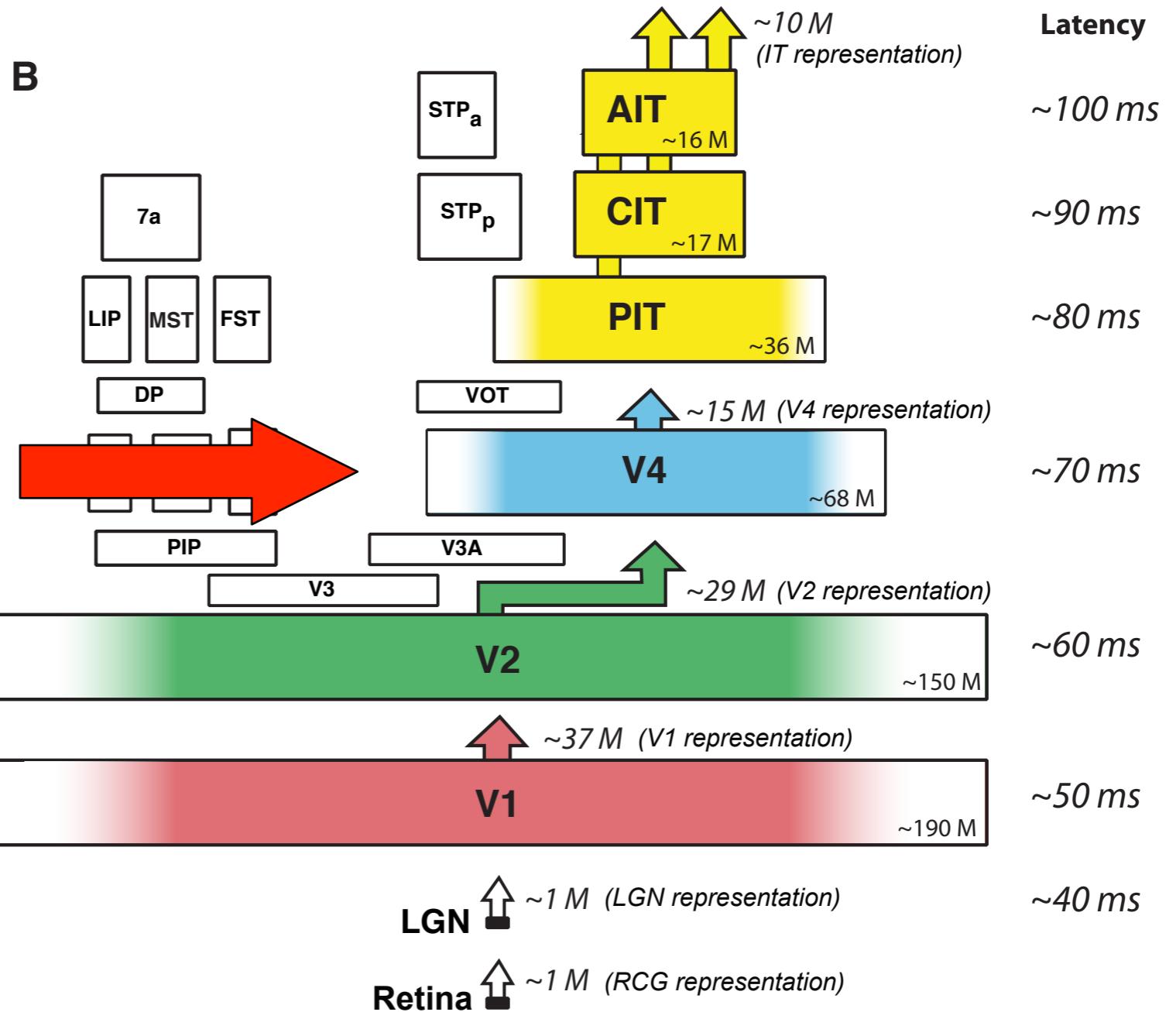


Interpretation:

- V2 neurons apply “and-like” operators on V1 outputs
- those “ands” are tuned toward natural co-occurring V1 statistics

So, maybe a hierarchically-built sparse auto-encoding in a 2-layer model with max pooling??

You are here.



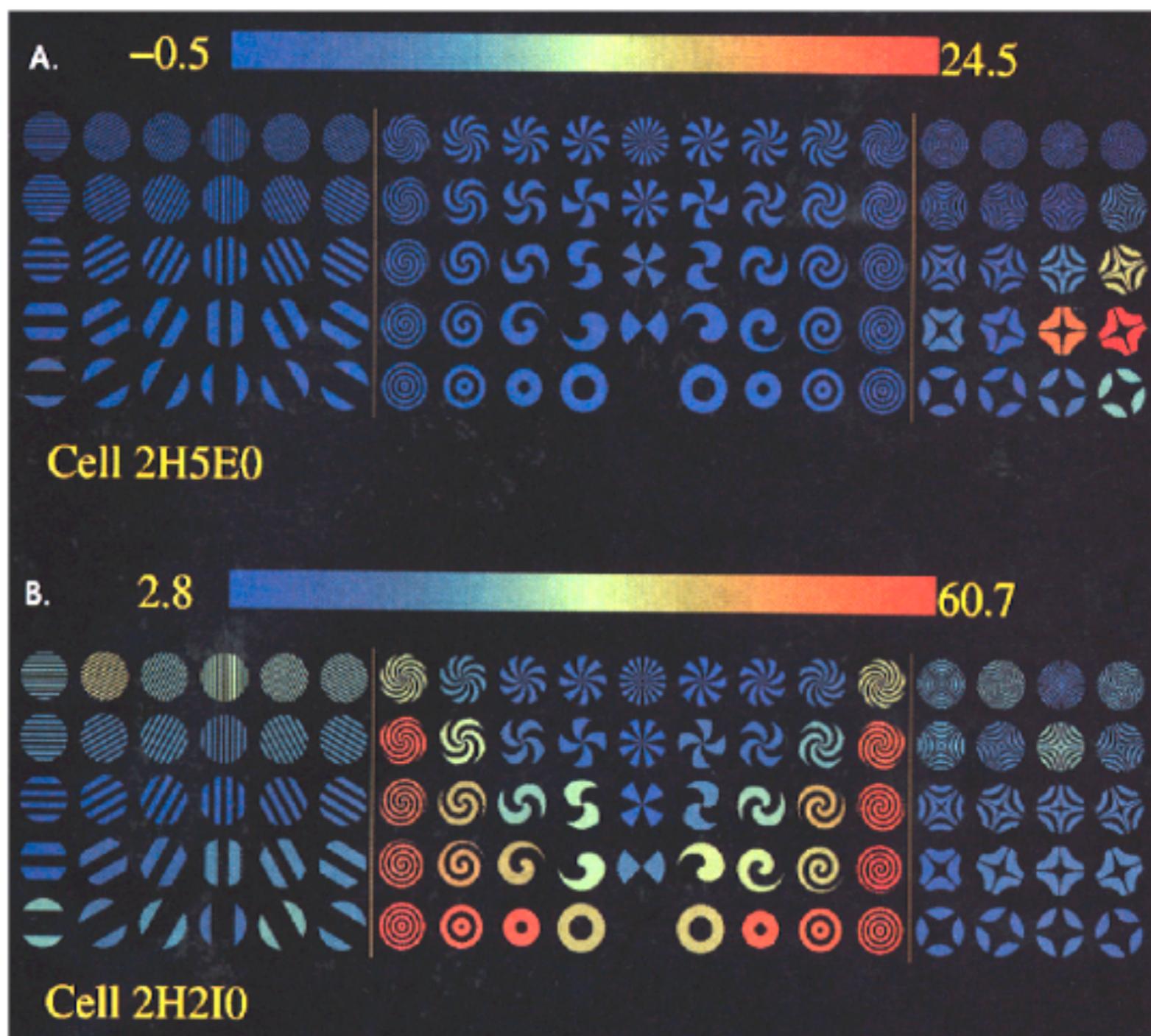
Area V4 (cortical area after V2):

V4 Responses to Non-Cartesian Gratings

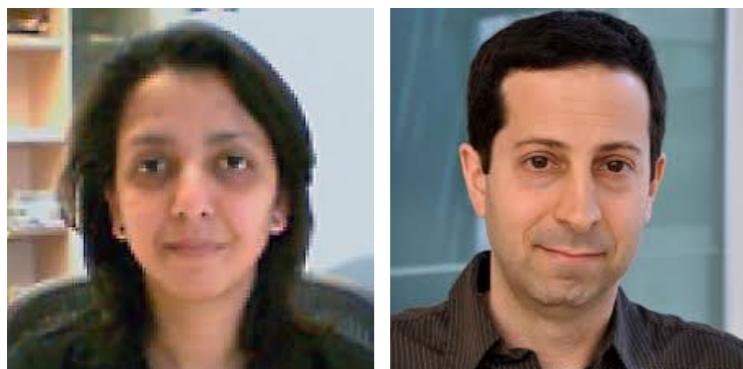
Gallant et al. 1996



Jack Gallant



Area V4 (cortical area after V2):



Anitha Pasupathy

Scott Brincat



Ed Connor

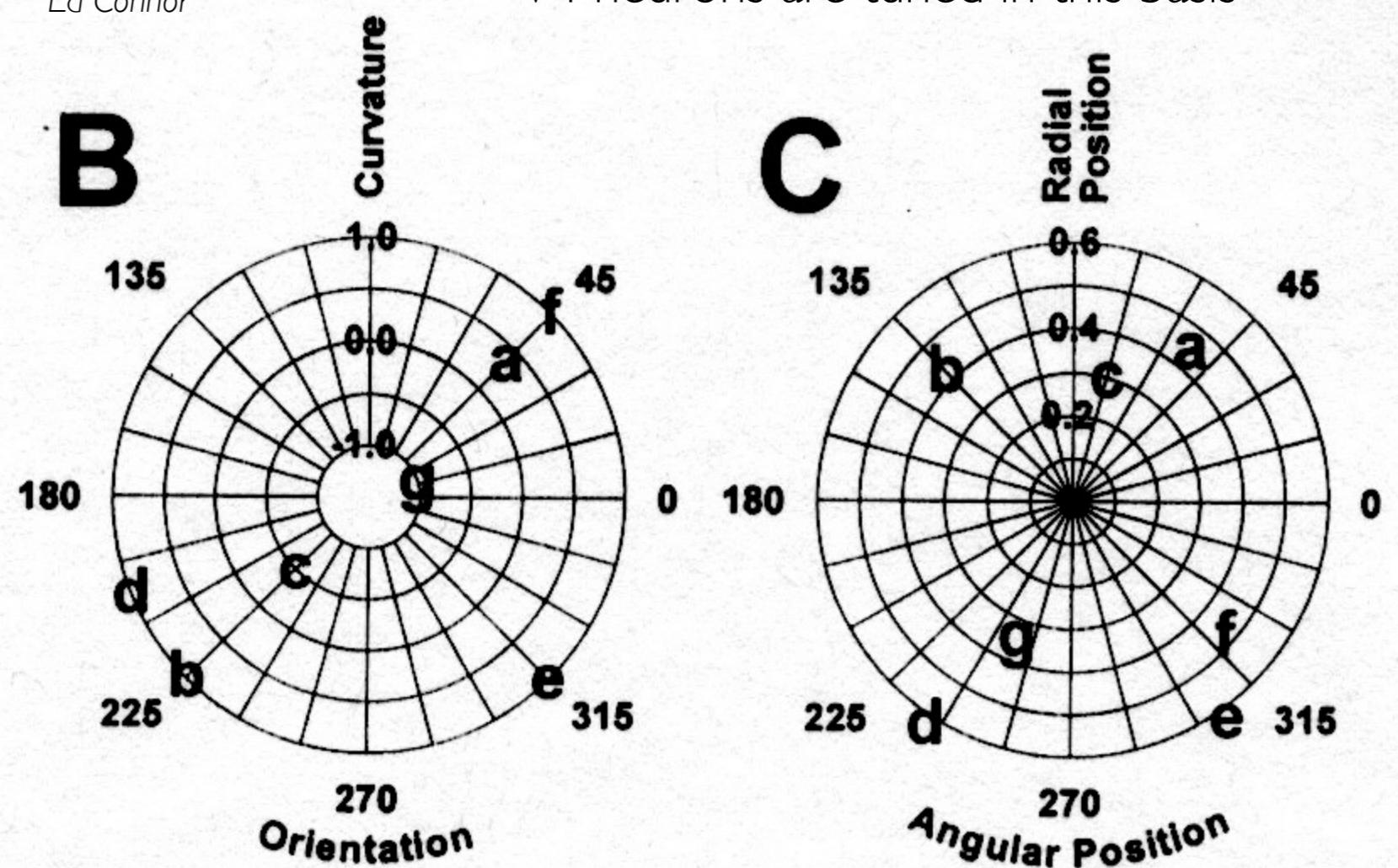
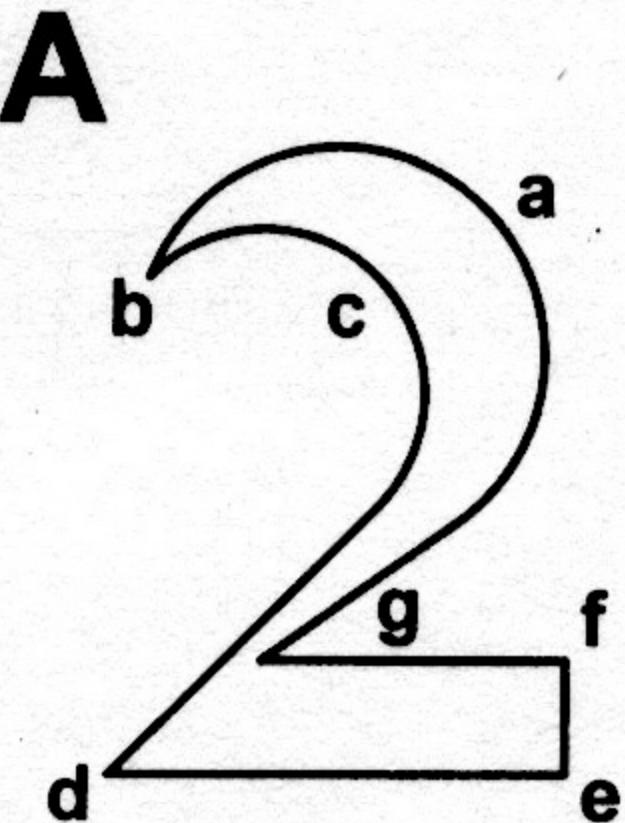
Make a basis for shapes:

each shape = set of curved elements

each element = (ang position, curvature)

Hypothesis:

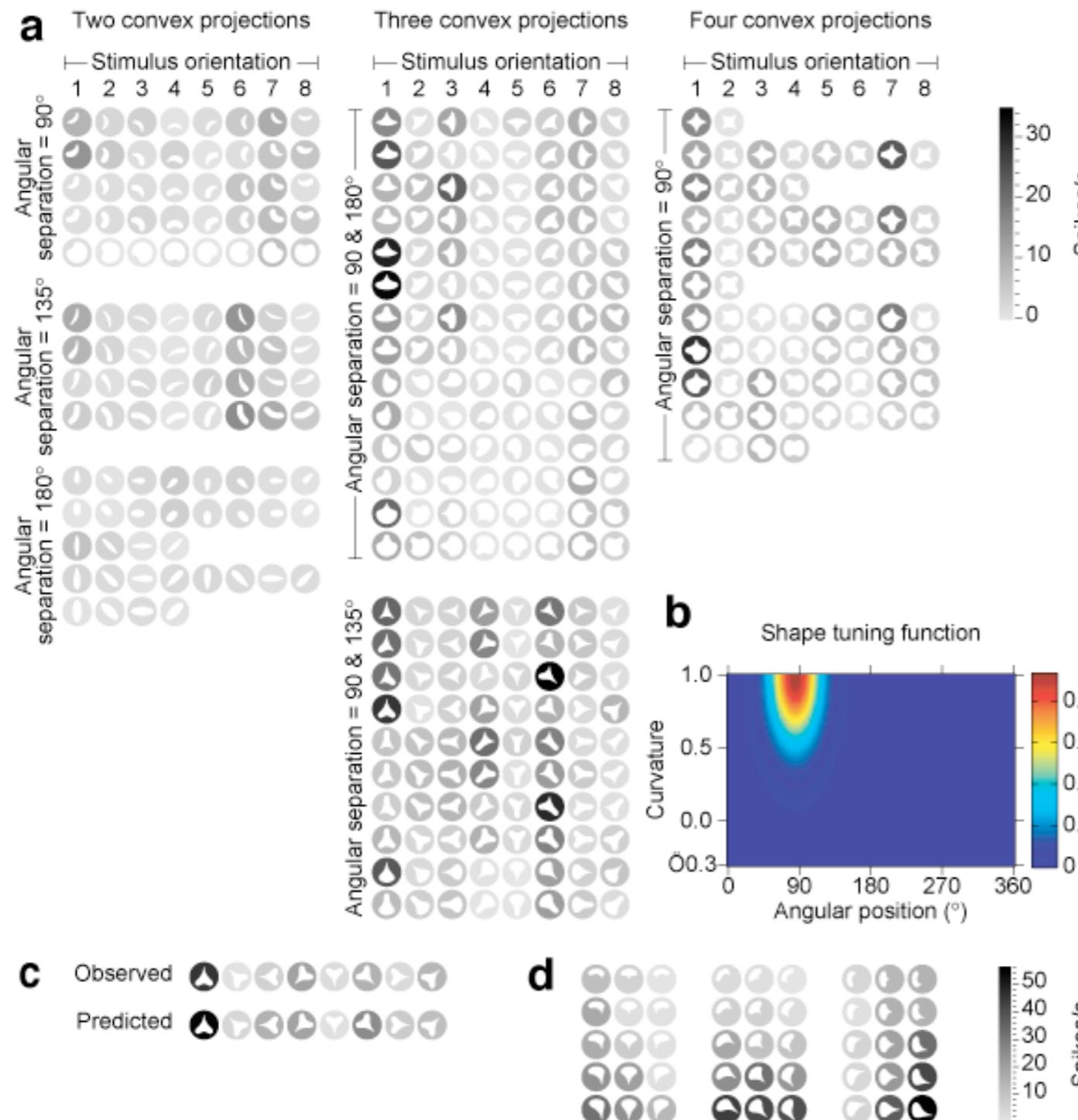
V4 neurons are tuned in this basis



A structural (parts-based) shape-coding scheme based on contour fragments. *A*, The example shape, a bold numeral 2, can be decomposed into contour fragments (*a-g*) with different curvatures, orientations, and positions. *B*, The curvature and orientation of each contour fragment is plotted on a 2-D domain. *C*, The positions of the contour fragments (relative to the object center) are plotted on a 2-D domain. Together, plots *B* and *C* represent a 4-D domain for describing contour fragments.

What shape features drive V4 response?

Adapted from C.E. Connor



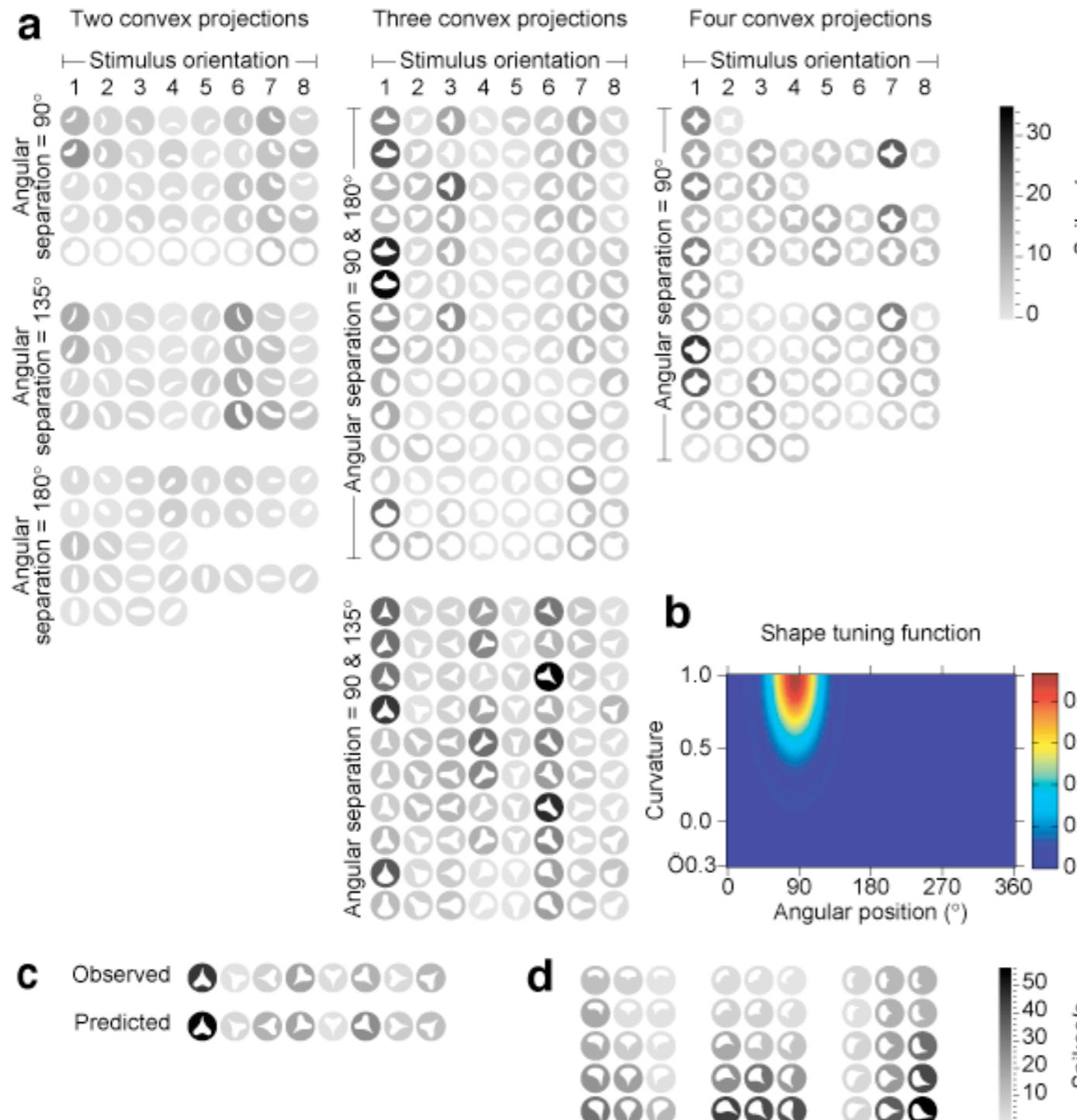
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Pasupathy and Connor (V4)
Brincat and Connor (PIT)

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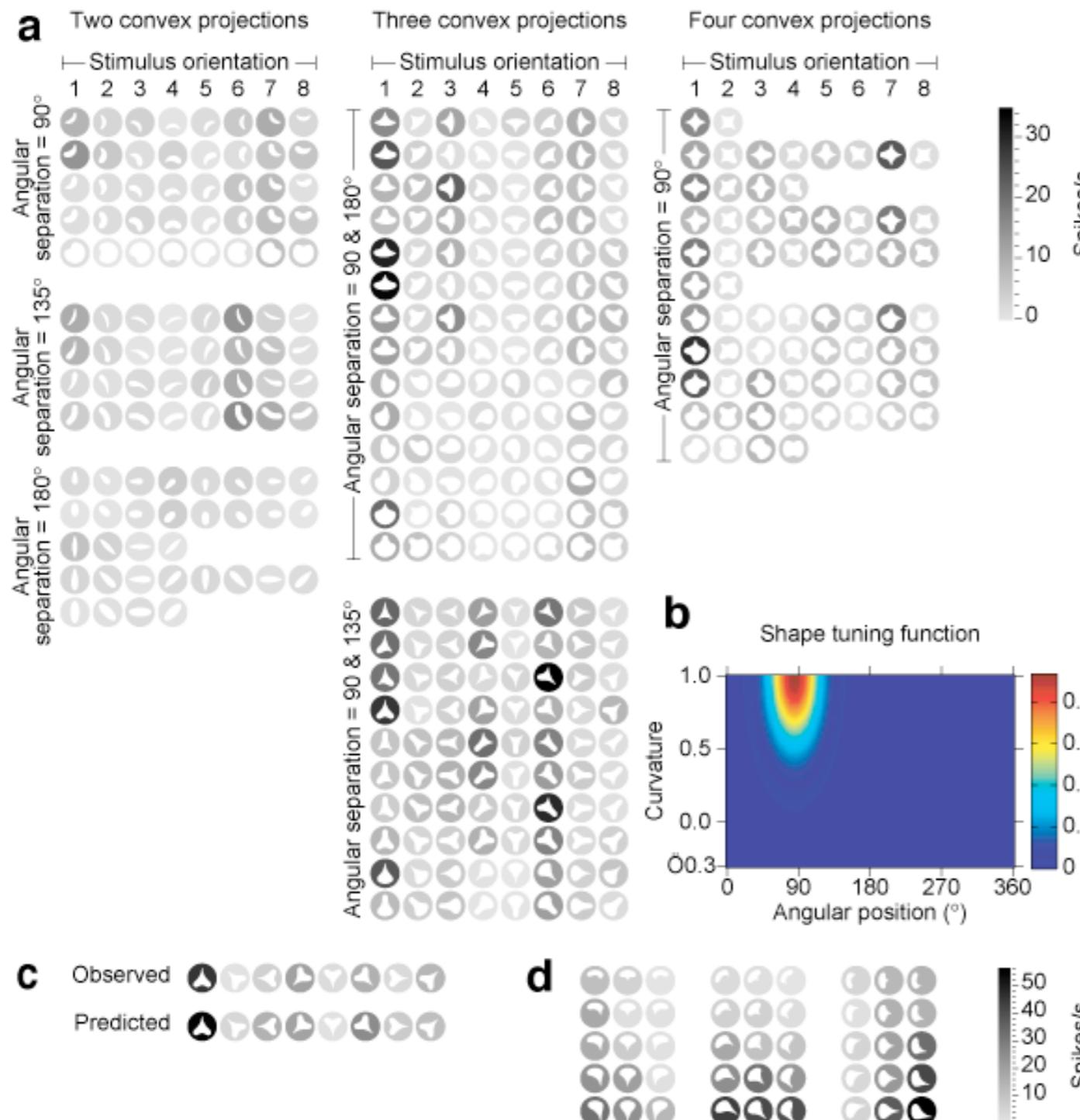
Experimental result:

Hypothesis explains ~50% of the explainable response variance for these types of stimuli

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Hypothesis:

V4 neurons are tuned in this basis

Experimental result:

Hypothesis explains ~50% of the explainable response variance for these types of stimuli

Problem:

No predictions for any other images.

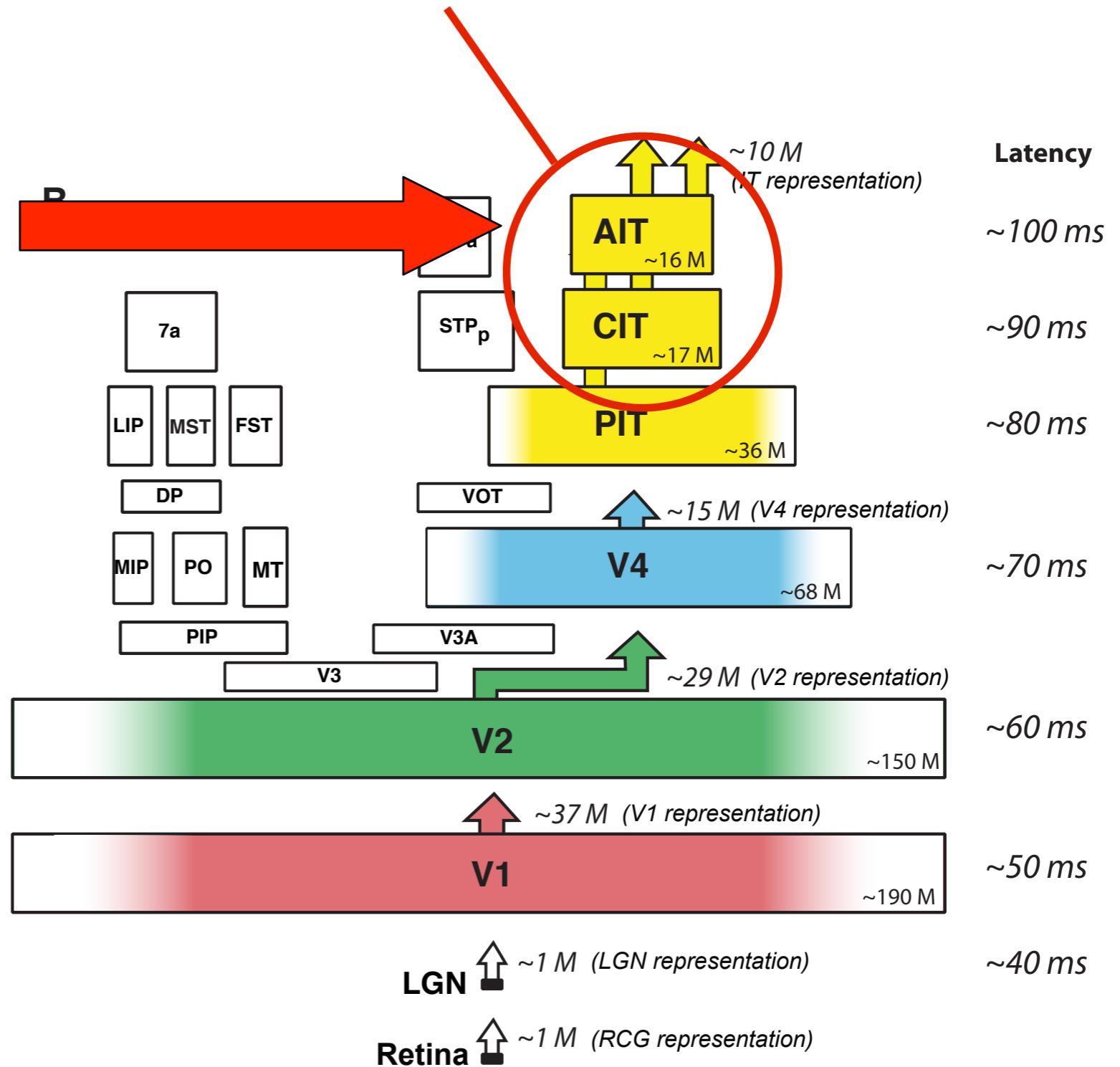
i.e.

is not an “image-computable” model

Pasupathy and Connor (V4)
Brincat and Connor (PIT)

You are here.

“IT” (Inferior temporal cortex)



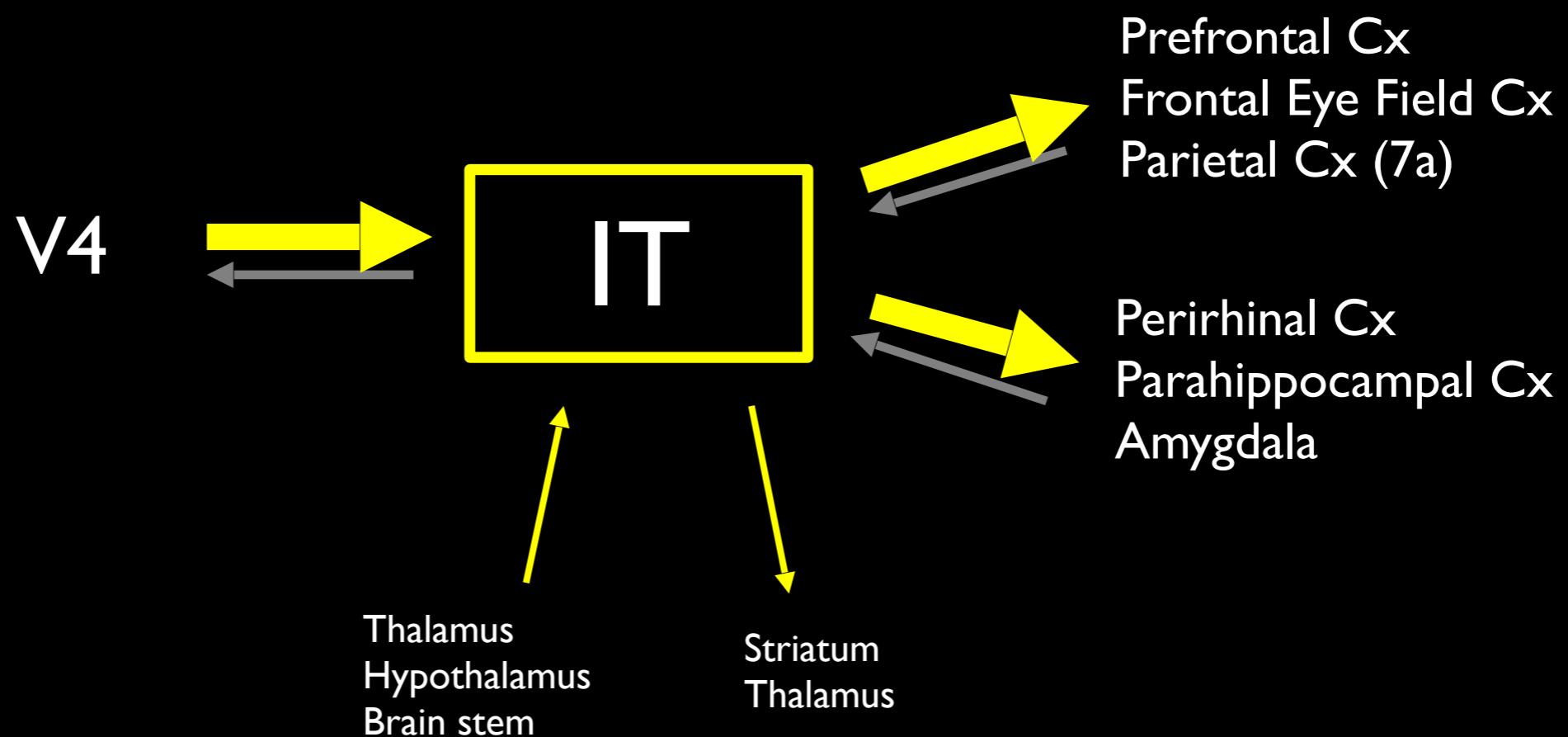
IT statistics (rhesus monkey)

~ 7.7 cm²

~ 8% of neocortex (~ 15% of visual cortex)

~ 90 million neurons

Subregions: (PIT, CIT, AIT) (TEO, TE)



Stimulus selectivity in inferotemporal cortex

Gross, Rocha-Miranda & Bender 1972



Increasing ability to drive this IT neuron -->

The use of [these] stimuli was begun one day when, having failed to drive a unit with any light stimulus, we waved a hand at the stimulus screen and elicited a very vigorous response from the previously unresponsive neuron...

We then spent the next 12 hr testing various paper cutouts in an attempt to find the trigger feature for this unit. When the entire set of stimuli used were ranked according to the strength of the response that they produced, we could not find a simple physical dimension that correlated with this rank order. However, the rank order of adequate stimuli did correlate with similarity (for us) to the shadow of a monkey hand" (Gross et al., 1972).

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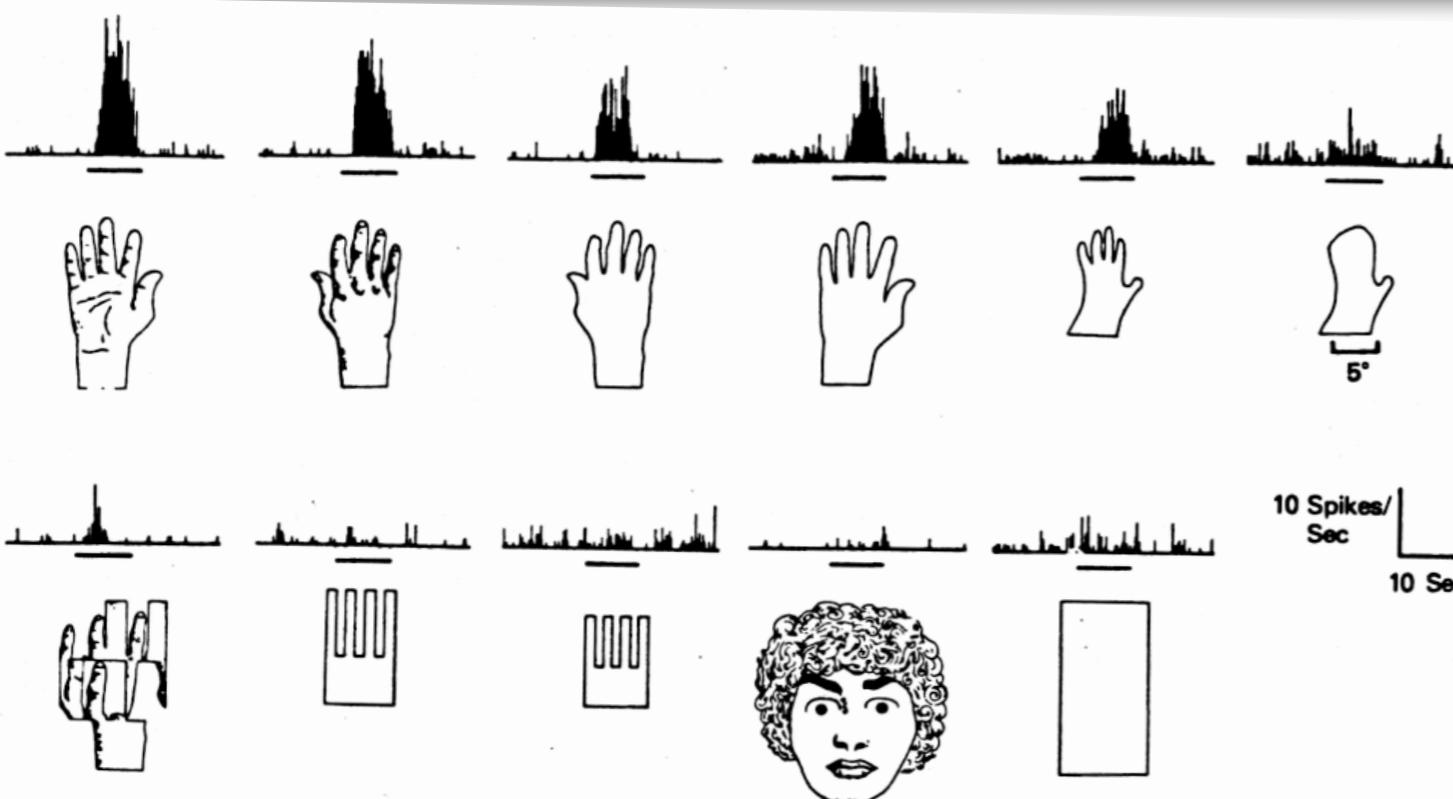
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Joyce Carol Oates!

Charlie Gross

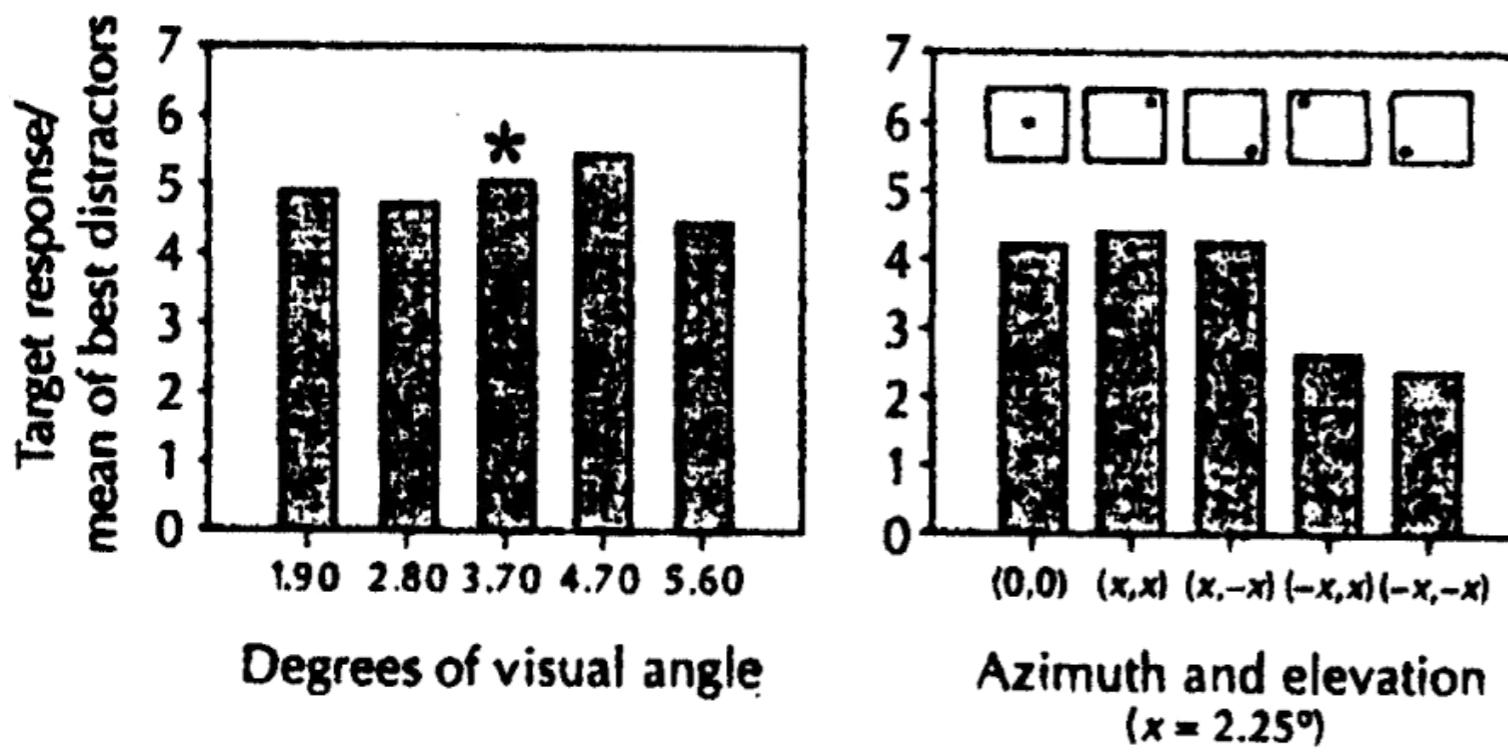


What stimulus feature are IT neurons actually “tuned” to?



Desimone et al. (1984)

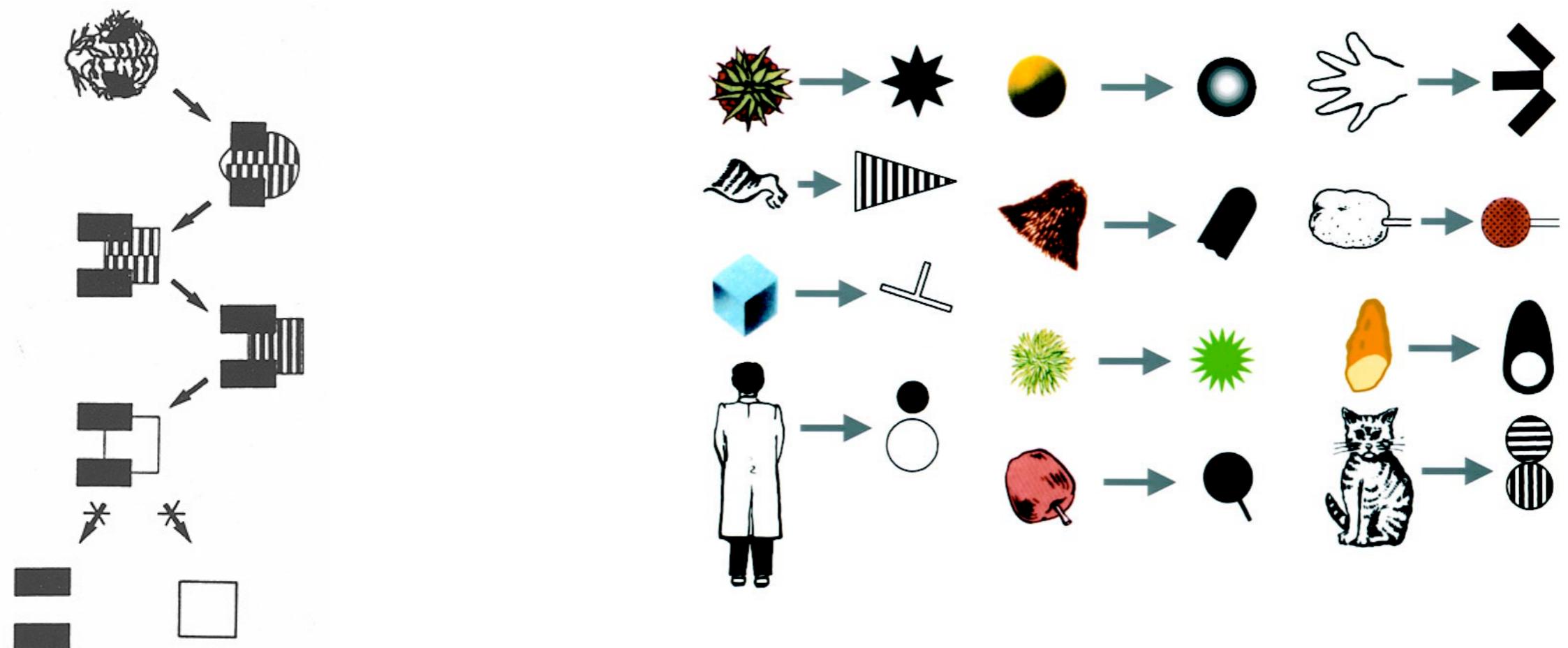
IT neurons can be tuned to specific combinations of features (high “selectivity”)



That selectivity is tolerant to changes in position and size

Logothetis et al. (1995)

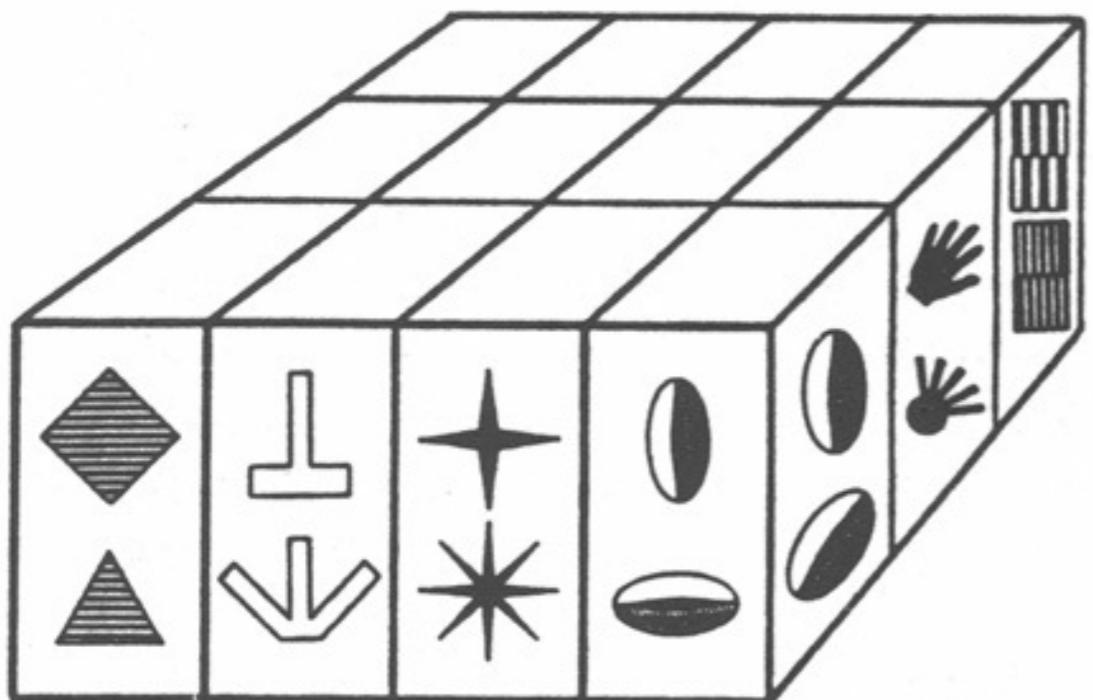
What stimulus feature are IT neurons actually “tuned” to?



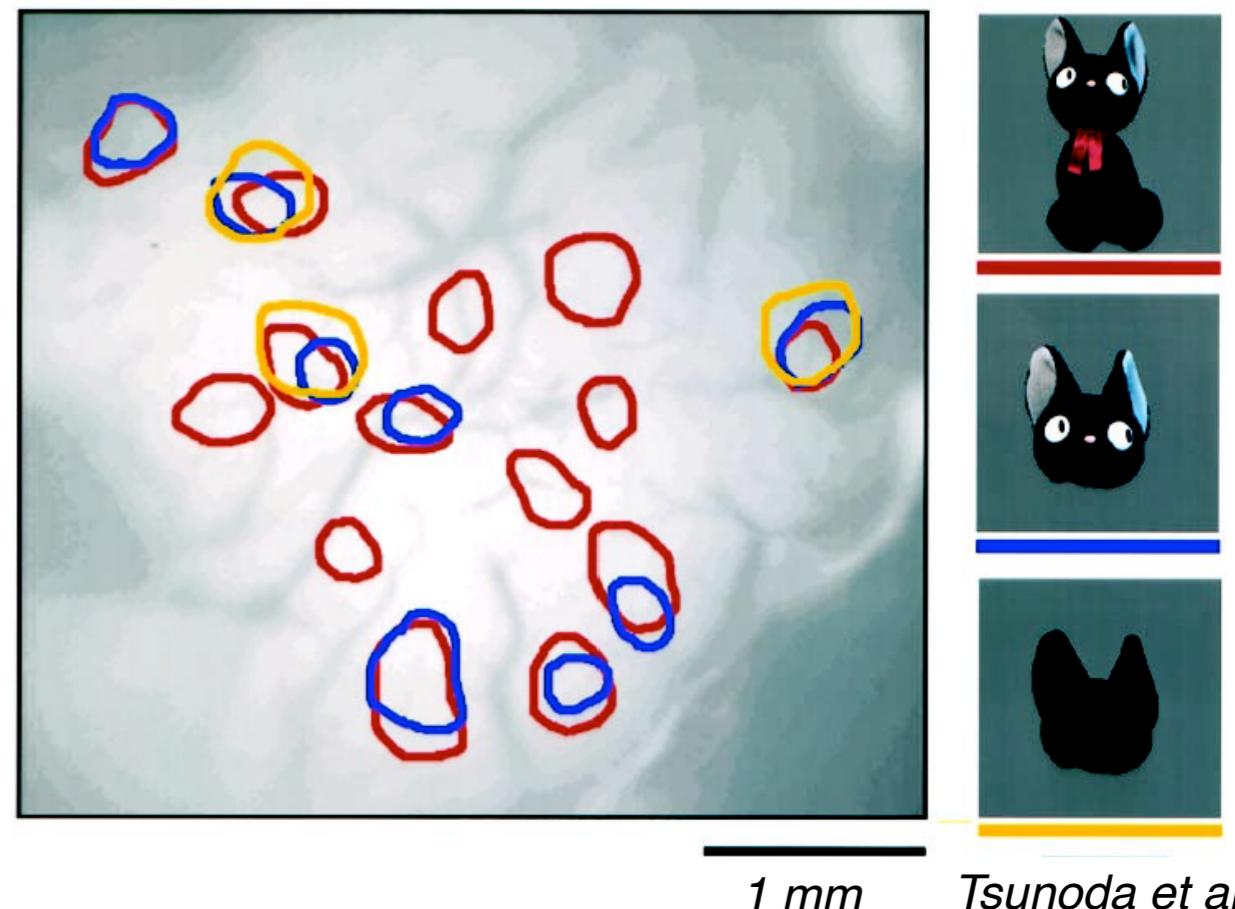
Tanaka et al.



IT has spatial organization at 500 um - 1 mm scale



Tanaka et al.

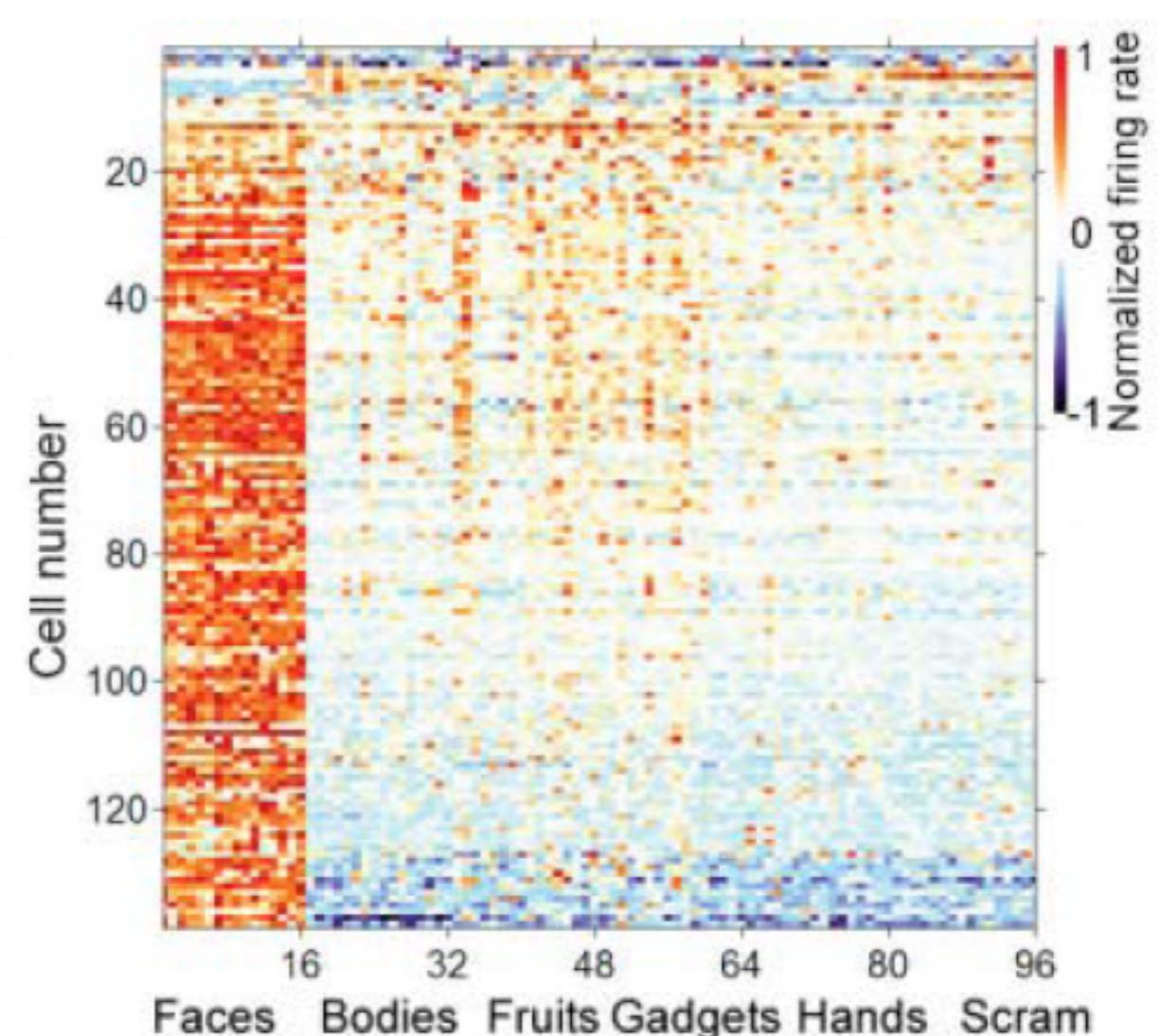
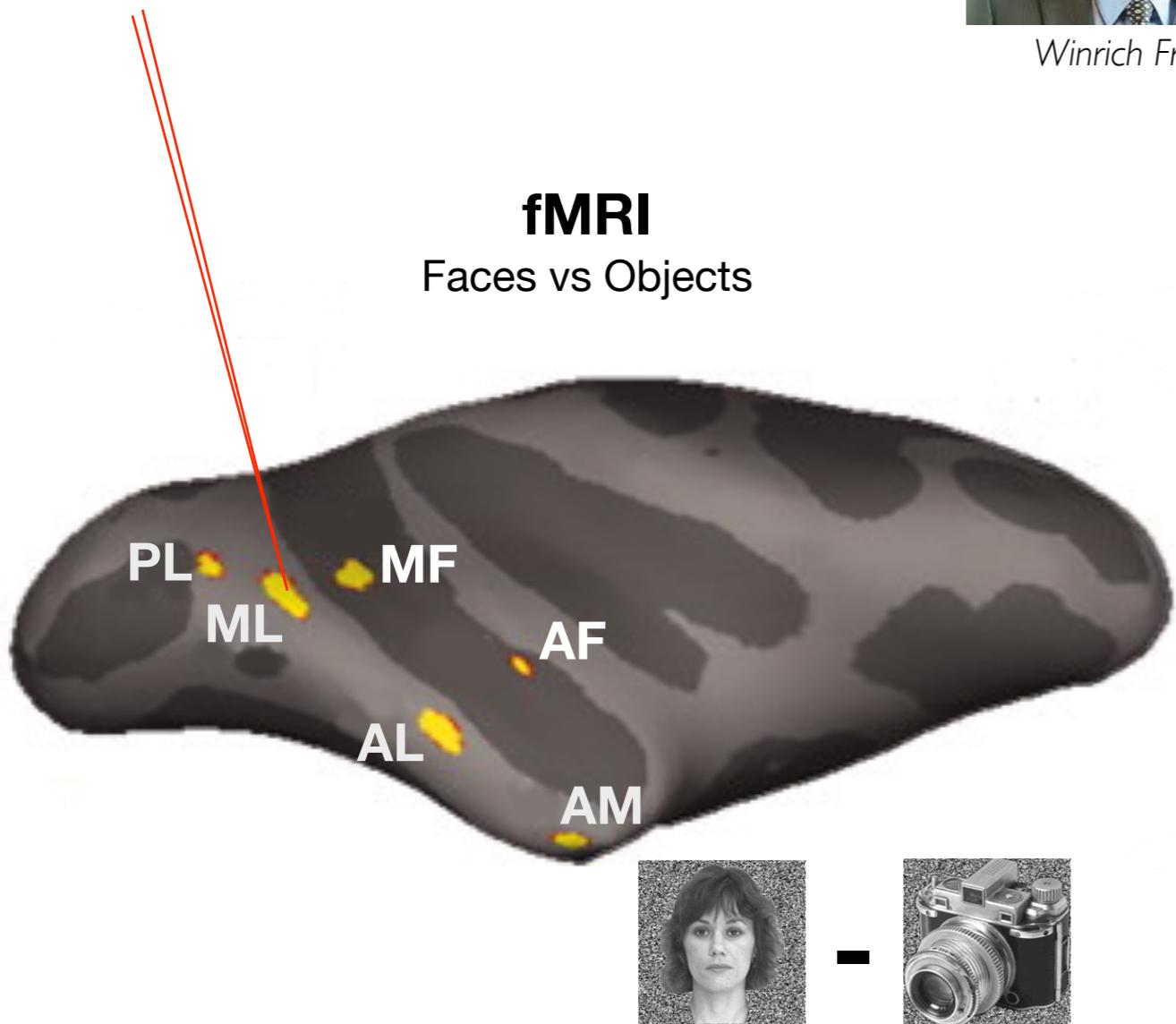


1 mm

Tsunoda et al.

Larger scale (2-6 mm) organization for some image contrasts

Face Patches in IT

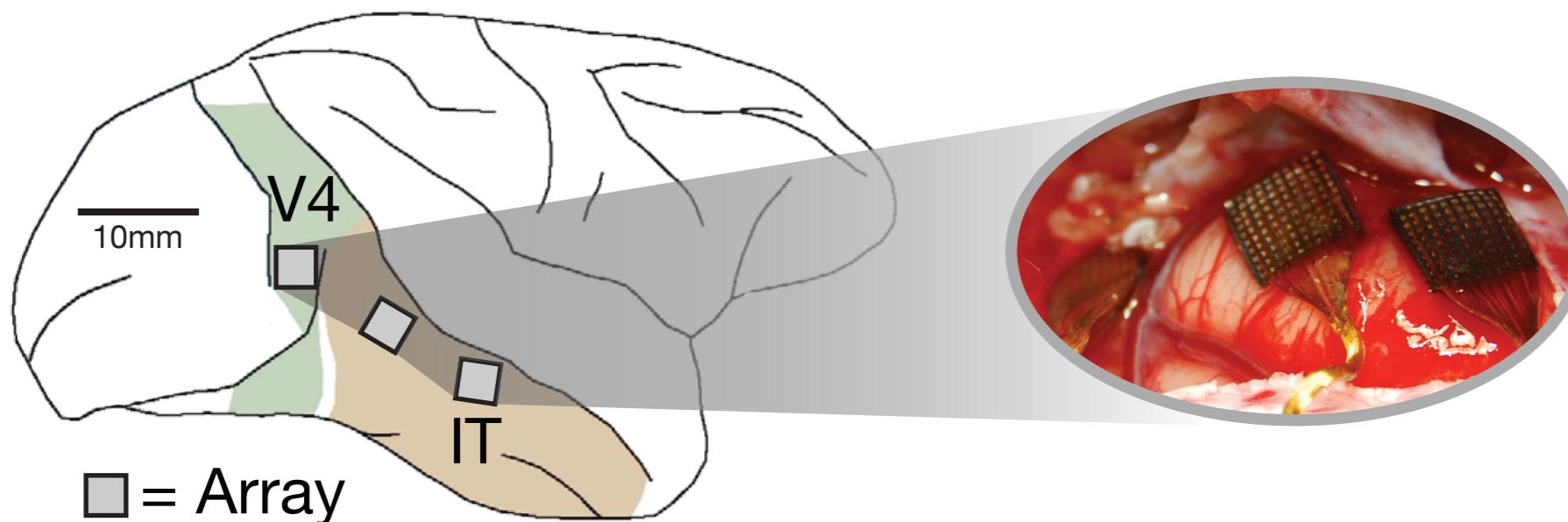


Tsao, Freiwald, and Livingstone used fMRI to reveal a set of face selective regions in macaque IT (aka “face patches”)

Most of the single neurons in these regions showed a preference for frontal faces

Multi-array Electrophysiology Experiment

Multi-array electrophysiology in macaque V4 and IT.



About 300 total sites



Ha Hong



Jim DiCarlo

Multi-array Electrophysiology Experiment

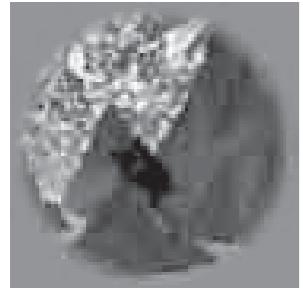
5760 images

64 objects

8 categories

uncorrelated photo backgrounds

Animals



Boats



Cars



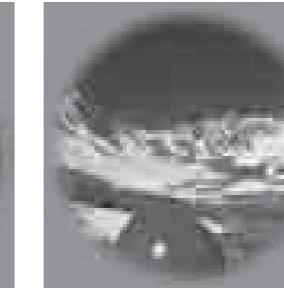
Chairs



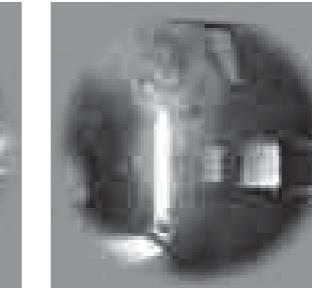
Faces



Fruits



Planes



Tables



Low variation



... 640 images

Medium variation



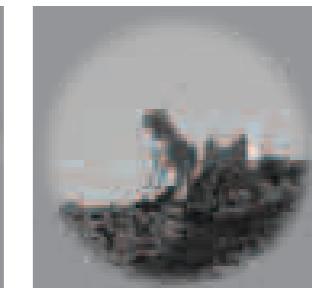
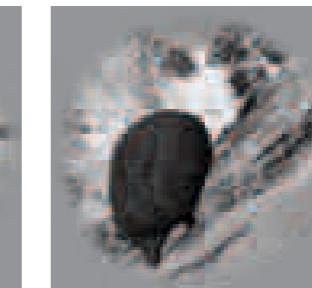
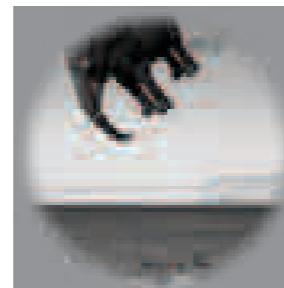
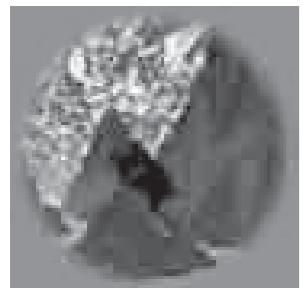
... 2560 images

High variation



... 2560 images

Pose, position, scale, and background variation



Multi-array Electrophysiology Experiment



Multi-array Electrophysiology Experiment



complex, uncorrelated backgrounds **prevent low-level
cheating**
part of what we mean by “complex task”

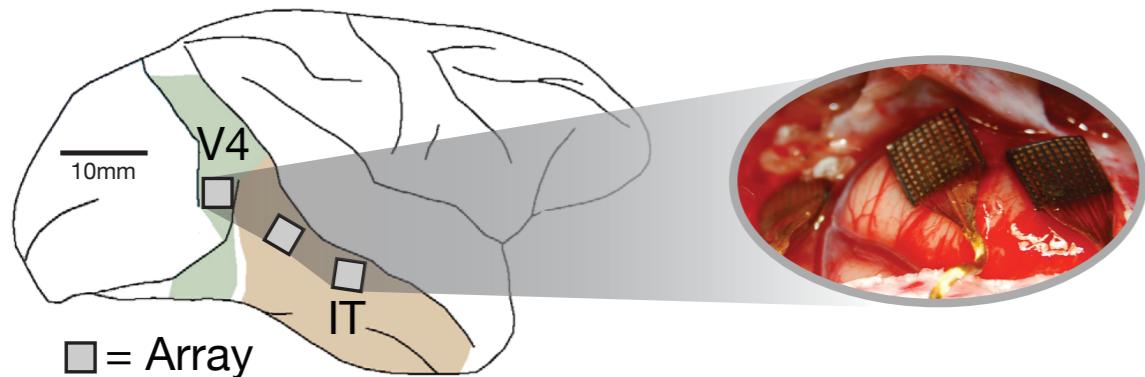
Multi-array Electrophysiology Experiment



Ellie. C. Shay & K. Kar (Winter 2019)

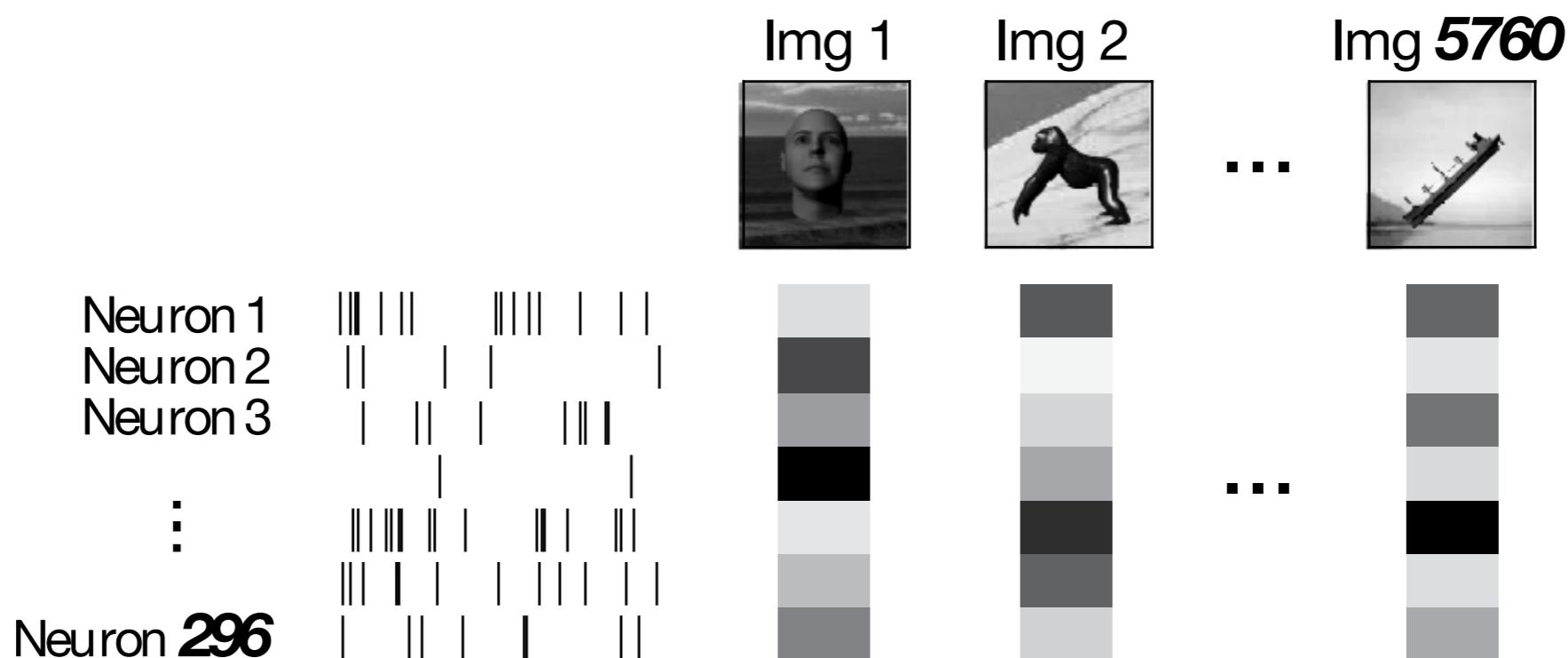
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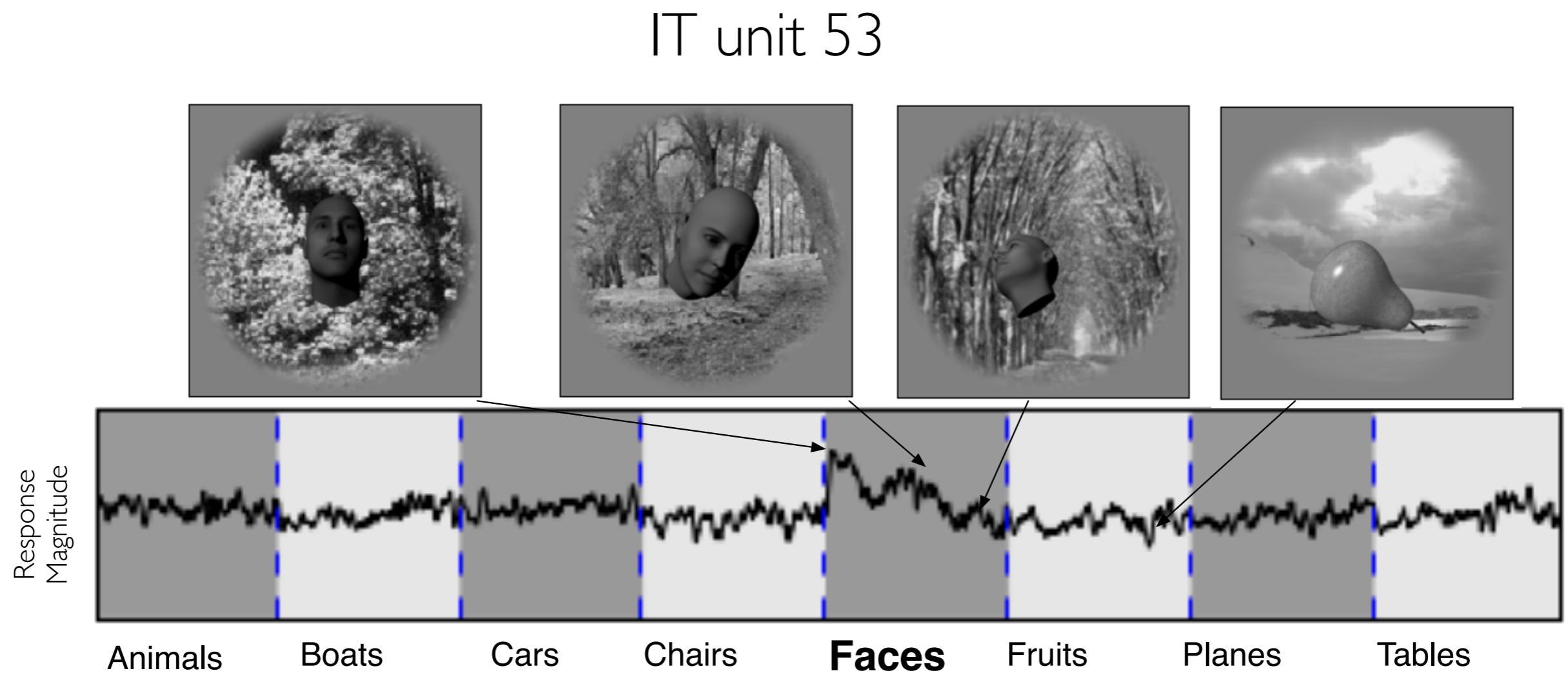
About 300 total sites

Output = Binned spike counts 70ms-170ms post stimulus presentation averaged over 25-50 reps of each image.



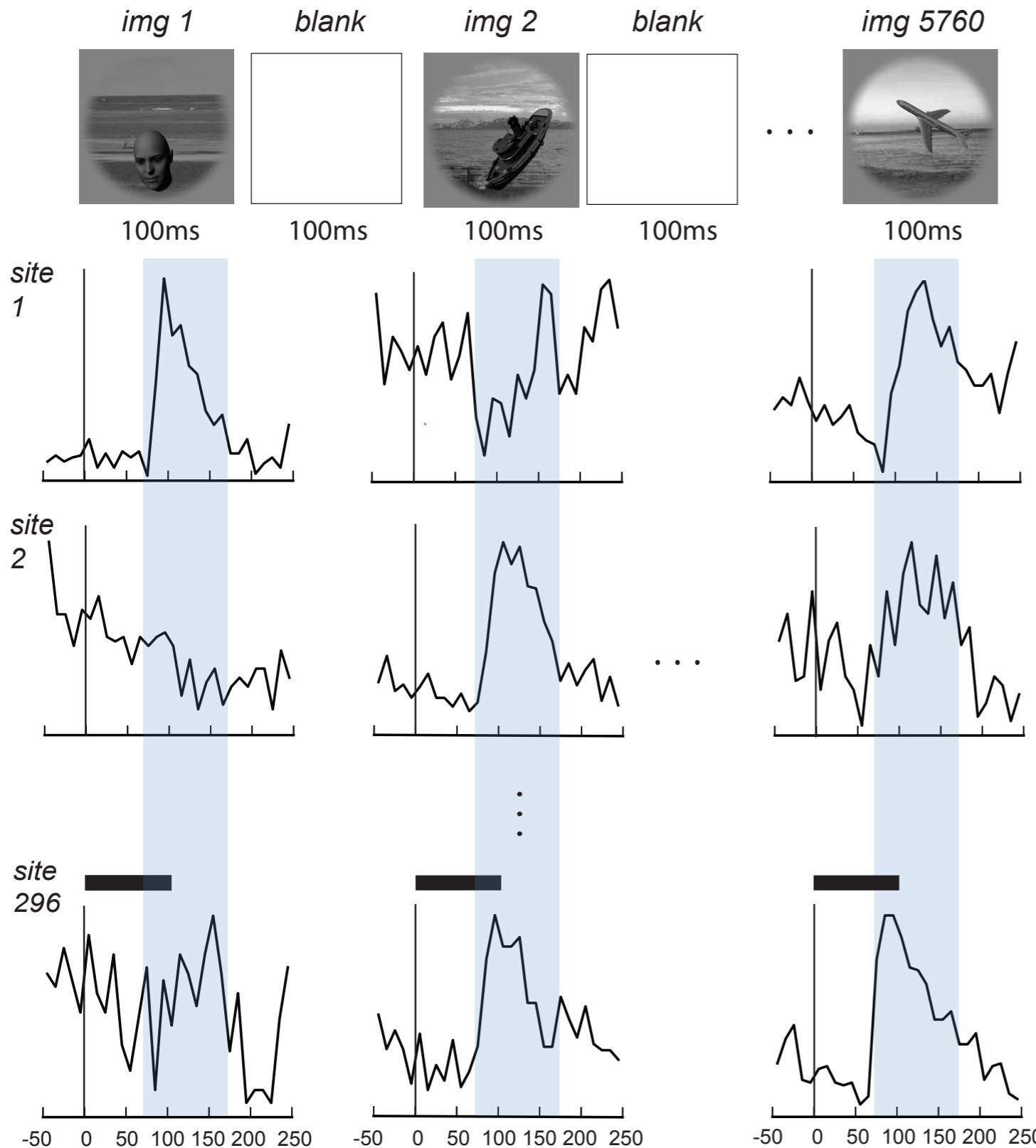
Multi-array Electrophysiology Experiment

Responses to 1600 test images of two example units

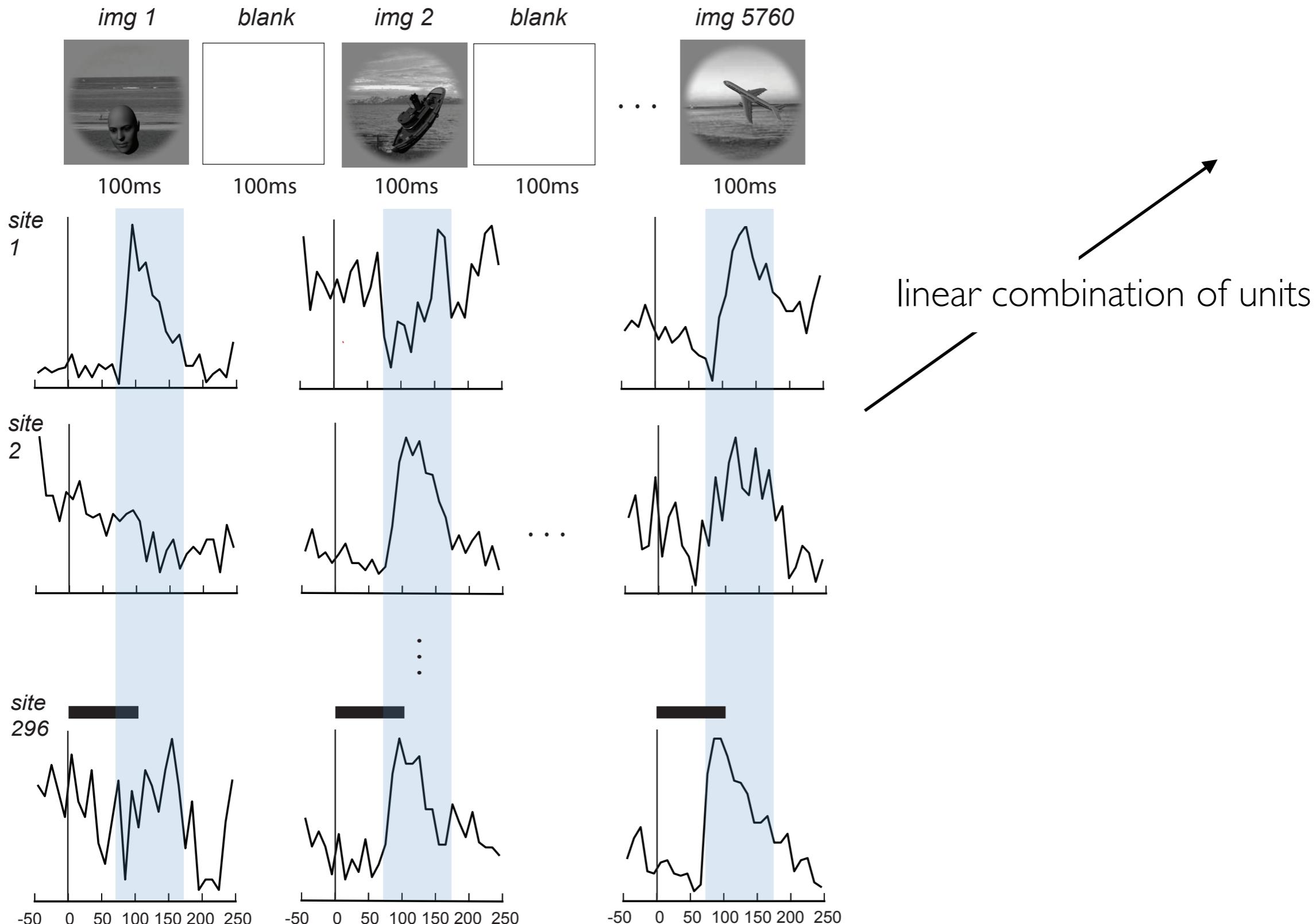


Images sorted first by **category**, then **variation level**.

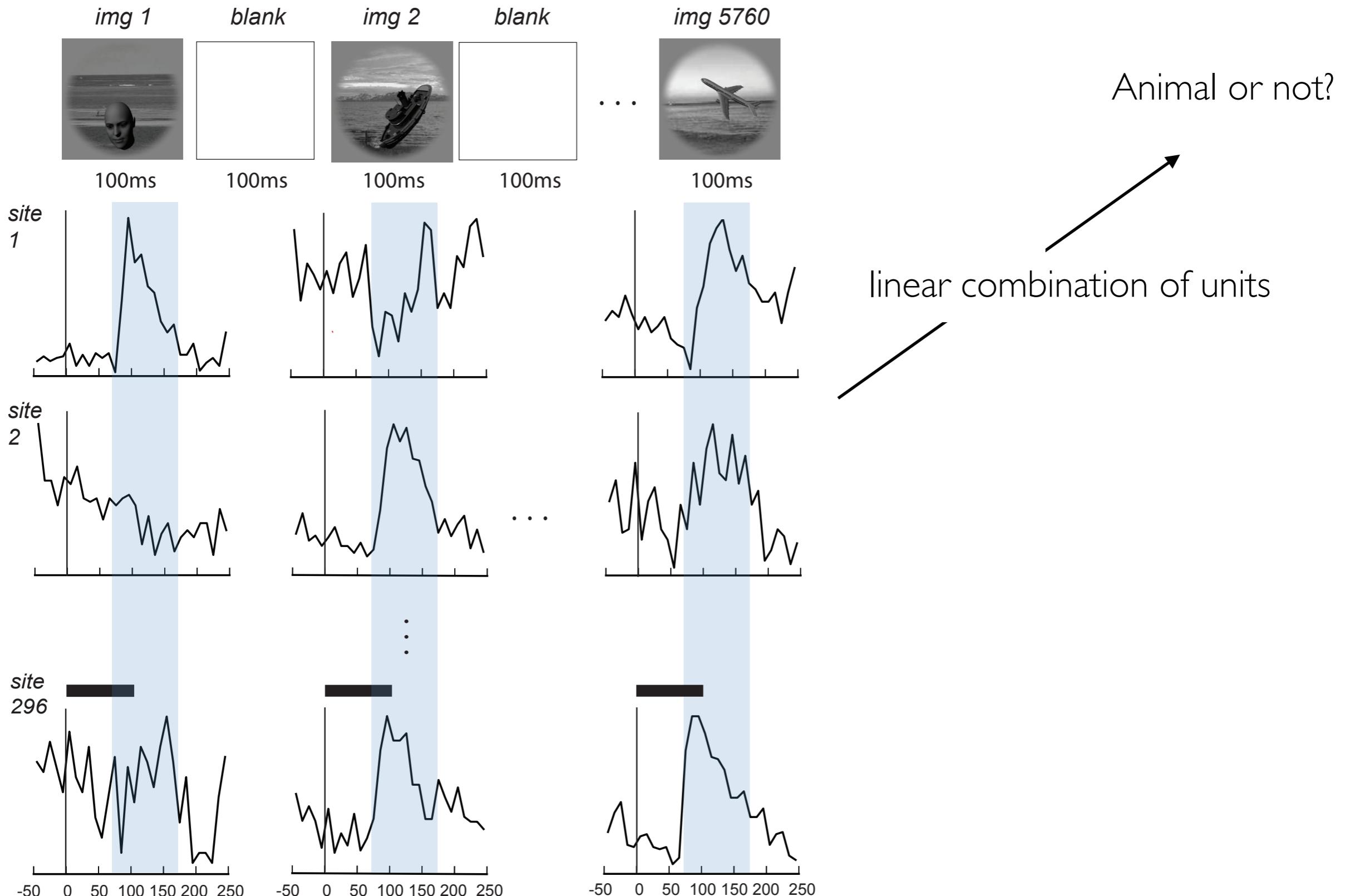
Neural-Behavior Decoding



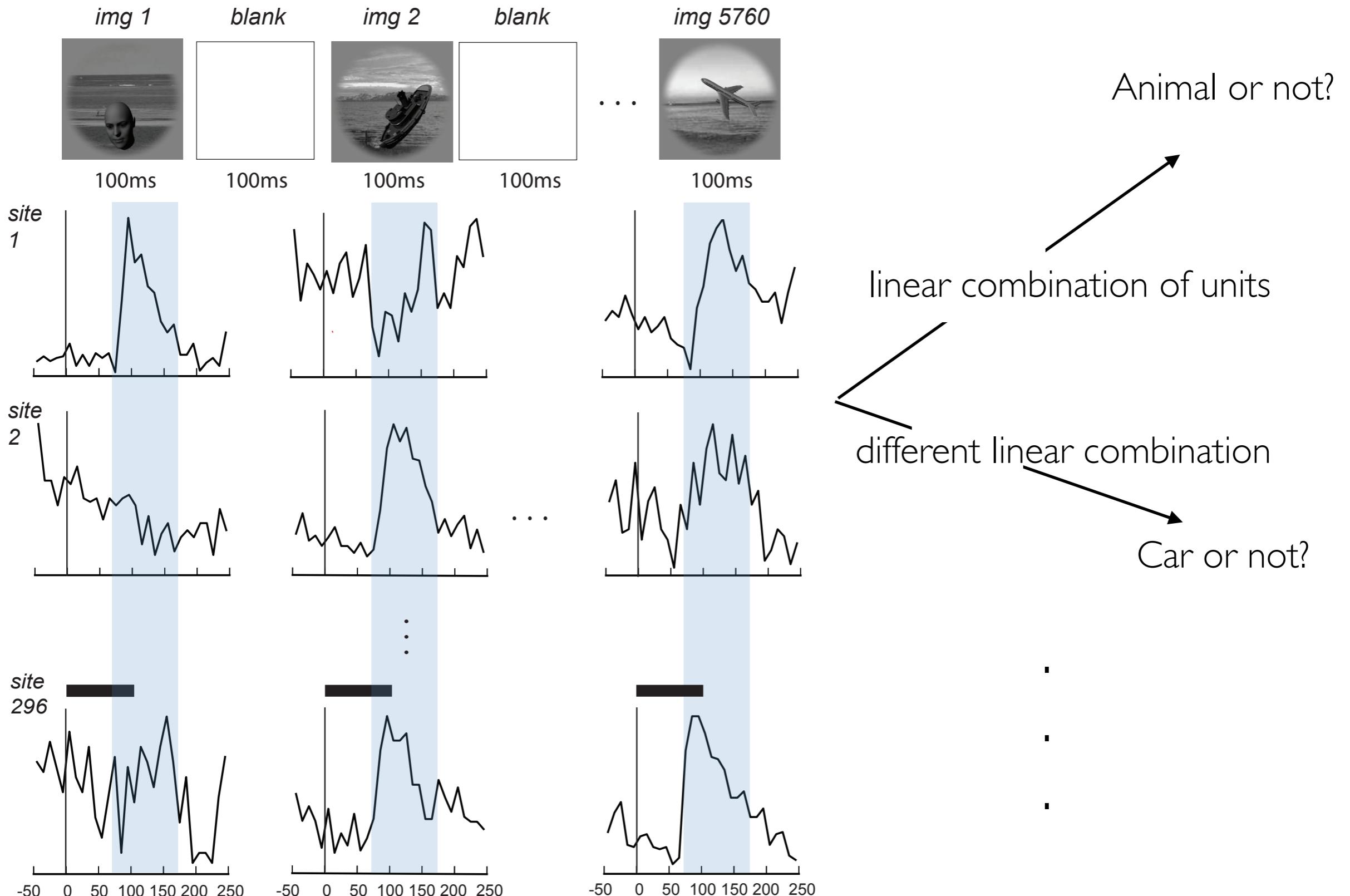
Neural-Behavior Decoding



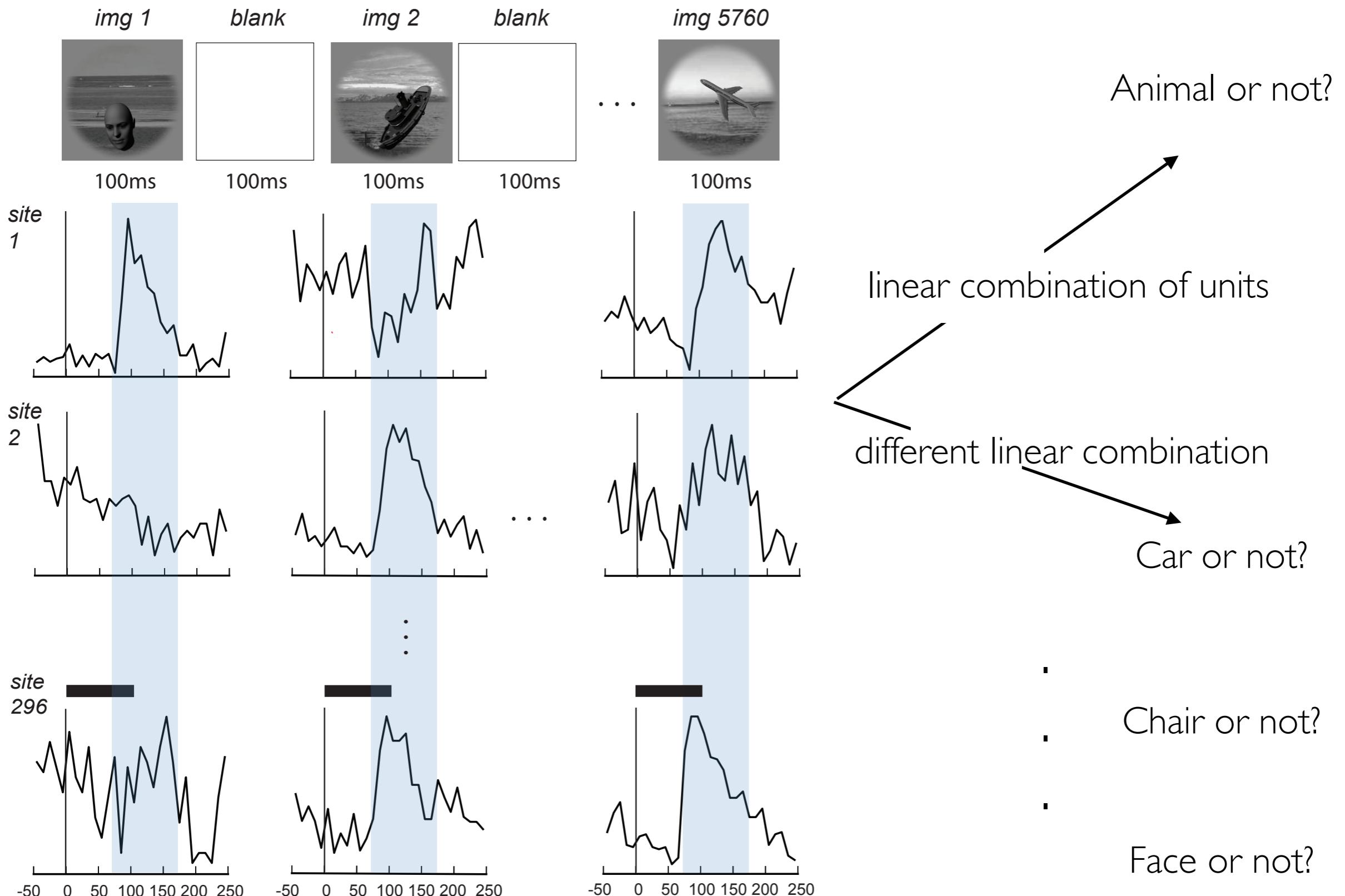
Neural-Behavior Decoding



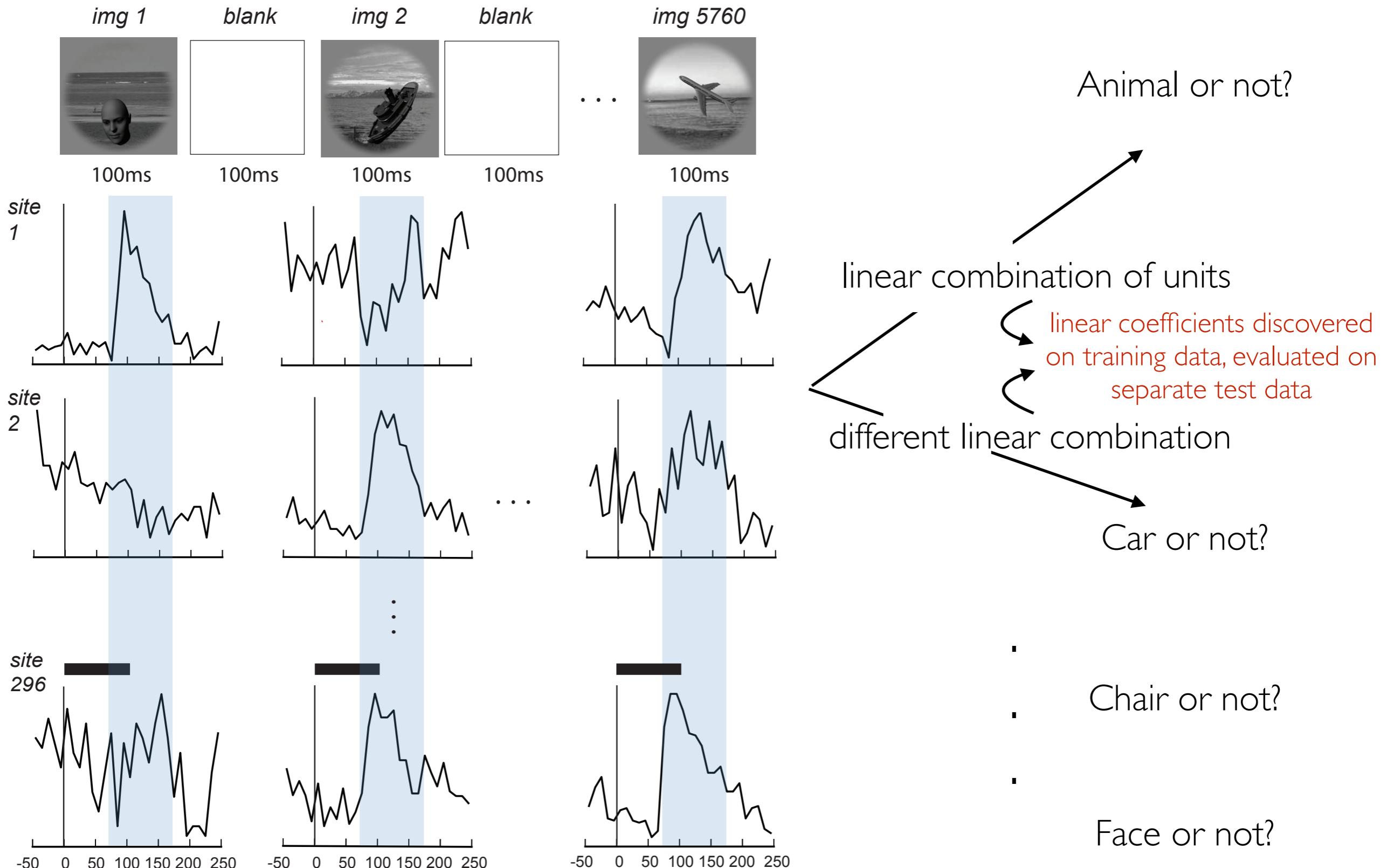
Neural-Behavior Decoding



Neural-Behavior Decoding

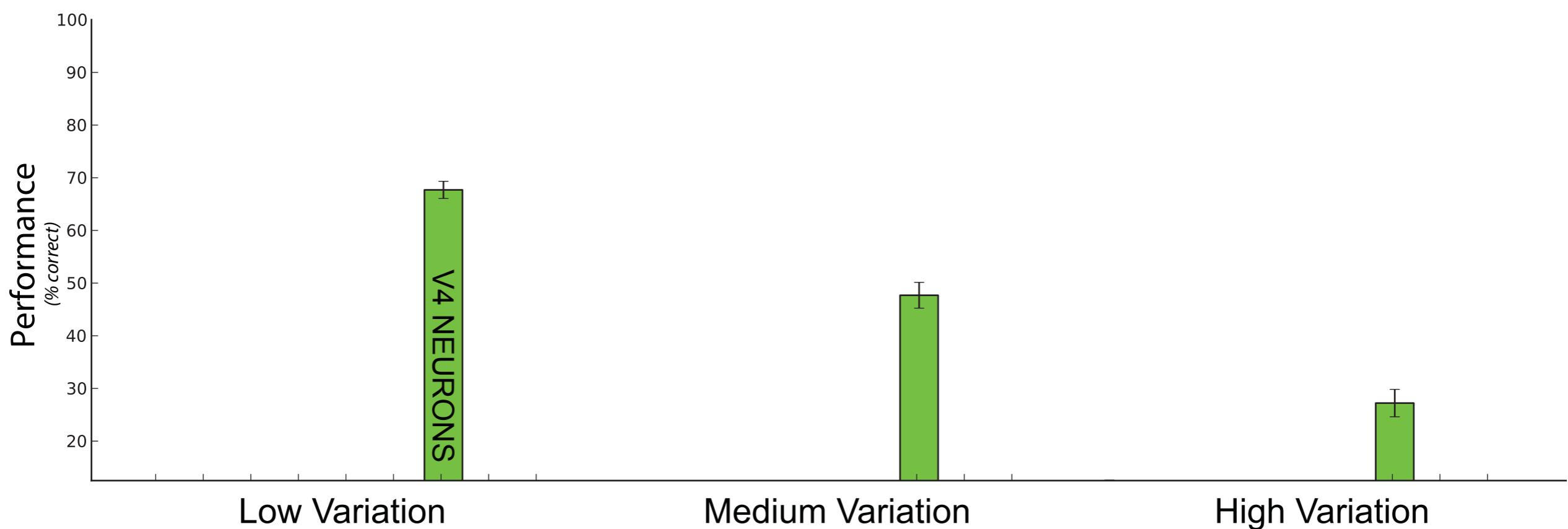
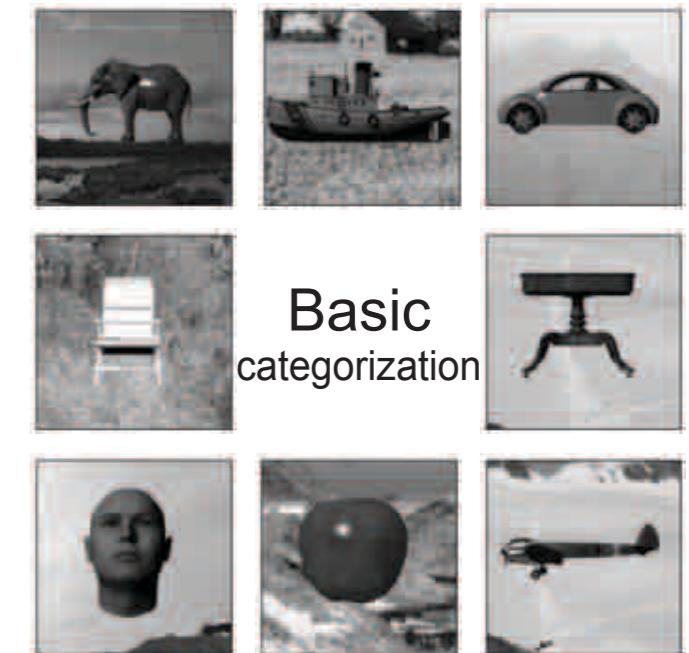


Neural-Behavior Decoding



Decoding Behaviorally Output from Neural Populations

V4 loses out at higher variation:



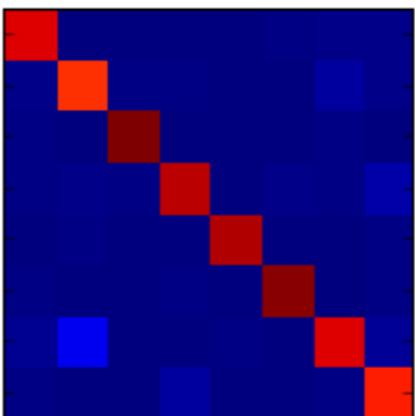
Range of Human Behavior

at
ceiling ...

Variation Level

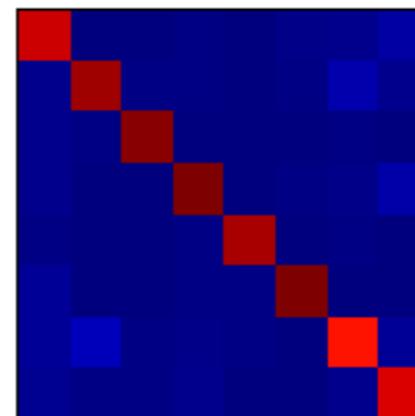
Low

Animals
Boats
Cars
Chairs
Faces
Fruits
Planes
Tables



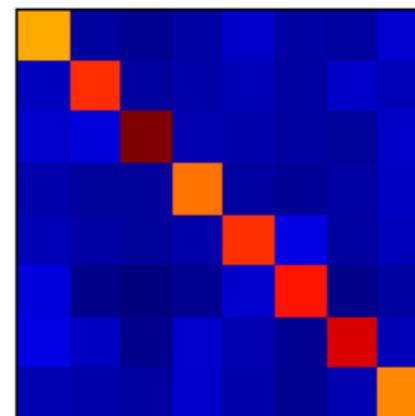
Cars Lo var

Medium



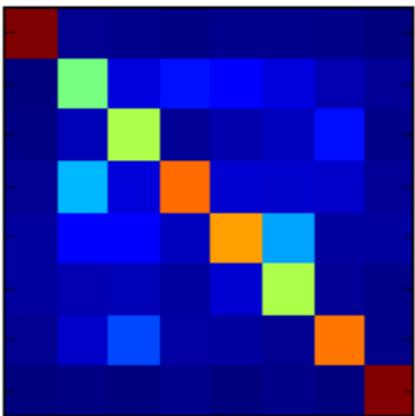
Cars Med var

High

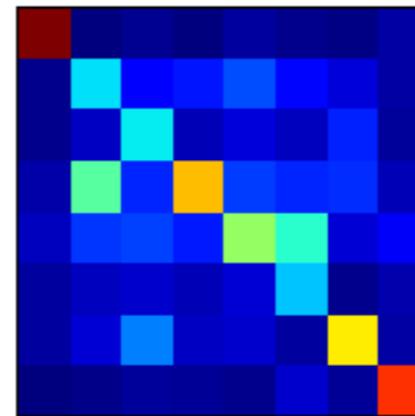


Cars Hi var

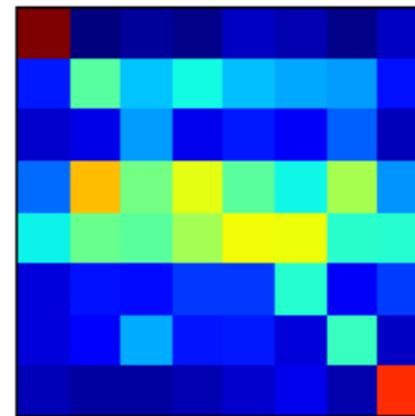
Car 1
Car 2
Car 3
Car 4
Car 5
Car 6
Car 7
Car 8



Faces Lo var

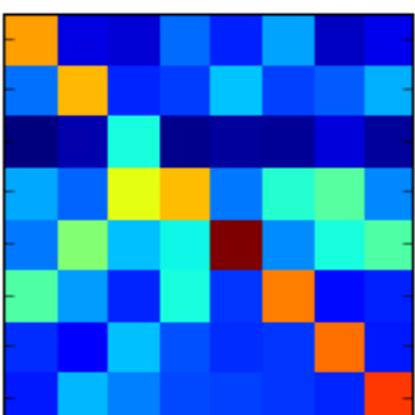


Faces Med var



Faces Hi var

Face 1
Face 2
Face 3
Face 4
Face 5
Face 6
Face 7
Face 8

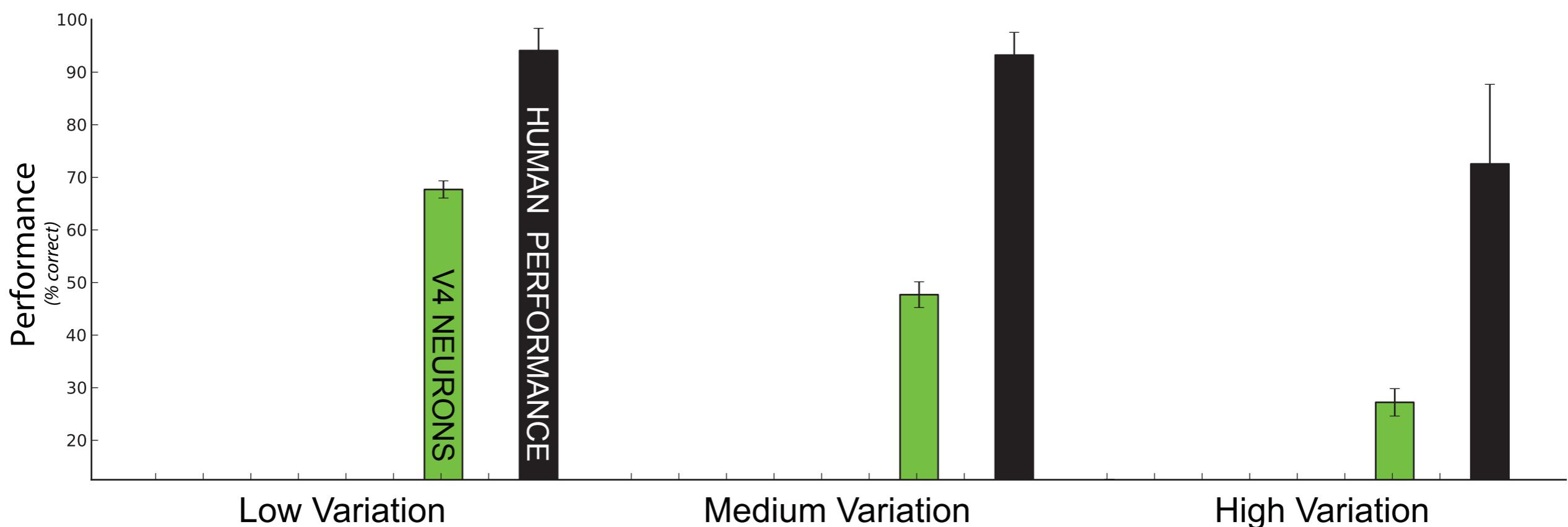
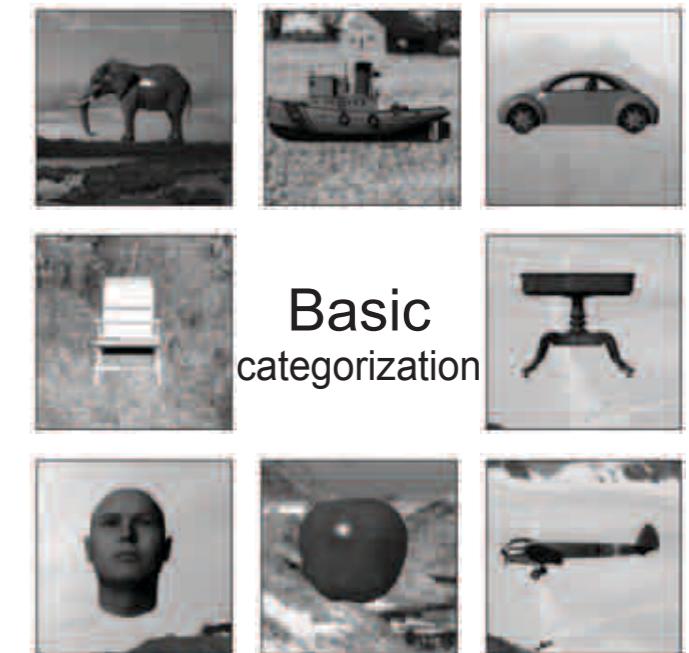


... at
chance

Decoding Behaviorally Output from Neural Populations

V4 loses out at higher variation:

... but humans are much less affected.

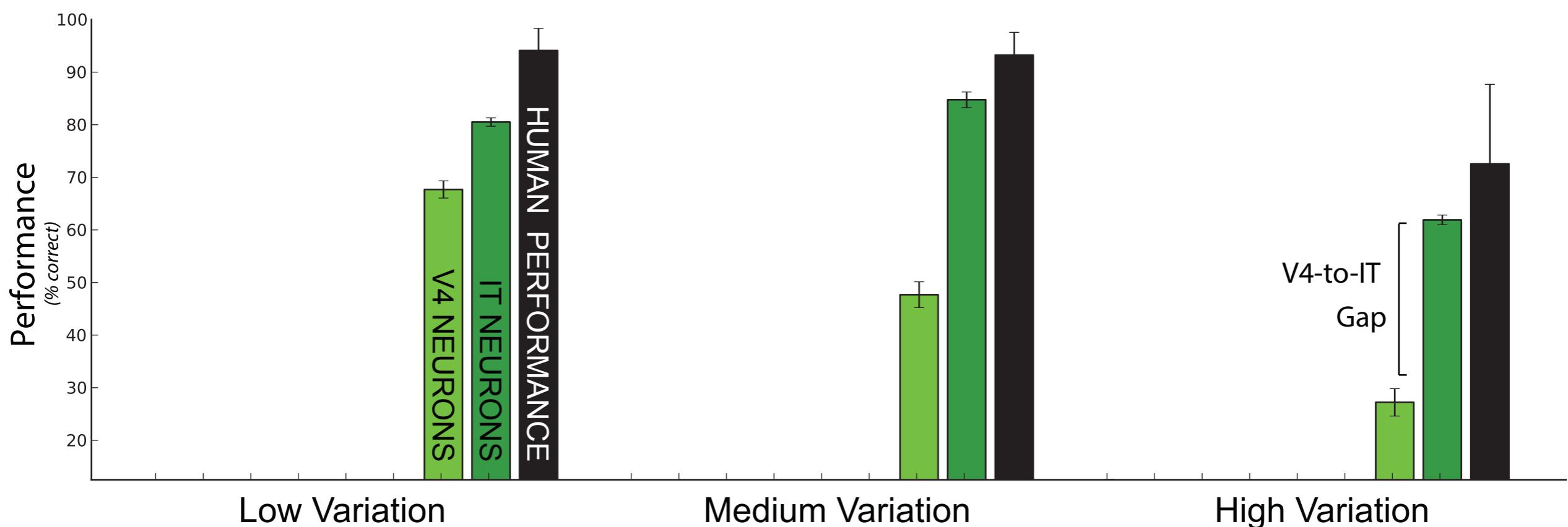
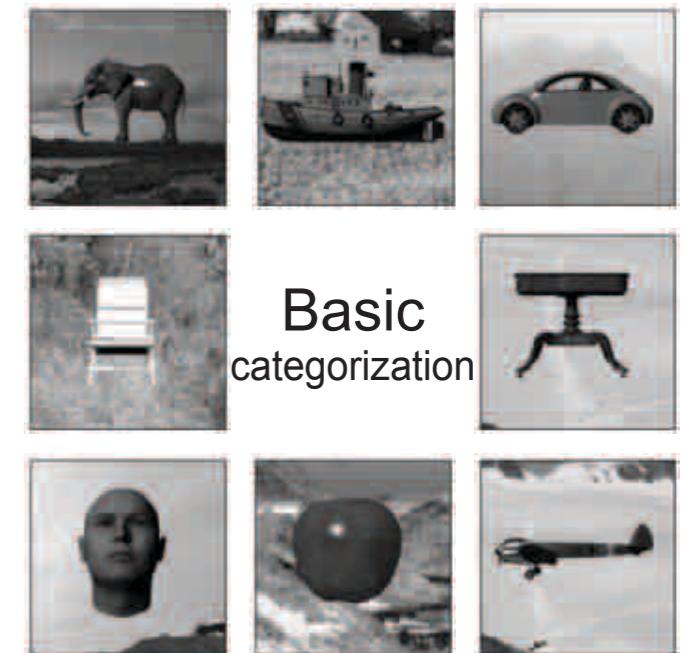


IT Neurons Track Human Performance

V4 loses out at higher variation:

... but humans are much less affected.

... as is the IT neural population.

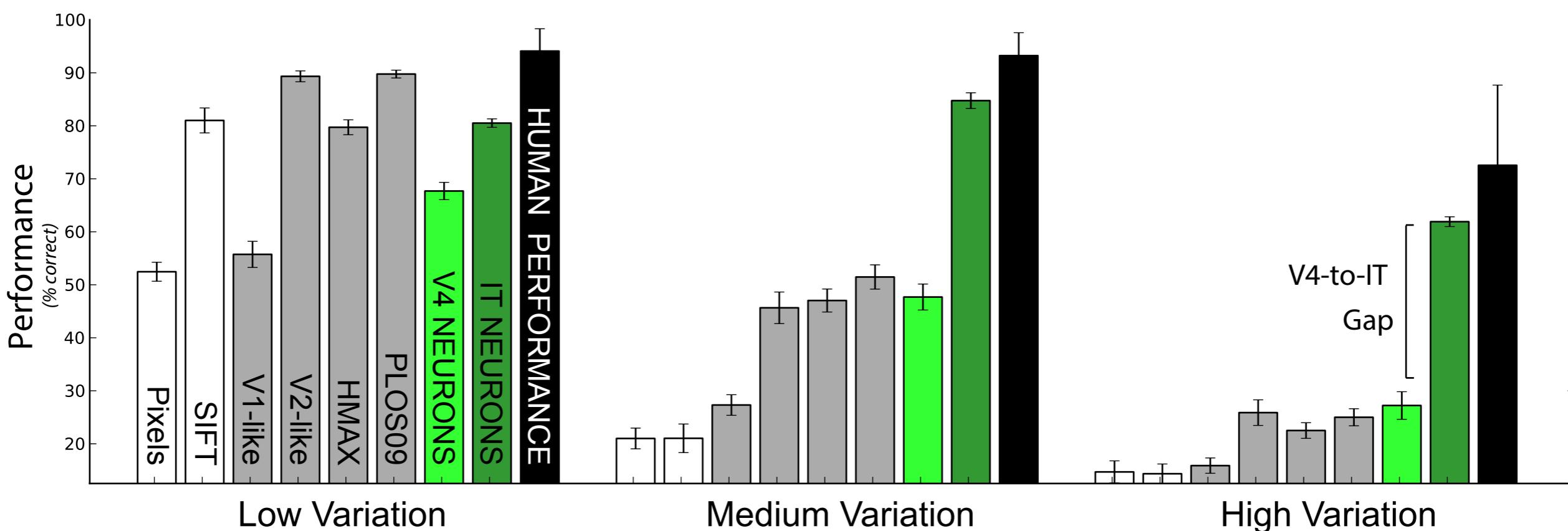
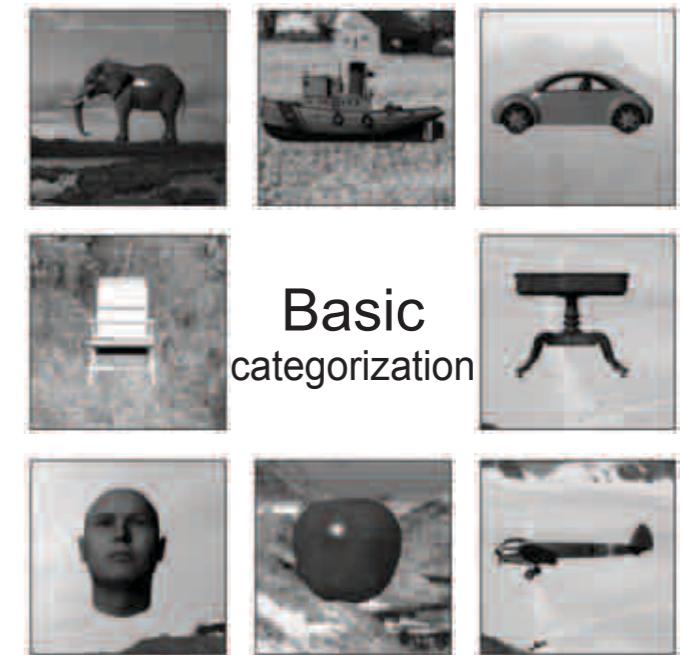


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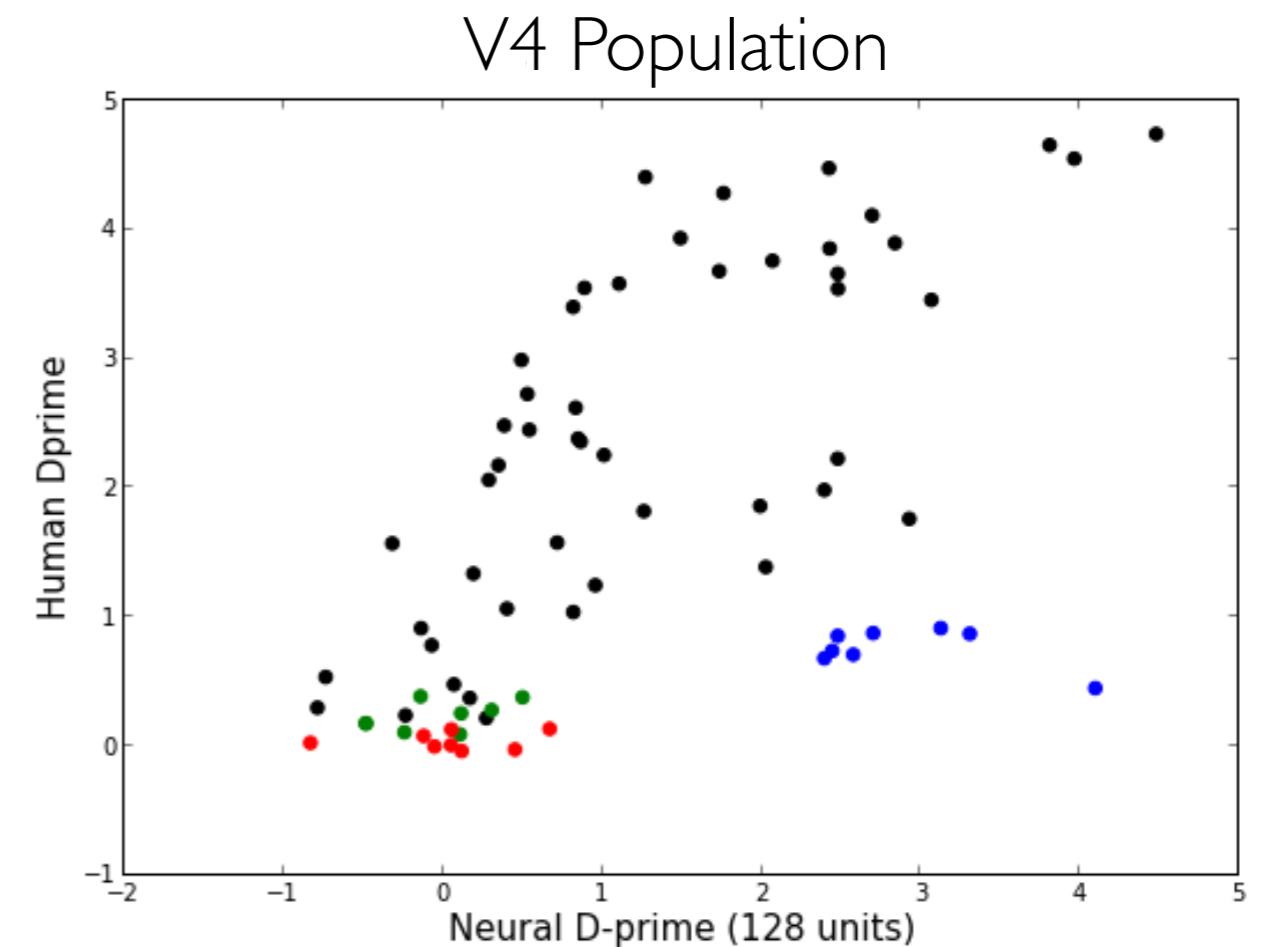
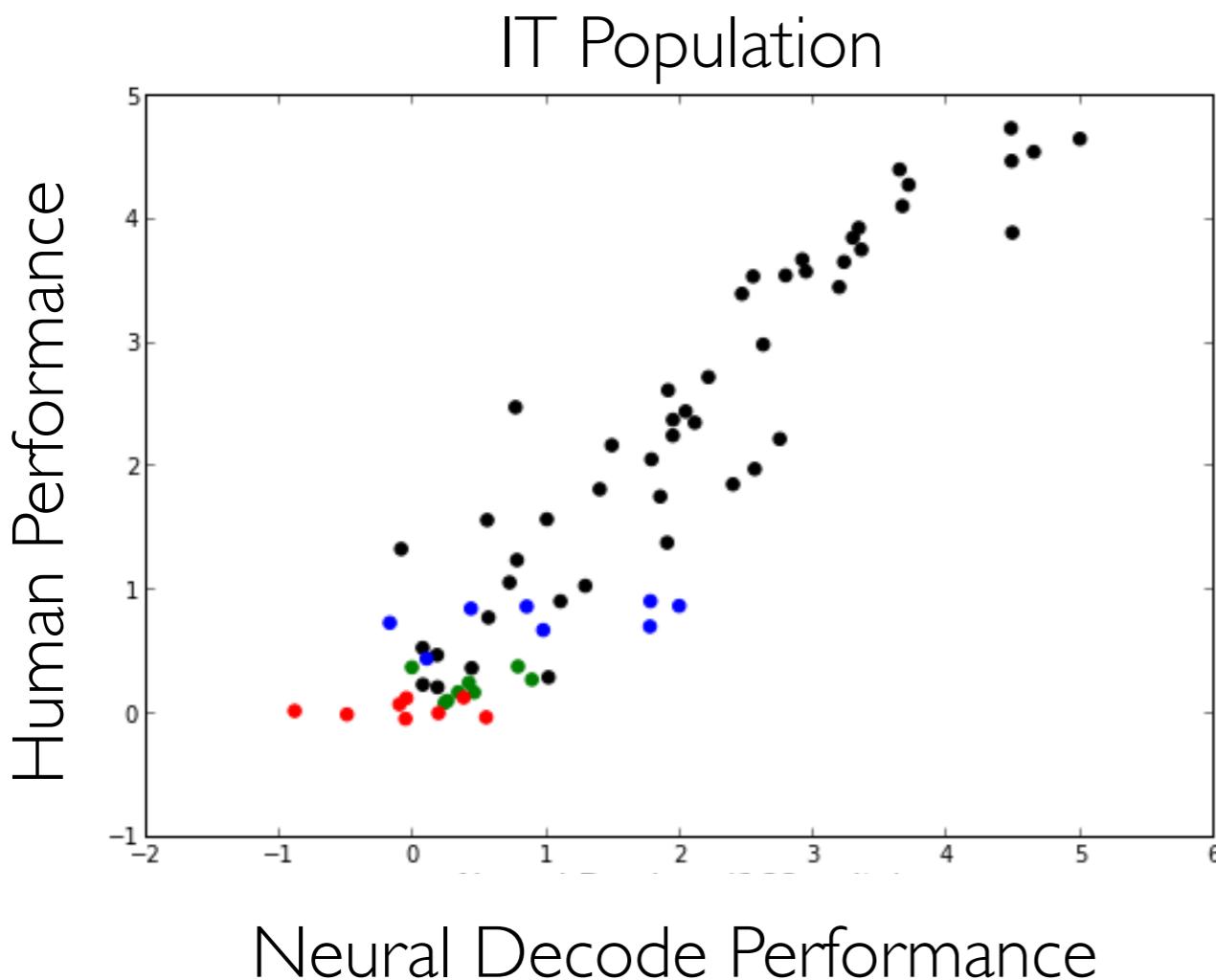


Yamins* and Hong* et. al. **PNAS** (2014)

At high variation levels, IT much better than V4 and existing models.

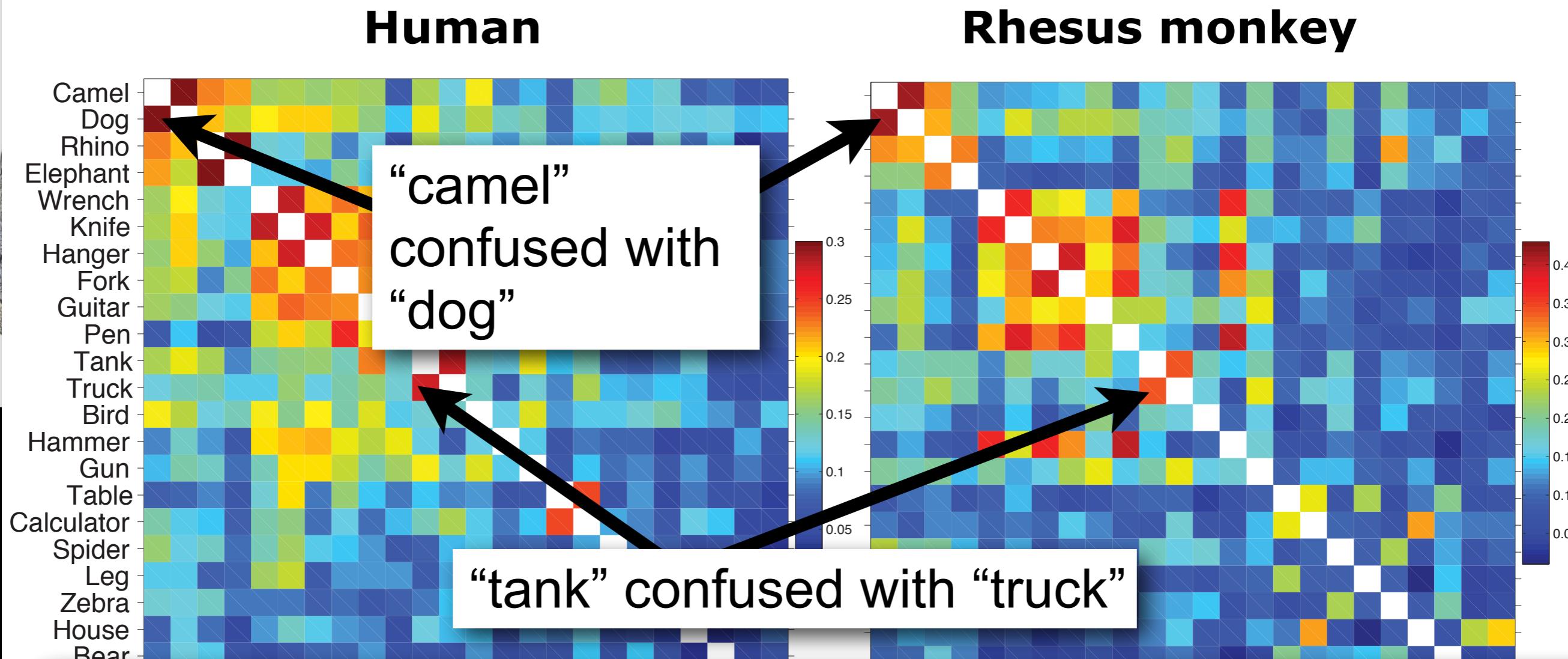
IT Neurons Track Human Performance

IT matches human error patterns as well as raw performance.



- Low-Variation Face subordinate tasks.

Human / Monkey similarities



Upshot: human and non-human primate basic level core object perception (sp. identification) are indistinguishable

Ca E R p h /re K lan F Gu F F T F E mi C T c u l c i p - Z e Ho B sh W

Does not depend on reporting effector (touch vs. eye movement)

Comparison of Object Recognition Behavior in Human and Monkey

R. Rajalingham, K Schmidt, J.J. DiCarlo, **Vision Sciences Society** (2014)

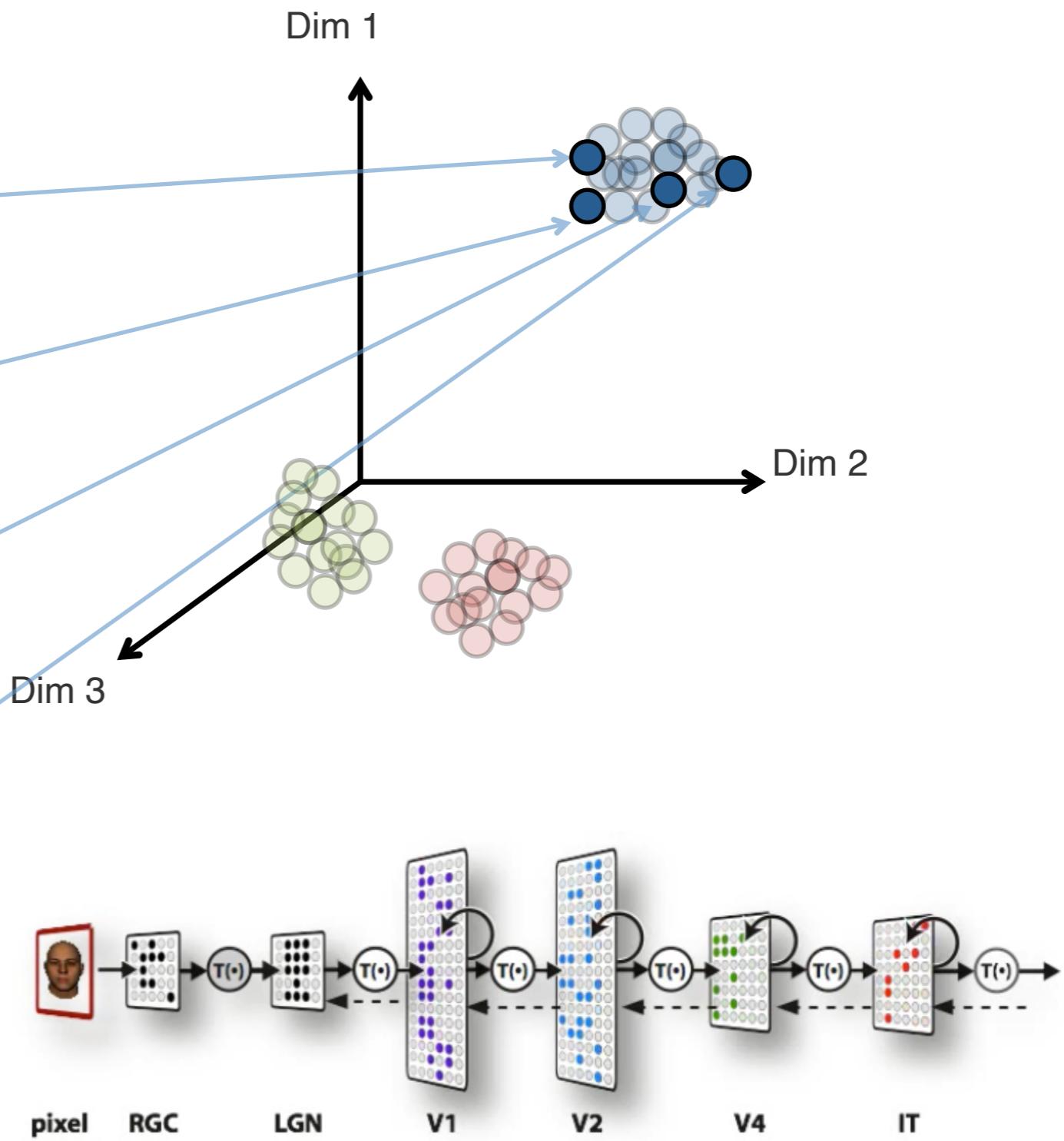
R. Rajalingham, K Schmidt, J.J. DiCarlo, **J. Neuroscience** (2015)

Feature Space as Encoding

Pixel space: $R \sim 1000000$

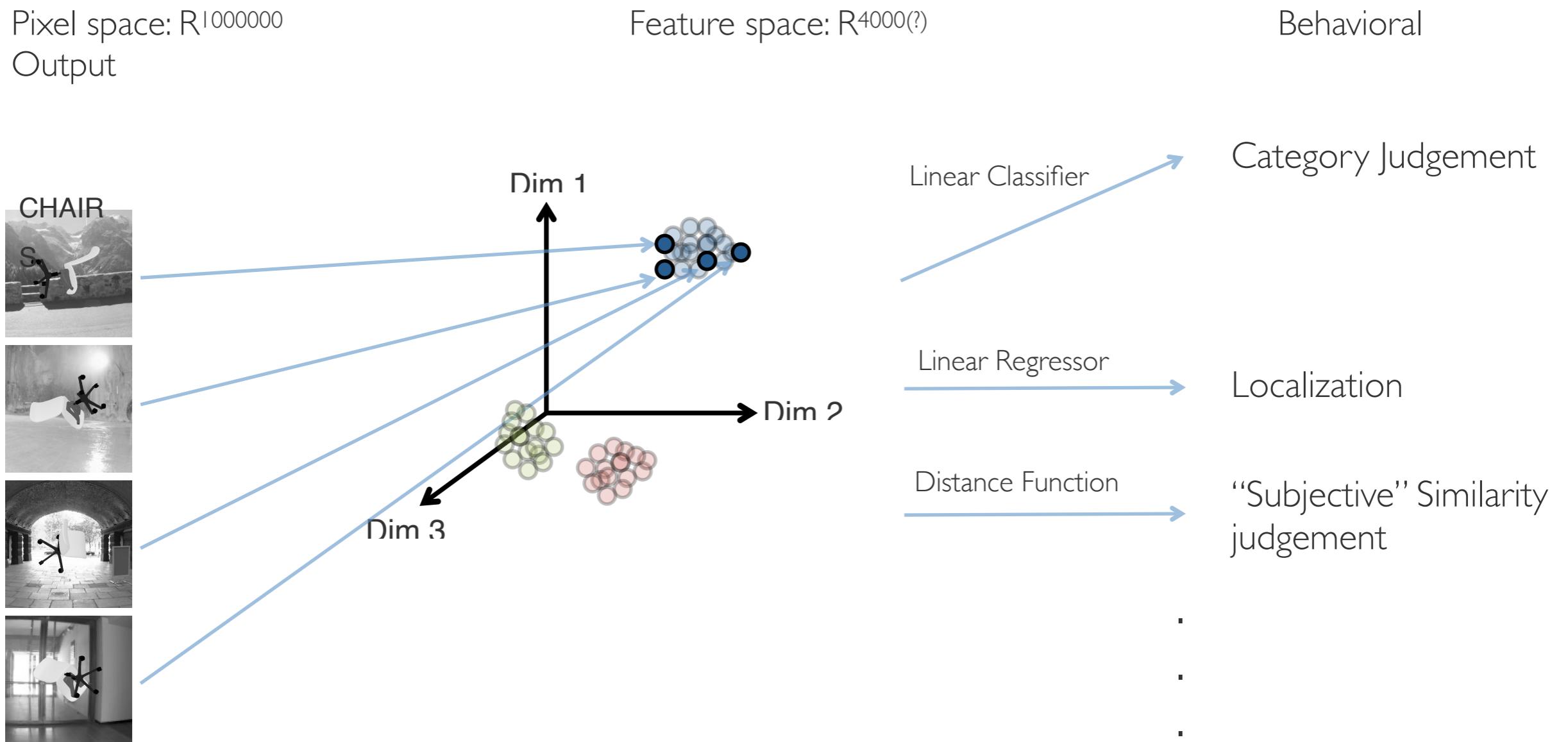
Feature space: $R^{4000(?)}$

CHAIRS



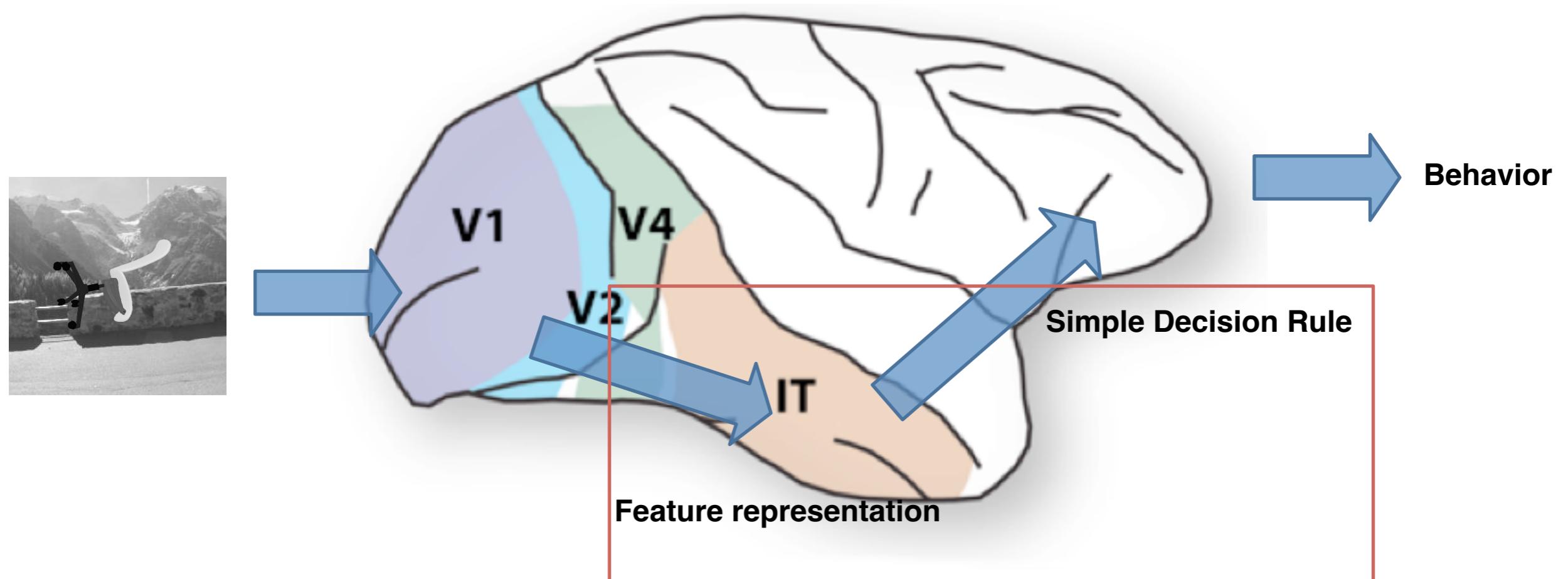
Feature Space as Encoding

Behavior = Feature space + Simple decision rule
= encoding + decoding

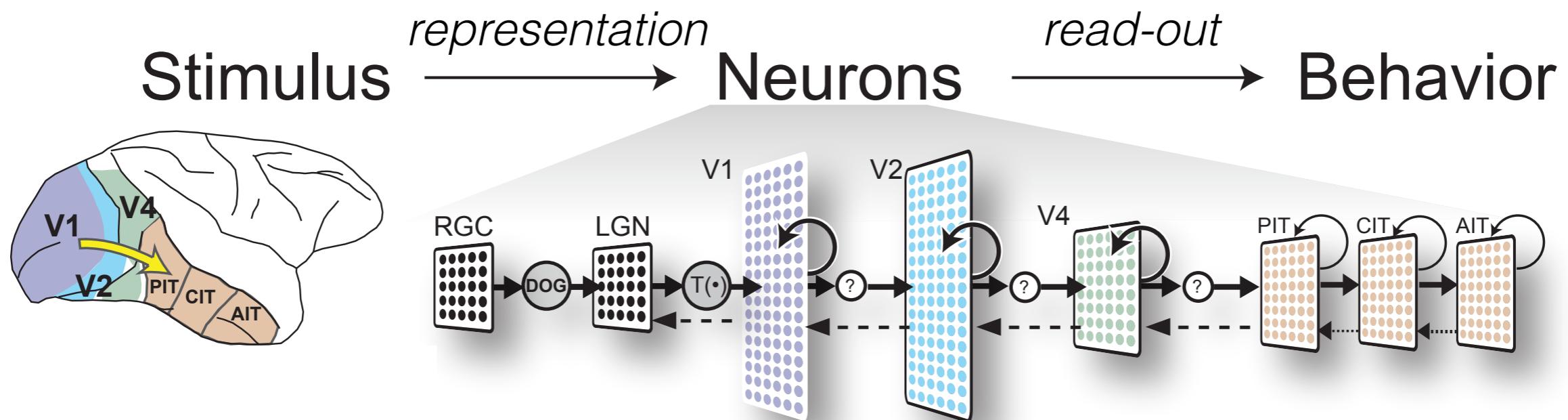


Encoding & Decoding

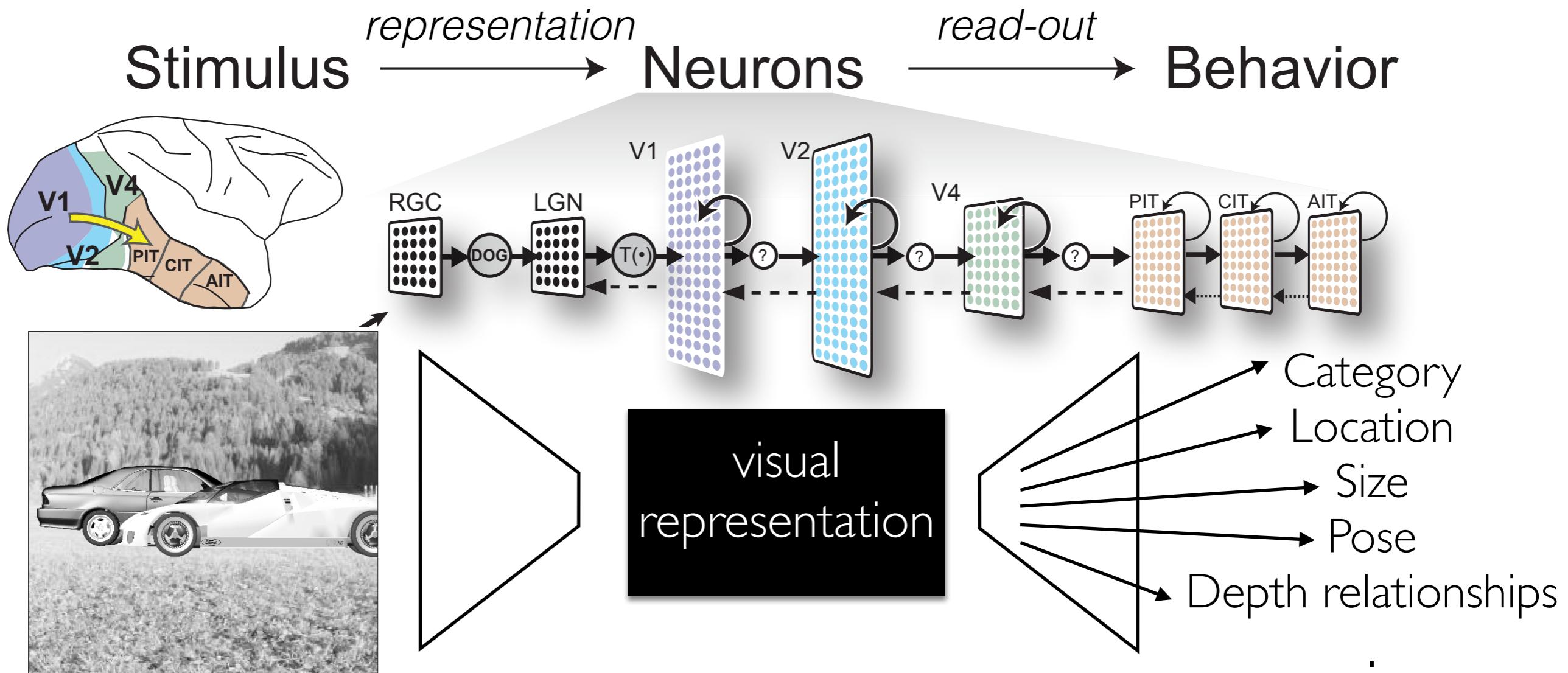
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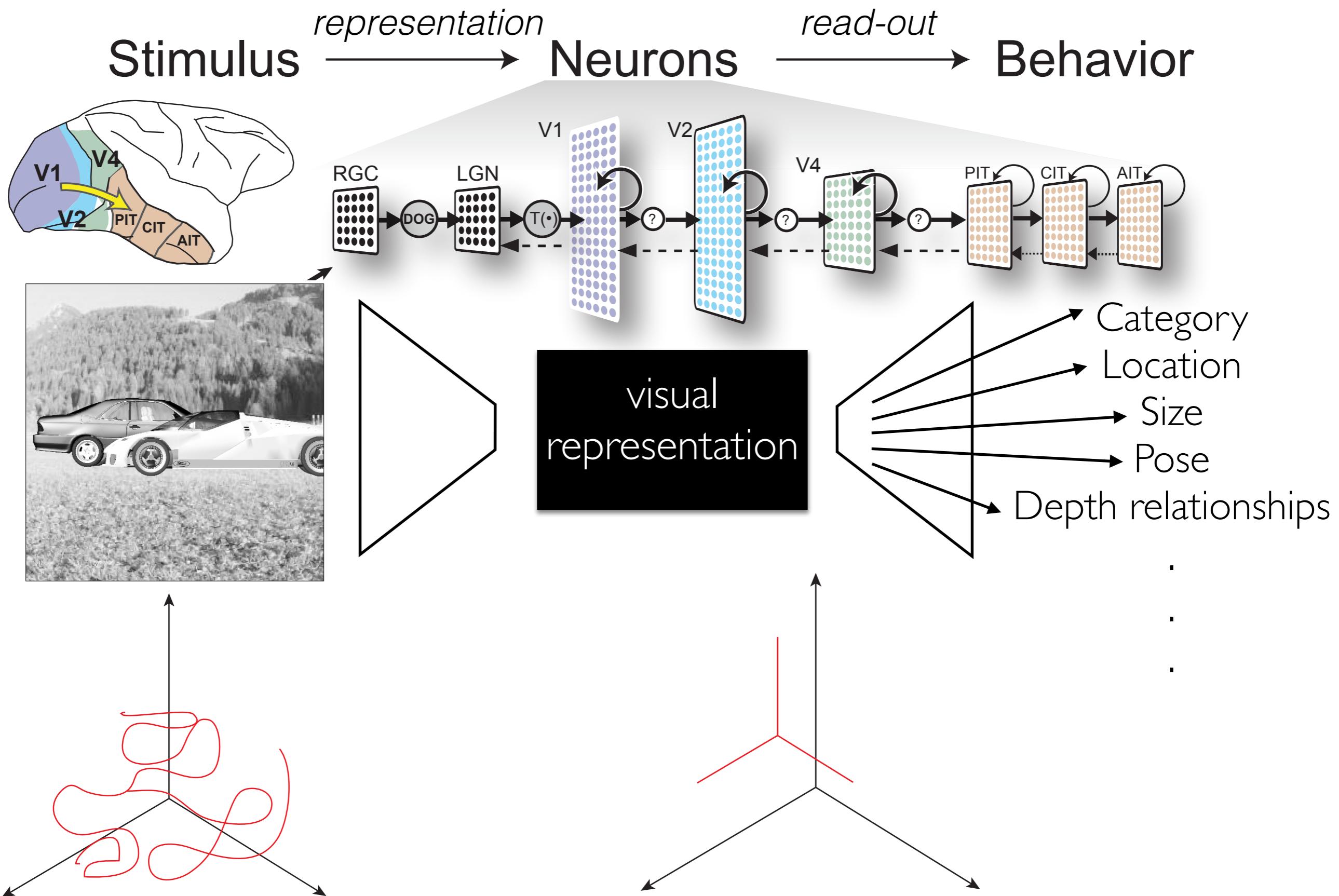
Encoding & Decoding



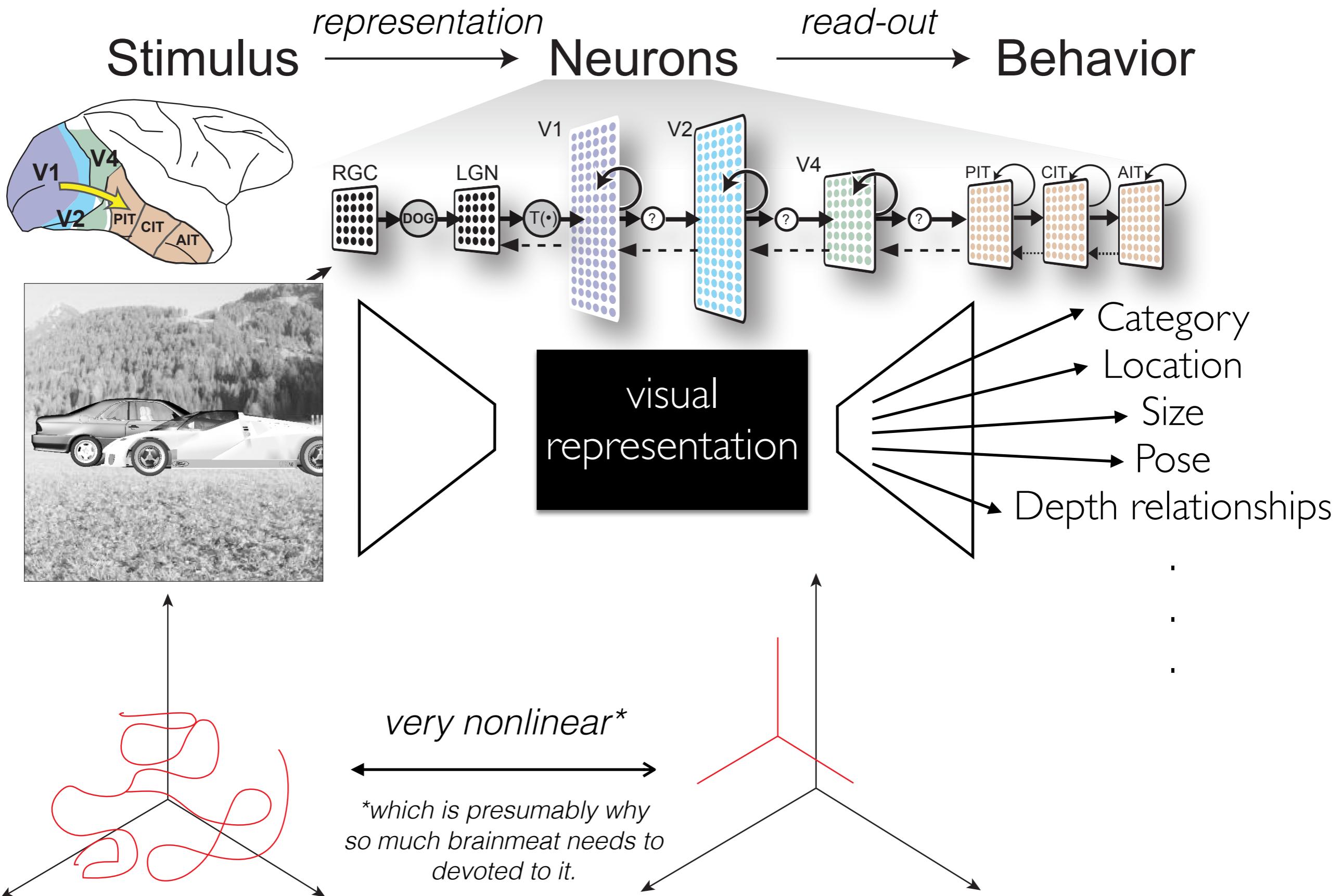
Encoding & Decoding



Encoding & Decoding

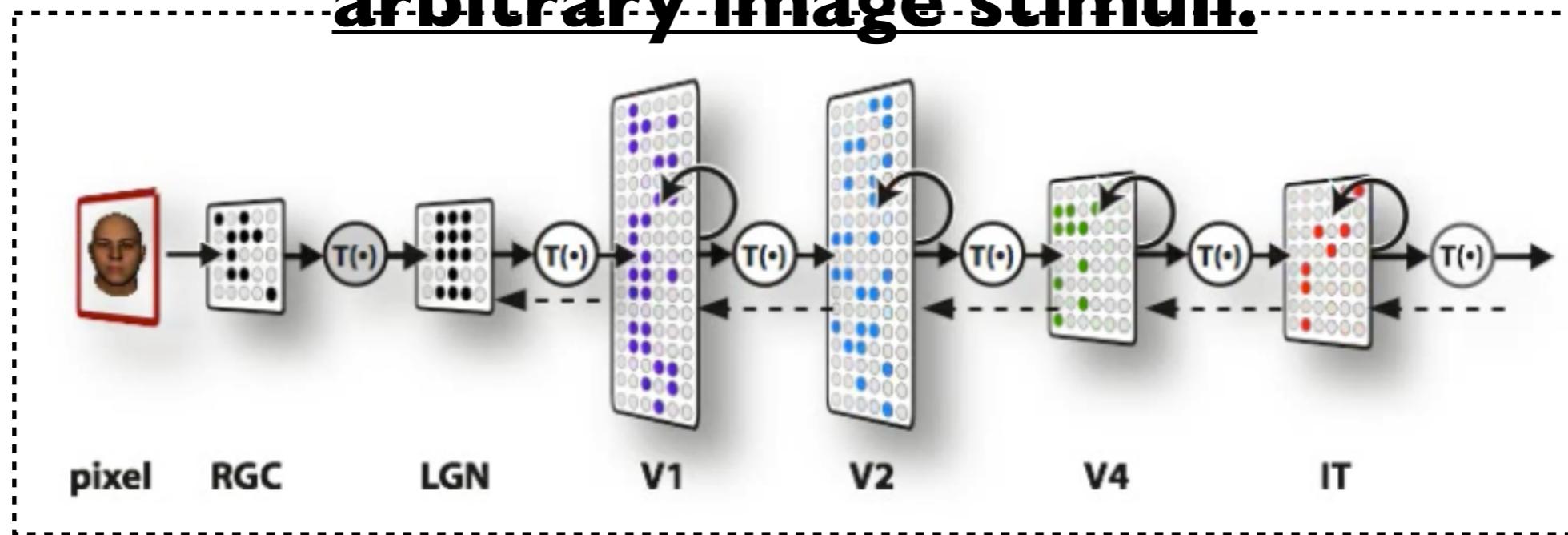


Encoding & Decoding



Ventral Stream

GOAL: Predictive model of single-neuron responses throughout the ventral stream to arbitrary image stimuli.

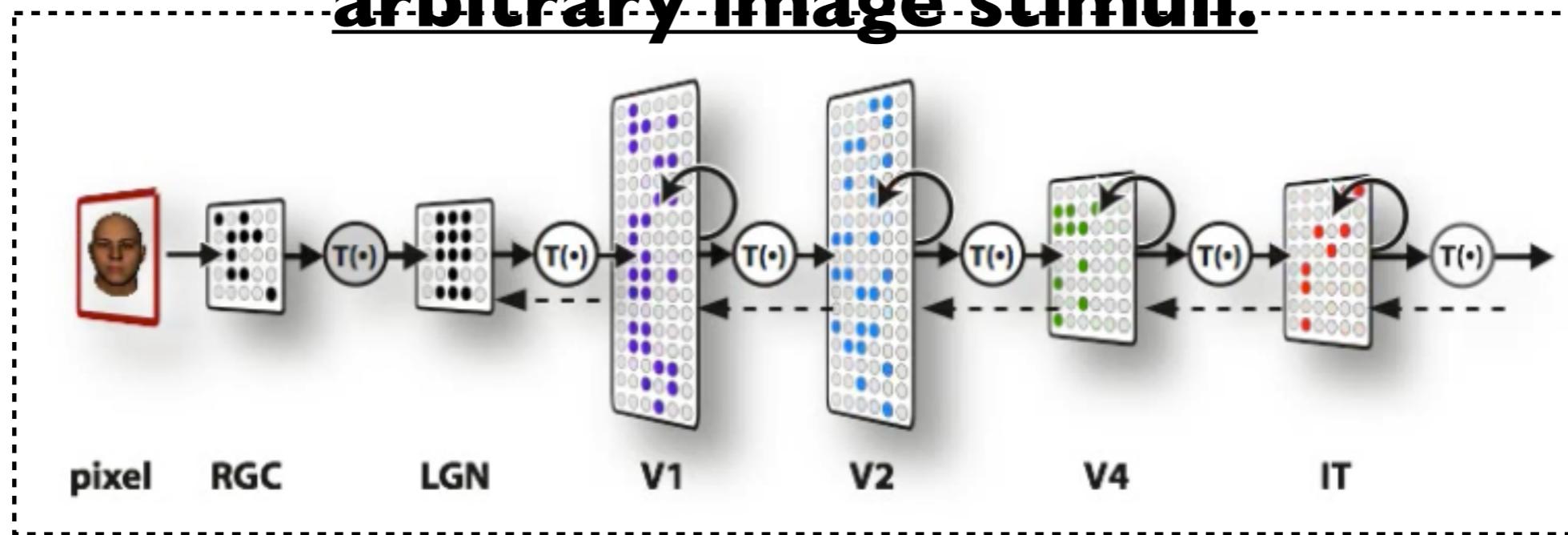


Key questions:

- (a) how many layers?

Ventral Stream

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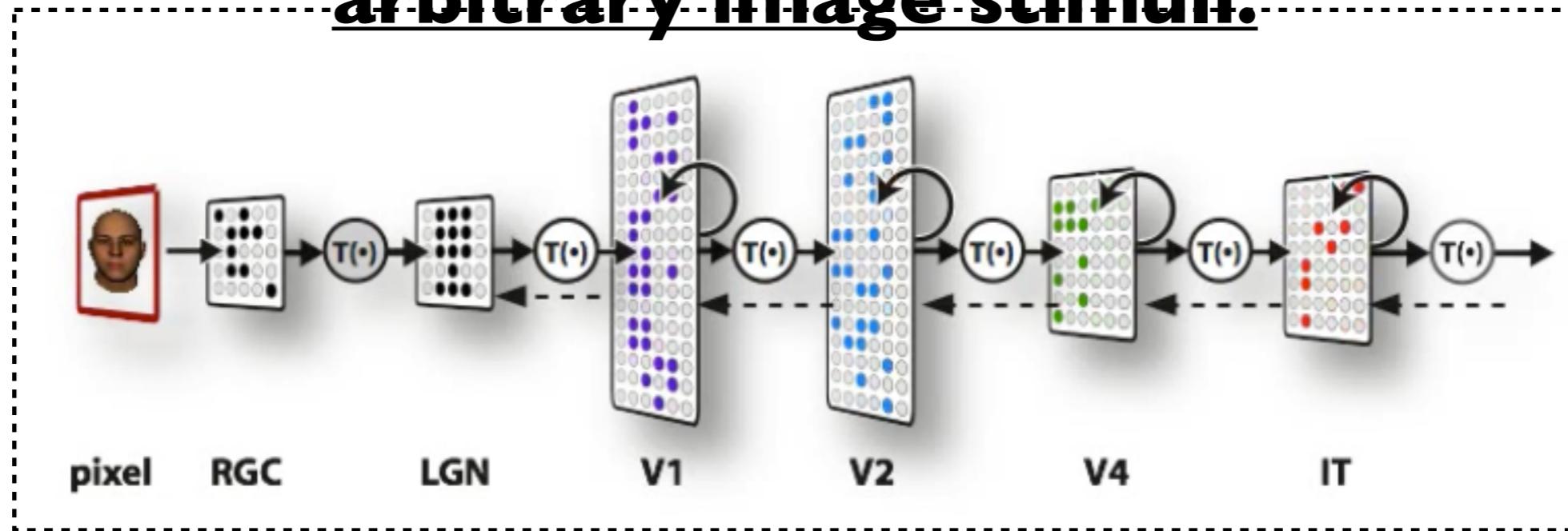


Key questions:

- (a) how many layers?
- (b) what's in each layer; specifically?

Ventral Stream

GOAL: Predictive model of single-neuron responses throughout the ventral stream to arbitrary image stimuli.



Key questions:

- (a) how many layers?
- (b) what's in each layer; specifically?
- (c) what behavioral goals and biophysical facts constrain it to be as it is?

**How are we supposed to use all this hard-won
(Retina-IT) neuroscience knowledge to make
an actual model?**